FINAL REPORT OF SPECIFIC PURPOSE LIDAR SURVEY

LiDAR, Breaklines and Contours for

Taylor County, Florida

State of Florida
Division of Emergency Management
Contract 07-HS-34-14-00-22-469
Task Order 20070525-492718a
PDS Task Order B

October 30, 2009

Prepared by:

Dewberry
8401 Arlington Blvd.
Fairfax, VA 22031-4666
for
Program & Data Solutions (PDS)
1625 Summit Lake Drive, Suite 200
Tallahassee, FL 32317

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For:
State of Florida
Division of Emergency Management
2555 Shumard Oak Blvd.
Tallahassee, FL 32399

By:
Program & Data Solutions (PDS)
1625 Summit Lake Drive, Suite 200
Tallahassee, FL 32317

Prepared by:
David F. Maune, PhD, PSM, PS, GS, CP, CFM
Florida Professional Surveyor and Mapper No. LS6659
Dewberry
8401 Arlington Blvd.
Fairfax, VA 22031

Table of Contents

Report of Specific Purpose LiDAR Survey, LiDAR-Generated Breaklines and Contours Taylor County, Florida

Type of Survey: Specific Purpose Survey

This report pertains to a Specific Purpose LiDAR Survey of Taylor County, Florida, conducted in the summer of 2007, and breaklines and contours generated in 2007 and 2008, for the Florida Division of Emergency Management (FDEM).

The LiDAR dataset, breaklines and contours were prepared by the Program and Data Solutions (PDS) team under FDEM contract 07-HS-34-14-00-22-469, Task Order 20070525-492718a (PDS Task Order B). The LiDAR dataset of Taylor County was acquired by The Sanborn Map Company (Sanborn) in the summer of 2007 and processed to a bare-earth digital terrain model (DTM); it was produced to FDEM vertical accuracy specifications that differ from NOAA specifications in other counties in the Florida Panhandle (i.e., Escambia, Santa Rosa, Walton, and northern Bay County) as summarized in Table 1.

Table 1. Comparison of FDEM and NOAA Vertical Accuracy Criteria

Vertical Accuracy Criteria	FDEM Specifications	NOAA Specifications
Fundamental Vertical Accuracy (FVA) at the 95% confidence level, in open terrain (non-vegetated) land cover only	**≤ 18.2-cm** (0.60-ft) (based on $RMSE_z$ of 9.25-cm x 1.9600)	**≤ 29.4-cm** (0.96-ft) (based on $RMSE_z$ of 15-cm x 1.9600)
Consolidated Vertical Accuracy (CVA) at the 95% confidence level, in all land cover categories combined	**≤ 36.3-cm** (1.19-ft) (based on 95^{th} percentile) or $RMSE_z$ of 18.5-cm x 1.9600	**≤ 36.3-cm** (1.19-ft) (based on 95^{th} percentile) or $RMSE_z$ of 18.5-cm x 1.9600

Under Task Order B, this is one of 12 similar county reports prepared by the PDS team of coastal areas along the Florida Panhandle, from Escambia County through Levy County, considered by FDEM to be vulnerable to hurricane tidal surges. Of these 12 reports, those for coastal Escambia, Santa Rosa, Walton and northern Bay County are based on LiDAR data previously acquired in support of the Northwest Florida Water Management District (NWFWMD) and produced to different accuracy specifications as indicated in Table 1 and to different point densities. The LiDAR datasets produced for Escambia, Santa Rosa and Walton counties were produced by three different NOAA contractors, but with independent QA/QC by Dewberry.

The reports for coastal areas of Taylor County, as well as Okaloosa, Bay, Gulf, Franklin, Wakulla, Jefferson, Dixie, and Levy counties are based on LiDAR data acquired in 2007 by the PDS team under the referenced FDEM contract, produced to the more-rigorous FDEM specifications. Detailed breaklines and contours were produced by the PDS team for areas to be mapped/improved as identified by a tile index provided by FDEM to PDS. Each tile covers an area of 5000 ft by 5000 ft. The map at Appendix A displays the 692 tiles of Taylor County for which LiDAR DTMs and LiDAR-derived breaklines and contours were produced by the PDS team under Task Order B. To avoid double counting, tiles on the county border with Jefferson County and Dixie County were delivered only in one county dataset ─ normally whichever county included the majority of the area of each 5000 ft by 5000 ft tile.

Rather than describe only the data provided of Taylor County in isolation, this report also explains the differences between LiDAR datasets acquired of Escambia, Santa Rosa and Walton counties and those of other counties in the Florida Panhandle produced to different specifications. In addition to the differences in vertical accuracy criteria, summarized in Table 1, there are also differences in the geodetic control used for the different contracts, and there are different point densities between the data acquired to NOAA specifications and data acquired to FDEM Baseline Specifications:

- For the nine new counties mapped by the PDS team for FDEM in the Florida Panhandle under Task Order B, a rigorous geodetic control network was established by the PDS team for all coastal counties between Okaloosa and Levy counties, but excluding Walton County which had been previously mapped by NOAA. Thus, the survey control used for Escambia, Santa Rosa, and Walton counties may differ from the geodetic control network established for the nine other counties in the Panhandle. Primarily because a rigorous geodetic control network was surveyed by the PDS team for the nine new counties, it is expected that there will be differences in the elevations of topographic surfaces between counties, primarily around the boundaries of Escambia, Santa Rosa and Walton counties where the 2006 LiDAR datasets, controlled to older survey control, merge with the 2007 LiDAR datasets controlled to the new geodetic control network established by the PDS team.

- For the nine new counties, including Taylor County, the FDEM Baseline Specifications require a maximum post spacing of 4 feet, i.e., an average point density of less than 1 point per square meter. However, the PDS team required a much higher point density of its subcontractors in order to increase the probability of penetrating dense foliage during the mandated summer acquisition; with nominal post spacing of 0.7 meters per flight line and 50% sidelap between flight lines, the average point density is 4 points per square meter. The NOAA specifications for Escambia County, Santa Rosa County, Walton County, and northern Bay County, required a nominal post spacing of 2 meters, yielding an average point density of 0.25 points per square meter. The significance of this difference is that the nine new counties acquired for FDEM, including Taylor County, have LiDAR point densities approximately 16 times higher than the LiDAR point densities in Escambia County, Santa Rosa County, Walton County, and northern Bay County. With higher point density there is a greater probability of penetrating dense vegetation and minimizing areas defined as "low confidence areas."

The PDS Team

PDS is a Joint Venture consisting of PBS&J, Dewberry, and URS Corp:

- PBS&J provided local client liaison in Tallahassee. PBS&J was also responsible for the overall ground survey effort including management of field survey subcontractors – Allen Nobles & Associates, Inc. (ANA) and Diversified Design & Drafting Services, Inc. (3DS) – which performed the geodetic control surveys and quality assurance/quality control (QA/QC) checkpoint surveys used for independent accuracy testing by Dewberry and URS. These surveyors executed a network adjustment of control points used throughout the Florida Panhandle. It was important to execute this network adjustment because of widely-held concerns that the survey control was deficient in the Florida Panhandle counties. Mr. Glenn Bryan, PSM, of PBS&J, and Mr. Brett Wood, PSM, of 3DS, were the technical leads for the control surveys and QA/QC surveys.

- Dewberry was responsible for the overall Work Plan and aerial survey effort for the nine new counties, including management of LiDAR subcontractors that performed the LiDAR data acquisition and post-processing and produced LAS classified data. A staff of QA/QC specialists at Dewberry's Fairfax (VA) office performed quality assessments of the breaklines and contours. Dewberry served as the single point of contact with FDEM. Dr. David Maune, PSM, was Dewberry's technical lead for the digital orthophoto and LiDAR surveys and derived products. Under separate contract with NOAA, Dr. Maune had previously served as Dewberry's Quality Manager for its independent QA/QC of LiDAR data produced by NOAA for the NWFWMD of Escambia, Santa Rosa, and Walton counties.

- URS Corp. was responsible for data management and information management. URS developed the GeoCue Distributed Production Management System (DPMS), managed and tracked the flow of data, performed independent accuracy testing and quality assessments of FDEM's new LiDAR data acquired in 2007, tracked and reported the status of individual tiles during production, and produced all final deliverables for FDEM. Mr. Robert Ryan, CP, of URS, was the technical lead for this effort.

Name of Company in Responsible Charge

Dewberry
8401 Arlington Blvd.
Fairfax, VA 22031-4666

Name of Responsible Surveyor

David F. Maune, PhD, PSM, PS, GS, CP, CFM
Florida Professional Surveyor and Mapper (PSM) No. LS6659

Survey Area

The project area for this report encompasses approximately 620.5 square miles within Taylor County and small adjoining areas of Jefferson County and Dixie County.

Map Reference

There are no hardcopy map sheets for this project. The map at Appendix A provides graphical reference to the 5000-ft x 5000-ft tiles covered by this report.

Summary of FDEM Baseline Specifications

All new data produced for FDEM under the referenced contract are required to satisfy the Florida Baseline Specifications, included as appendices to PDS's Task Order B, dated May 23, 2007, from FDEM. To expedite production, the Florida Baseline Specifications were modified by FDEM to require new LiDAR data acquisition during the summer of 2007 (leaf-on) as opposed to the normal leaf-off.

Task Order B presented demanding technical challenges for the PDS team because the existing geodetic control monuments in the Florida Panhandle are believed to be the most inaccurate in Florida, with elevation discrepancies as much as several feet; and some areas in the Panhandle are subject to subsidence. LiDAR elevations produced relative to some survey control monuments are believed to differ by as much as several feet from LiDAR elevations produced relative to other control monuments in the Panhandle. This caused a new geodetic control network to be established by the PDS team for the counties to be newly surveyed, but without adjusting the geodetic control monuments used for Escambia

County, Santa Rosa County, Walton County, and northern Bay County for which existing LiDAR data was used "as is."

The official State Plane Coordinate System tiling scheme was provided by FDEM to the PDS team on July 10, 2007 for Florida's North Zone. The Taylor County tiling footprint graphic is shown at Appendix A.

The Florida Baseline Specifications required the LiDAR data to be collected using an approved sensor with a maximum field of view (FOV) of 20˚ on either side of nadir, with GPS baseline distances limited to 20 miles, with maximum post spacing of 4 feet in unobscured areas for random point data, and with vertical root mean square error ($RMSE_z$) ≤ 0.30 ft and Fundamental Vertical Accuracy (FVA) ≤ 0.60 ft at the 95% confidence level in open terrain (bare-earth and low grass); this accuracy is equivalent to 1 ft contours in open terrain when tested in accordance with the National Map Accuracy Standard (NMAS). In other land cover categories (brush lands and low trees, forested areas fully covered by trees, and urban areas), the Florida Baseline Specifications required the LiDAR data's $RMSE_z$ to be ≤ 0.61 ft with Supplemental Vertical Accuracy (SVA) and Consolidated Vertical Accuracy (CVA) ≤ 1.19 ft at the 95% confidence level; this accuracy is equivalent to 2 ft contours when tested in accordance with the NMAS. *Low confidence areas*, originally called *obscured vegetated areas*, are defined for areas where the vertical data may not meet the data accuracy requirements due to heavy vegetation.

The Florida Baseline Specifications also required the horizontal accuracy to meet or exceed 3.8 feet at the 95% confidence level, using $RMSE_r$ x 1.7308. This means that the horizontal (radial) RMSE ($RMSE_r$) must meet or exceed 2.20 ft. This is the horizontal accuracy required of maps compiled at a scale of 1:1,200 (1" = 100') in accordance with the traditional National Map Accuracy Standard.

To meet and exceed these specifications for the nine new county LiDAR datasets, the PDS team established the following more-rigorous specifications for its LiDAR subcontractors:

- Instead of a 20˚ FOV on either side of nadir, the PDS team limited the FOV to 18˚
- Instead of GPS baselines ≤ 20 miles, the PDS team limited baseline lengths to ≤ 20 km, except in one small isolated area where the baseline length was approximately 23 km (14 miles).
- Instead of 4 foot post spacing which yields an average of 0.67 points per m^2, the PDS team chose 0.7 m point spacing and 50% sidelap that yields an average of more than 4 points per m^2. Thus, the PDS team's average point density is nearly 6 times higher than required by FDEM, greatly increasing the probability of LiDAR points penetrating through dense vegetation so as to minimize areas defined as *low confidence areas*. The PDS team defines *low confidence areas* as vegetated areas of ½ acre or larger that are considered obscured to the extent that adequate vertical data cannot be clearly determined to accurately define the DTM. Such areas indicate where the vertical data may not meet the data accuracy requirements due to heavy vegetation.

The first deliverable is LiDAR mass points, delivered to LAS 1.1 specifications, including the following LAS classification codes:

- Class 1 = Unclassified, and used for all other features that do not fit into the Classes 2, 7, 9, or 12, including vegetation, buildings, etc.
- Class 2 = Ground, includes accurate LiDAR points in overlapping flight lines
- Class 7 = Noise, includes LiDAR points in overlapping flight lines
- Class 9 = Water, includes LiDAR points in overlapping flight lines

- Class 12 = Overlap, including areas of overlapping flight lines which have been deliberately removed from Class 1 because of their reduced accuracy.

Table 2 compares the LiDAR LAS classes specified by the FDEM and NOAA specifications.

Table 2. Comparison of FDEM and NOAA LAS Classes

FDEM LAS Classes	NOAA LAS Classes
Class 1 – Unclassified, including vegetation, buildings, bridges, piers Class 2 – Ground points (used for contours) Class 7 – Noise Class 9 – Water[1] Class 12 – Overlap points deliberately removed	Class 1 – Unclassified Class 2 – Ground points (used for contours) Class 9 – Water

For each 500 square mile area within the nine new county datasets, a total of 120 "blind" QA/QC checkpoints were surveyed, totally unknown to (i.e., "blind" from) the LiDAR subcontractors. Each set of 120 QA/QC checkpoints had the goal to include 30 checkpoints in each of the following four land cover categories:

- Category 1 = bare-earth and low grass
- Category 2 = brush lands and low trees
- Category 3 = forested areas fully covered by trees
- Category 4 = urban areas

In a few cases, there were insufficient dispersed areas to acquire 30 QA/QC checkpoints for one or more land cover categories; when this occurred, Dewberry advised the surveyors to select additional QA/QC checkpoints for land cover categories that were predominant in the area and therefore more representative of the area being tested.

The following vertical accuracy guidelines were specified by the Florida Baseline Specifications:

- In category 1, the $RMSE_z$ must be ≤ 0.30 ft ($Accuracy_z$ ≤ 0.60 ft at the 95% confidence level); $Accuracy_z$ in Category 1 refers to Fundamental Vertical Accuracy (FVA) which defines how accurate the elevation data are when not complicated by asphalt or vegetation that may cause elevations to be either lower or higher than the bare earth terrain. This is equivalent to the accuracy expected of 1 ft contours in non-vegetated terrain.
- In category 2, the $RMSE_z$ must be ≤ 0.61 ft ($Accuracy_z$ ≤ 1.19 ft at the 95% confidence level); $Accuracy_z$ in Category 2 refers to Supplemental Vertical Accuracy (SVA) in brush lands and low trees and defines how accurate the elevation data are when complicated by such vegetation that frequently causes elevations to be lower or higher than the bare earth terrain. This is equivalent to the accuracy expected of 2 ft contours in such terrain.

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[1] Infrared radiation from LiDAR is partially absorbed by water, and all elevations in LAS Class 9 should be recognized as unreliable and treated accordingly.

- In category 3, the $RMSE_z$ must be ≤ 0.61 ft ($Accuracy_z$ ≤ 1.19 ft at the 95% confidence level); $Accuracy_z$ in Category 3 refers to Supplemental Vertical Accuracy (SVA) in forested areas fully covered by trees and defines how accurate the elevation data are when complicated by such vegetation that frequently causes elevations to be lower or higher than the bare earth terrain. This is equivalent to the accuracy expected of 2 ft contours in such terrain.
- In category 4, the $RMSE_z$ must be ≤ 0.61 ft ($Accuracy_z$ ≤ 1.19 ft at the 95% confidence level); $Accuracy_z$ in Category 4 refers to Supplemental Vertical Accuracy (SVA) in urban areas typically paved with asphalt and defines how accurate the elevation data are when complicated by asphalt that frequently causes elevations to be lower than the bare earth terrain. This is equivalent to the accuracy expected of 2 ft contours in such terrain.
- In all land cover categories combined, the $RMSE_z$ must be ≤ 0.61 ft ($Accuracy_z$ ≤ 1.19 ft at the 95% confidence level); $Accuracy_z$ in all categories combined refers to Consolidated Vertical Accuracy (CVA).
- The terms FVA, SVA and CVA are explained in Chapter 3, *Accuracy Standards & Guidelines*, of "Digital Elevation Model Technologies and Applications: The DEM Users Manual," published by the American Society for Photogrammetry and Remote Sensing (ASPRS), January, 2007.

A second major deliverable consists of nine types of breaklines, produced in accordance with the PDS team's Data Dictionary at Appendix C:

1. Coastal shoreline features
2. Single-line hydrographic features
3. Dual-line hydrographic features
4. Closed water body features
5. Road edge-of-pavement features
6. Bridge and overpass features
7. Soft breakline features
8. Island features
9. Low confidence areas

Another major deliverable includes both one-foot and two-foot contours, produced from the mass points and breaklines, certified to meet or exceed NSSDA standards for one-foot contours. Two-foot contours within obscured vegetated areas are not required to meet NSSDA standards. These contours were also produced in accordance with the PDS team's Data Dictionary at Appendix C.

Table 3 is included below for ease in understanding the accuracy requirements when comparing the traditional National Map Accuracy Standard (NMAS) and the newer National Standard for Spatial Data Accuracy (NSSDA). This table is extracted from Table 13.2 of "Digital Elevation Model Technologies and Applications: The DEM Users Manual," published in January, 2007 by ASPRS. The traditional NMAS uses Vertical Map Accuracy Standard (VMAS) to define vertical accuracy at the 90% confidence level, whereas the NSSDA uses $Accuracy_z$ to define vertical accuracy at the 95% confidence level. Both the VMAS and $Accuracy_z$ are computed with different multipliers for the very same $RMSE_z$ value which represents vertical accuracy at the 68% confidence level for each equivalent contour interval specified. The term $Accuracy_z$ (vertical accuracy at the 95% confidence level) is comparable to the terms described below as Fundamental Vertical Accuracy (FVA), Consolidated Vertical Accuracy (CVA) and

Supplemental Vertical Accuracy (SVA) which also define vertical accuracy at the 95% confidence level. In open (non-vegetated) terrain, $Accuracy_z$ is exactly the same as FVA (both computed as $RMSE_z$ x 1.9600) because there is no logical justification for elevation errors to depart from a normal error distribution. In vegetated areas, vertical accuracy at the 95% confidence level ($Accuracy_z$) can also be computed as $RMSE_z$ x 1.9600; however, because vertical errors do not always have a normal error distribution in vegetated terrain, alternative guidelines from the National Digital Elevation Program (NDEP) and American Society for Photogrammetry and Remote Sensing (ASPRS) allow the 95th percentile method to be used (as with the CVA and SVA) to report the vertical accuracy at the 95% confidence level in land cover categories other than open terrain.

Table 3. Comparison of NMAS/NSSDA Vertical Accuracy

NMAS Equivalent Contour Interval	**NMAS** VMAS (90 percent confidence level)	**NSSDA** $RMSE_z$ (68 percent confidence level)	**NSSDA** $Accuracy_z$, (95 percent confidence level)
1 ft	0.5 ft	0.30 ft or 9.25 cm	0.60 ft or 18.2 cm
2 ft	1.0 ft	0.61 ft or 18.5 cm	1.19 ft or 36.3 cm

The next major deliverable includes metadata compliant with the Federal Geographic Data Committee's (FGDC) Content Standard for Spatial Metadata in an ArcCatalog-compatible XML format. Copies of all survey reports, including this Report of Specific Purpose LiDAR Survey, must be delivered in PDF format as attachments to the metadata.

The last major deliverable includes the Vertical Accuracy Report of Taylor County, based on independent comparison of the LiDAR data with the QA/QC checkpoints, surveyed and tested in accordance with guidelines of the National Standard for Spatial Data Accuracy (NSSDA), American Society for Photogrammetry and Remote Sensing (ASPRS), Federal Emergency Management Agency (FEMA), and National Digital Elevation Program (NDEP), and using the QA/QC checkpoints surveyed by Dewberry and listed at Appendix E.

Instead of delivering one vertical accuracy report, using 120 QA/QC checkpoints for each 500 square miles of the project area, separate reports are delivered for each county. Therefore, individual county vertical accuracy reports may be based on fewer than or more than 120 QA/QC checkpoints, depending on whether the area mapped in each county is smaller than or larger than 500 square miles. Regardless, the average density of QA/QC checkpoints remains the same on average for each countywide report.

Datums and Coordinates: North American Datum of 1983 (NAD 83)/HARN for horizontal coordinates and North American Vertical Datum of 1988 (NAVD 88) for vertical coordinates. All coordinates are Florida State Plane Coordinate System (SPCS) in U.S. Survey Feet. All Panhandle counties listed are in the Florida SPCS North Zone, except for Levy County which is delivered in both Florida SPCS North and West Zones. Levy County is normally in the West Zone but the LiDAR data are also delivered in the North Zone for ease in merger with all Panhandle counties for SLOSH modeling of all counties from Escambia through Levy.

Appendix I to this report provides the Geodatabase structure for all digital vector deliverables in Taylor County.

Acronyms and Definitions

3DS	Diversified Design & Drafting Services, Inc.
$Accuracy_r$	Horizontal (radial) accuracy at the 95% confidence level, defined by the NSSDA
$Accuracy_z$	Vertical accuracy at the 95% confidence level, defined by the NSSDA
ANA	Allen Nobles & Associates, Inc.
ASFPM	Association of State Floodplain Managers
ASPRS	American Society for Photogrammetry and Remote Sensing
CFM	Certified Floodplain Manager (ASFPM)
CMAS	Circular Map Accuracy Standard, defined by the NMAS
CP	Certified Photogrammetrist (ASPRS)
CVA	Consolidated Vertical Accuracy, defined by the NDEP and ASPRS
DEM	Digital Elevation Model (gridded DTM)
DTM	Digital Terrain Model (mass points and breaklines to map the bare earth terrain)
DSM	Digital Surface Model (top reflective surface, includes treetops and rooftops)
FDEM	Florida Division of Emergency Management
FEMA	Federal Emergency Management Agency
FGDC	Federal Geographic Data Committee
FOV	Field of View
FVA	Fundamental Vertical Accuracy, defined by the NDEP and ASPRS
GS	Geodetic Surveyor
GIS	Geographic Information System Surveyor
LAS	LiDAR data format as defined by ASPRS
LiDAR	Light Detection and Ranging
LMSI	Laser Mapping Specialists Inc.
MHHW	Mean Higher High Water
MHW	Mean High Water, defines official shoreline in Florida
MLLW	Mean Lower Low Water
MLW	Mean Low Water
MSL	Mean Sea Level
NAD 83	North American Datum of 1983
NAVD 88	North American Vertical Datum of 1988
NDEP	National Digital Elevation Program
NMAS	National Map Accuracy Standard
NOAA	National Oceanic and Atmospheric Administration
NSSDA	National Standard for Spatial Data Accuracy
NSRS	National Spatial Reference System
NWFWMD	Northwest Florida Water Management District
PDS	Program & Data Solutions, joint venture between PBS&J, Dewberry and URS Corp
PS	Photogrammetric Surveyor
PSM	Professional Surveyor and Mapper (Florida)
QA/QC	Quality Assurance/Quality Control
$RMSE_h$	Vertical Root Mean Square Error (RMSE) of ellipsoid heights
$RMSE_r$	Horizontal (radial) Root Mean Square Error (RMSE) computed from $RMSE_x$ and $RMSE_y$
$RMSE_z$	Vertical Root Mean Square Error (RMSE) of orthometric heights
SLOSH	Sea, Lake, and Overland Surges from Hurricanes
SRWMD	Suwannee River Water Management District
SVA	Supplemental Vertical Accuracy, defined by the NDEP and ASPRS

TIN	Triangulated Irregular Network
VMAS	Vertical Map Accuracy Standard, defined by the NMAS

Ground Surveys and Dates

Past experience with control in the Florida Panhandle area indicated a need to improve the accuracy of the existing survey monuments. For the nine newly-mapped counties in the Florida Panhandle, including Taylor County, the PDS team established a geodetic control network to provide accurate and consistent horizontal and vertical control for LiDAR and photogrammetric mapping using GPS technology. The project consisted of a Primary and two Secondary control networks supporting the mapping of approximately 6,113 square miles located in Northwest Florida. PBS&J managed the overall ground survey effort including management of field survey subcontractors, Allen Nobles & Associates, Inc. (ANA) and Diversified Design & Drafting Services, Inc. (3DS), which performed control surveys and QA/QC checkpoint surveys used for independent accuracy testing, and executed a network adjustment of control points used throughout the Florida panhandle.

The Primary network stations (see Figure 1) were used as base stations supporting the airborne GPS data acquisition, and as a consistent control framework for the more densely spaced Secondary control networks, and all subsequent control surveying activity on the project. They were setup at 40 kilometer spacing per the 2 centimeter requirements for Primary Control stated in the NOS NGS-58. The Primary Control network consisted of 55 stations, including 10 Continuously Operating Reference Stations (CORS), 27 existing monuments from the National Spatial Reference System (NSRS) and 18 new monuments set so as to limit LiDAR GPS baseline lengths to 20 Km relative to GPS base stations on either side of stations spaced ≈40 Km apart. Third order differential leveling was used to establish elevations on 20 Primary network stations in specific areas where published vertical stations could not be occupied directly with GPS. A minimally constrained (free) Least Squares adjustment was run to verify the internal accuracy of the Primary network. After evaluating and removing any outliers, a final free adjustment was generated, consisting of 191 independent vectors. The input error estimates were scaled by a factor of 14.90 which resulted in a properly weighted adjustment with a variance factor of 1.0154, with no flagged residuals. A constrained (fixed) 3-D horizontal adjustment was run using the same input error estimates as were used in the free adjustment; the variance factor was 1.3712 and there were no flagged residuals. A constrained (fixed) 1-D vertical adjustment was run using the same input error estimates as were used in the free adjustment; Station BE3991 was fixed in latitude, longitude and orthometric height; the variance factor was 1.2866 and there were no flagged residuals.

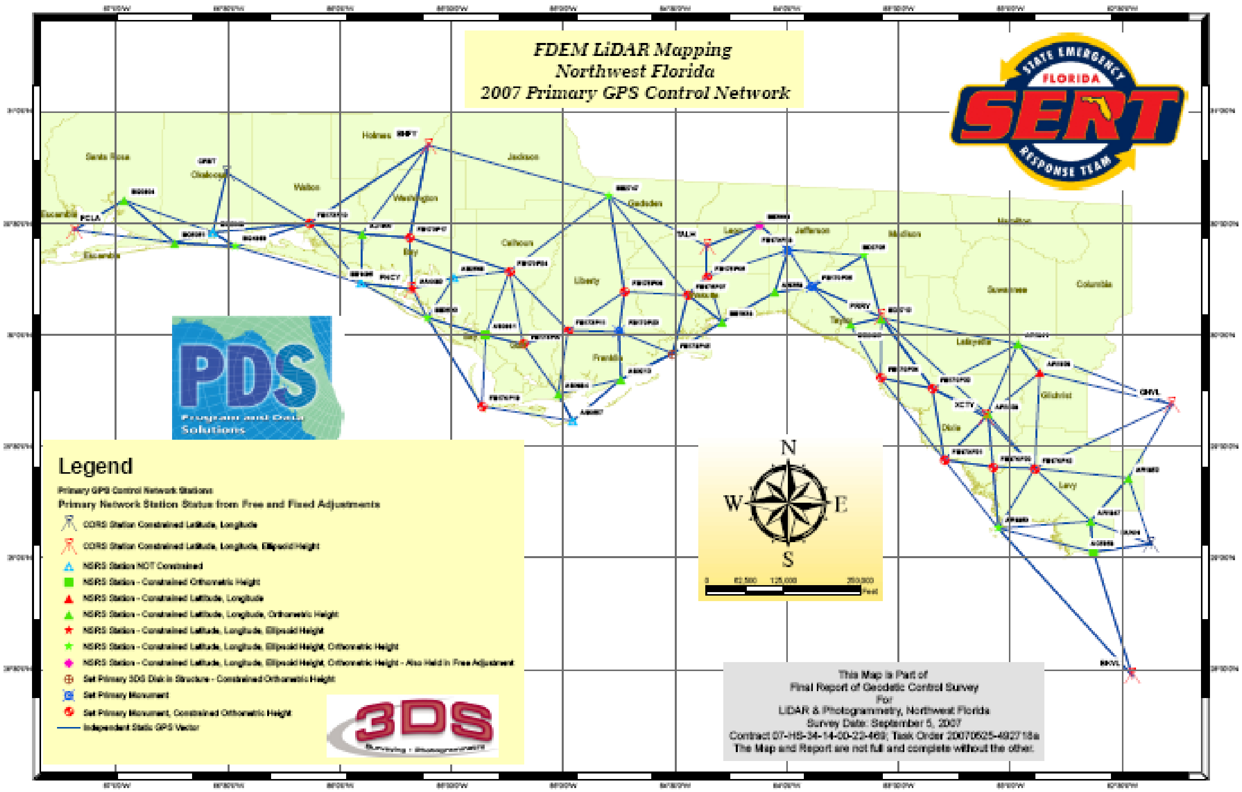


Figure 1. Primary Control Network

The Secondary network stations (see Figure 2) were used to support the measurement of both LiDAR and orthophoto QA/QC checkpoint sites. They were setup at 15 kilometer spacing per the 2 centimeter requirements for Secondary Control stated in NOS NGS-58.

The first Secondary Control network consisted of 4 stations in the Okaloosa County area. The second Secondary Control network consisted of all remaining mapping areas in the Florida Panhandle. The Secondary Control networks included a total of 80 control points, including 16 recovered NSRS monuments, 2 recovered DNR monuments, and 62 new monuments set for this network. A minimally constrained (free) Least Squares adjustment was run to verify the internal accuracy of the Secondary networks. After evaluating and removing any outliers, a final free adjustment was generated. This final free adjustment consisted of 254 independent vectors. The input error estimates were scaled by a factor of 6.234, which resulted in a properly weighted adjustment with a variance factor of 1.000; there were no flagged residuals. A constrained (fixed) 3-D horizontal adjustment was run using the same input error estimates as were used in the free adjustment; the variance factor was 1.6339 and there were six flagged residuals. A constrained (fixed) 1-D vertical adjustment was run using the same input error estimates as were used in the free adjustment; Station BE3991 was fixed in latitude, longitude and orthometric height; the variance factor was 1.2136 and there were no flagged residuals.

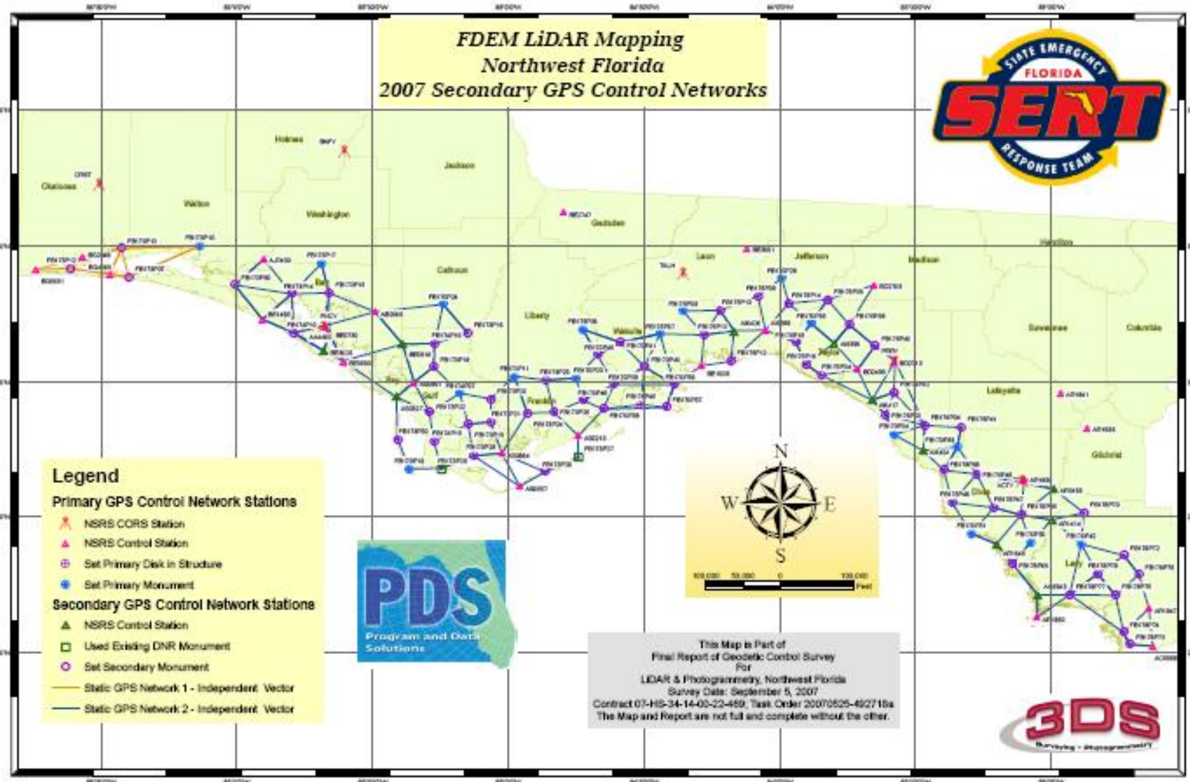


Figure 2. Secondary Control Networks

These GPS ground surveys were executed between May and September 2007. Full details are documented in 3DS's "Final Report of Geodetic Control Survey for LiDAR and Photogrammetry, Northwest Florida," dated March 13, 2008.

The QA/QC checkpoints used for this county are listed at Appendix E.

LiDAR Aerial Survey Areas and Dates

Sanborn collected the LiDAR data for Taylor County during the summer of 2007.

LiDAR Processing Methodology

A LiDAR processing report from Sanborn is included at Appendix D.

URS performed the LiDAR vertical accuracy assessment for Taylor County in accordance with *ASPRS Guidelines, Vertical Accuracy Reporting for Lidar Data*, May 24, 2004, and Section 1.5 of the *Guidelines for Digital Elevation Data*, published by the National Digital Elevation Program (NDEP), May 10, 2004. These guidelines call for the mandatory determination of Fundamental Vertical Accuracy (FVA) and Consolidated Vertical Accuracy (CVA), and the optional determination of Supplemental Vertical Accuracy (SVA). NOAA's accuracy specifications are compared with FDEM's accuracy specifications at Table 1. NOAA's checkpoint requirements are compared with FDEM's checkpoint requirements at Table 4.

Table 4. Comparison of FDEM and NOAA Checkpoint Requirements

	FDEM Specifications	NOAA Specifications
Land cover categories tested by QA/QC checkpoints	Four land cover categories tested: 1. Open terrain; bare-earth, low grass 2. Brush lands and low trees 3. Forested areas 4. Urban, built-up areas	Five land cover categories tested: 1. Open terrain; bare-earth, low grass 2. Weeds and crops 3. Scrub 4. Forested areas 5. Urban, built-up areas
Number of checkpoints per category	20 checkpoints, per category, for each 500 square mile area	20 checkpoints, per category, for each countywide dataset

The LiDAR dataset of Taylor County, delivered in May of 2008, passed the accuracy testing by URS as documented at Appendices E and F.

Fundamental Vertical Accuracy (FVA) is determined with QA/QC checkpoints located only in open terrain (grass, dirt, sand, and rocks) where there is a high probability that the LiDAR sensor detected the bare-earth ground surface, and where errors are expected to follow a normal error distribution. With a normal error distribution, the FVA at the 95 percent confidence level is computed as the vertical root mean square error ($RMSE_z$) of the checkpoints x 1.9600. The FVA is the same as $Accuracy_z$ at the 95% confidence level (for open terrain), as specified in Appendix 3-A of the *National Standard for Spatial Data Accuracy*, FGDC-STD-007.3-1998, see http://www.fgdc.gov/standards/projects/FGDC-standards-projects/accuracy/part3/chapter3. For FDEM, including Taylor County, the FVA standard is .60 feet, corresponding to an $RMSE_z$ of 0.30 feet or 9.25 cm, the accuracy expected from 1-foot contours. ***In Taylor County, the $RMSE_z$ in bare earth and low grass equaled 0.30 ft compared with the 0.30 ft specification of FDEM; and the FVA computed using $RMSE_z$ x 1.9600 was equal to 0.58 ft, compared with the 0.60 ft specification of FDEM.***

Consolidated Vertical Accuracy (CVA) is determined with all checkpoints, representing open terrain and all other land cover categories combined. If errors follow a normal error distribution, the CVA can be computed by multiplying the consolidated $RMSE_z$ by 1.9600. However, because bare-earth elevation errors often vary based on the height and density of vegetation, a normal error distribution cannot be assumed, and $RMSE_z$ cannot necessarily be used to calculate the 95 percent confidence level. Instead, a nonparametric testing method, based on the 95th percentile, may be used to determine CVA at the 95 percent confidence level. NDEP guidelines state that errors larger than the 95th percentile should be documented in the quality control report and project metadata. For FDEM, the CVA specification for all classes combined should be less than or equal to 1.19 feet; this same CVA specification was used by

NOAA. ***In Taylor County, the CVA computed using $RMSE_z$ x 1.9600 was equal to 0.86 ft, compared with the 1.19 ft specification of FDEM; and the CVA computed using the 95th percentile was equal to 0.84 ft. URS determined that the dataset passed the CVA standard.***

Supplemental Vertical Accuracy (SVA) is determined separately for each individual land cover category, recognizing that the LiDAR sensor and post-processing may not have mapped the bare-earth ground surface, and that errors may not follow a normal error distribution. SVA specifications are "target" values and not mandatory, recognizing that larger errors in some categories are offset by smaller errors in other land cover categories, so long as the overall mandatory CVA specification is satisfied. For each land cover category, the SVA at the 95 percent confidence level equals the 95^{th} percentile error for all checkpoints in that particular land cover category. For FDEM's specification, the SVA target is 1.19 feet for each category; this same SVA target specification was used by NOAA**.** ***In Taylor County, the SVA tested as 0.46 ft in bare earth and low grass, 0.47 ft in brush and low trees, 0.53 ft in forested areas, and 0.44 ft in urban terrain. All of these four land cover categories met theirs target value of 1.19 ft or less.***

The complete LiDAR Vertical Accuracy Report for Taylor County is at Appendix F.

LiDAR Horizontal Accuracy Testing

The LiDAR data was compiled to meet 3.8 feet horizontal accuracy at the 95% confidence level.

Whereas FDEM baseline specifications call for horizontal accuracy testing, traditional horizontal accuracy testing of LiDAR data is not cost effective for the following reasons:

- Paragraphs 3.2.2 and 3.2.3 of the National Standard for Spatial Data Accuracy (NSSDA) states: "Horizontal accuracy shall be tested by comparing the planimetric coordinates of well-defined points in the dataset with coordinates of the same points from an independent source of higher accuracy … when a dataset, e.g., a gridded digital elevation dataset or elevation contour dataset does not contain well-defined points, label for vertical accuracy only." Similarly, in Appendix 3-C of the NSSDA, paragraph 1 explains well-defined points as follows: "A well-defined point represents a feature for which the horizontal position is known to a high degree of accuracy and position with respect to the geodetic datum. For the purpose of accuracy testing, well-defined points must be easily visible or recoverable on the ground, on the independent source of higher accuracy, and on the product itself. Graphic contour data and digital hypsographic data may not contain well-defined points."
- Paragraph 1.5.3.4 of the *Guidelines for Digital Elevation Data*, published in 2004 by the National Digital Elevation Program (NDEP), states: "The NDEP does not require independent testing of horizontal accuracy for elevation products. When the lack of distinct surface features makes horizontal accuracy testing of mass points, TINs, or DEMs difficult or impossible, the data producer should specify horizontal accuracy using the following statement: *Compiled to meet __ (meters, feet) horizontal accuracy at 95 percent confidence level*."
- Paragraph 1.2, Horizontal Accuracy, of *ASPRS Guidelines, Vertical Accuracy Reporting for Lidar Data*, published by the American Society for Photogrammetry and Remote Sensing (ASPRS) in 2004, further explains why it is difficult and impractical to test the horizontal accuracy of LiDAR data, and explains why ASPRS does not require horizontal accuracy testing of LiDAR-derived elevation products.
- ASPRS has been actively seeking to develop cost-effective techniques to use LiDAR intensity imagery to test the horizontal accuracy of LiDAR data. As recently as May 1, 2008, at the annual conference of ASPRS, the most relevant technique for doing so was in a paper entitled "New

Horizontal Accuracy Assessment Tools and Techniques for Lidar Data," presented by the Ohio DOT. Whereas the technique had research value, it was neither practical nor affordable for use in horizontal accuracy testing of FDEM data.

- Appendix A of FDEM's Baseline Specifications require 20 horizontal test points for every 500 square mile area of digital orthophotos to be produced, and Appendix B of FDEM's Baseline Specifications requires 120 vertical test points for each 500 square mile area of LiDAR data to be produced. The PDS task orders included no funding for the more-expensive horizontal checkpoints that would be certain to appear on LiDAR intensity images as clearly-defined point features.
- In addition to LiDAR system factory calibration of horizontal and vertical accuracy, each of the PDS team's LiDAR subcontractors have different techniques for field calibration checks used to determine if bore-sighting is still accurate. Sanborn's technique, used for Taylor County, is explained at Appendix D. Sanborn's field calibration tests indicated the horizontal accuracy tested 2.274 feet at the 95 percent confidence level, well within FDEM's 3.8 foot specification.

LiDAR Qualitative Assessments

URS also performed the LiDAR qualitative assessment.

An assessment of the vertical accuracy alone does not yield a complete picture with regard to the usability of LiDAR data for its intended purpose. It is very possible for a given set of LiDAR data to meet the accuracy requirements, yet still contain artifacts (non-ground points) in the bare-earth surface, or a lack of ground points in some areas that may render the data, in whole or in part, unsuitable for certain applications.

Based on the extremely large volume of elevation points generated, it is neither time efficient, cost effective, nor technically practical to produce a perfectly clean (artifact-free) bare-earth terrain surface. The purpose of the LiDAR Qualitative Assessment Report (see Appendix G) is to provide a qualitative analysis of the "cleanliness" of the bare-earth terrain surface for use in supporting riverine and coastal analysis, modeling, and mapping.

The main software programs used by URS in performing the bare-earth data cleanliness review include the following:

- *GeoCue*: a geospatial data/process management system especially suited to managing large LiDAR data sets
- *TerraModeler*: used for analysis and visualization
- *TerraScan*: runs inside of MicroStation; used for point classification and points file generation
- *GeoCue LAS EQC:* is also used for data analysis and edit

The following systematic approach was followed by URS in performing the cleanliness review and analysis:

- Uploaded data to the GeoCue data warehouse (enhanced data management)
    - LiDAR: cut the data into uniform tiles measuring 5,000 feet by 5,000 feet – using the State Plane tile index provided by FDEM
    - Imagery: Best available orthophotography was used to facilitate the data review. Additional LiDAR Orthos were created from the LiDAR intensity data and used for review purposes.
- Performed coverage/gap check to ensure proper coverage of the project area

    - Created a large post grid (~30 meters) from the bare-earth points, which was used to identify any holes or gaps in the data coverage.
- Performed tile-by-tile analyses
    - Using TerraScan and LAS EQC, checked for gross errors in profile mode (noise, high and low points)
    - Reviewed each tile for anomalies; identified problem areas with a polygon, annotated comment, and screenshot as needed for clarification and illustration. Used ortho imagery when necessary to aid in making final determinations with regards to:
        - Buildings left in the bare-earth points file
        - Vegetation left in the bare-earth points file
        - Water points left in the bare-earth points file
        - Proper definition of roads
        - Bridges and large box culverts removed from the bare-earth points file
        - Areas that may have been "shaved off" or "over-smoothed" during the auto-filtering process
- Prepared and sent the error reports to LiDAR firm for correction
- Reviewed revisions and comments from the LiDAR firm
- Prepared and submitted final reports to FDEM

The LiDAR data of Taylor County was processed to a bare-earth terrain surface by Sanborn. The initial LiDAR dataset provided to URS for accuracy and qualitative assessment failed for three reasons: (1) systematic errors in vertical accuracy, (2) elevation offsets between flight lines and "cornrows" that exceeded the 20-cm criteria used by the LiDAR industry, and (3) excessive noise, artifacts and anomalies. The data was reprocessed and the revised dataset passed URS's qualitative assessment as reported at Appendix G.

Breakline Production Methodology

For the *hard breaklines*, Sanborn used GeoCue software to develop LiDAR stereo models of Taylor County so the LiDAR derived data could be viewed in 3-D stereo using Socet Set softcopy photogrammetric software. Using LiDARgrammetry procedures with LiDAR intensity imagery, Sanborn stereo-compiled the eight types of *hard breaklines* in accordance with the Data Dictionary at Appendix C.

For the *soft hydro breaklines*, Dewberry used 2.5-D techniques to digitize soft, linear hydrographic features first in 2-D and then used its GeoFIRM toolkit to drape the soft breaklines over the ESRI Terrain to derive the Z-values (elevations), also consistent with the Data Dictionary at Appendix C. All breakline compilation was performed under the direct supervision of an ASPRS Certified Photogrammetrist and Florida Professional Surveyor and Mapper (PSM). The breaklines conform with data format requirements outlined by the FDEM Baseline Specifications.

Whereas flowing rivers and streams are "hydro-enforced" to depict the downward flow of water, dry drainage features are not "hydro-enforced" but deliberately include undulations that more-accurately represent the true topography. This is, in fact, the ideal situation for topographic mapping.

The five figures below demonstrate how the PDS team's high LiDAR point density (4 points per square meter) are used to penetrate dense vegetation and accurately map the dry drainage feature not visible from a normal digital orthophoto (Figure 1); the total density of the LiDAR point cloud (Figure 2); the density of LAS Class 2 points that penetrated to the ground (Figure 3); the color-coded Terrain to help in visualizing the variable elevations (Figure 4); and the soft hydro breakline that approximates the potential flow line of the dry drainage feature and the contours that clearly show the undulations in the Terrain (Figure 5). At Figure 5, the 9-foot contour lines are *depression contours* that surround elevation points that are lower than 9-feet. Although the undulations, by definition, are not "hydro-enforced," the PDS Team's PSM in responsible charge of this project considers it a violation of professional standards if one were to deliberately degrade the accurate Terrain, soft hydro breakline and contours in a dry drainage feature in order to "hydro-enforce" that feature by filling the depressions and falsely scalping off the higher undulations in order to make an idealized monotonic dry streambed out of the true undulating streambed. To "hydro-enforce" such a dry streambed would be to falsify the true topography of naturally undulating terrain. The soft hydro breaklines are part of the hydrographic feature class, but have a separate sub-class code, 3. This enables hydro-enforced hydrographic features, sub-class codes 1 and 2 for single and dual lines, to be distinguished from these non-hydro-enforced soft hydrographic features representing dry drainage features.

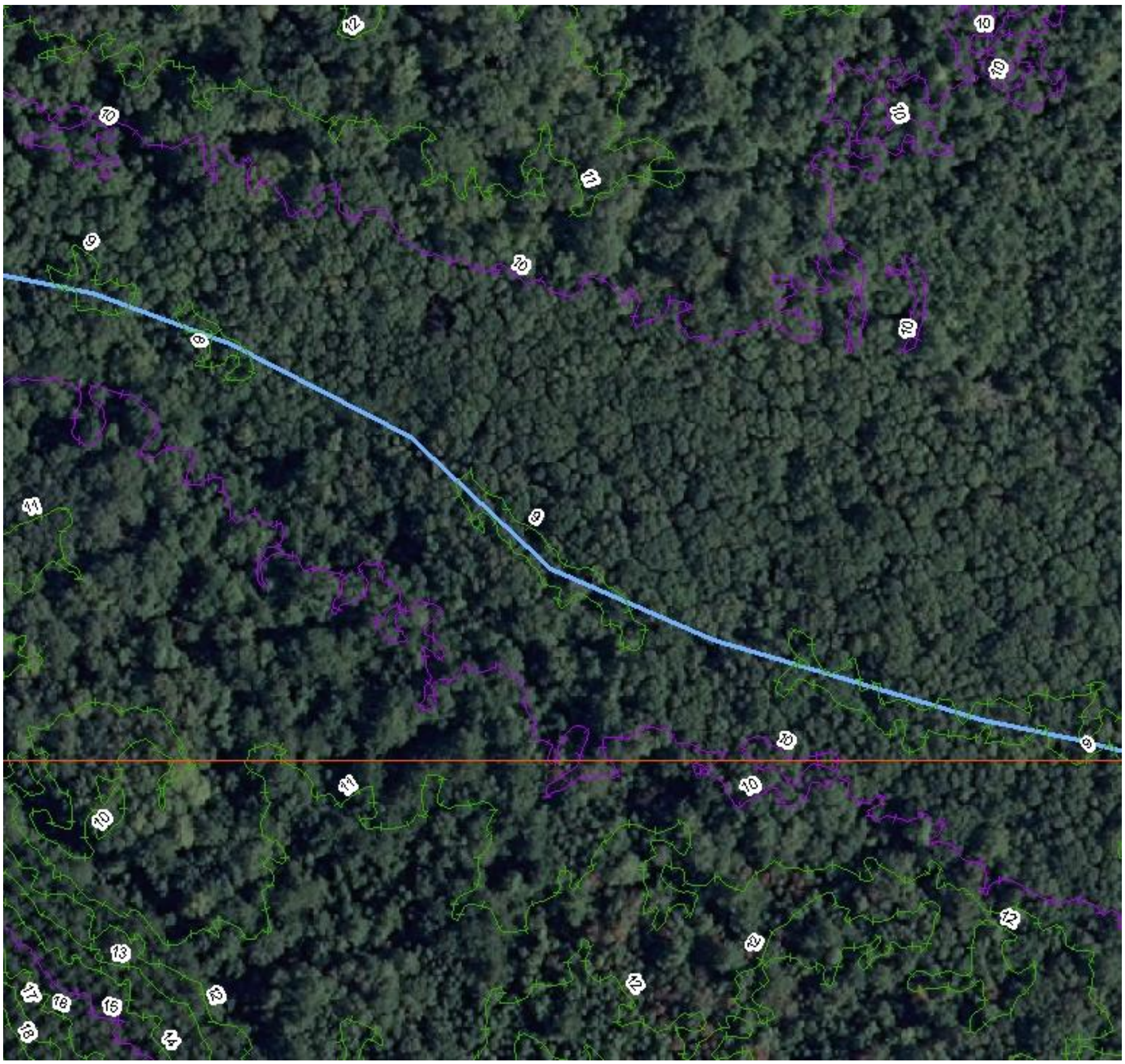


Figure 3. Even in very dense vegetation, the PDS team's high LiDAR point density (4 points per square meter) enabled the detection of dry drainage features beneath the vegetation.

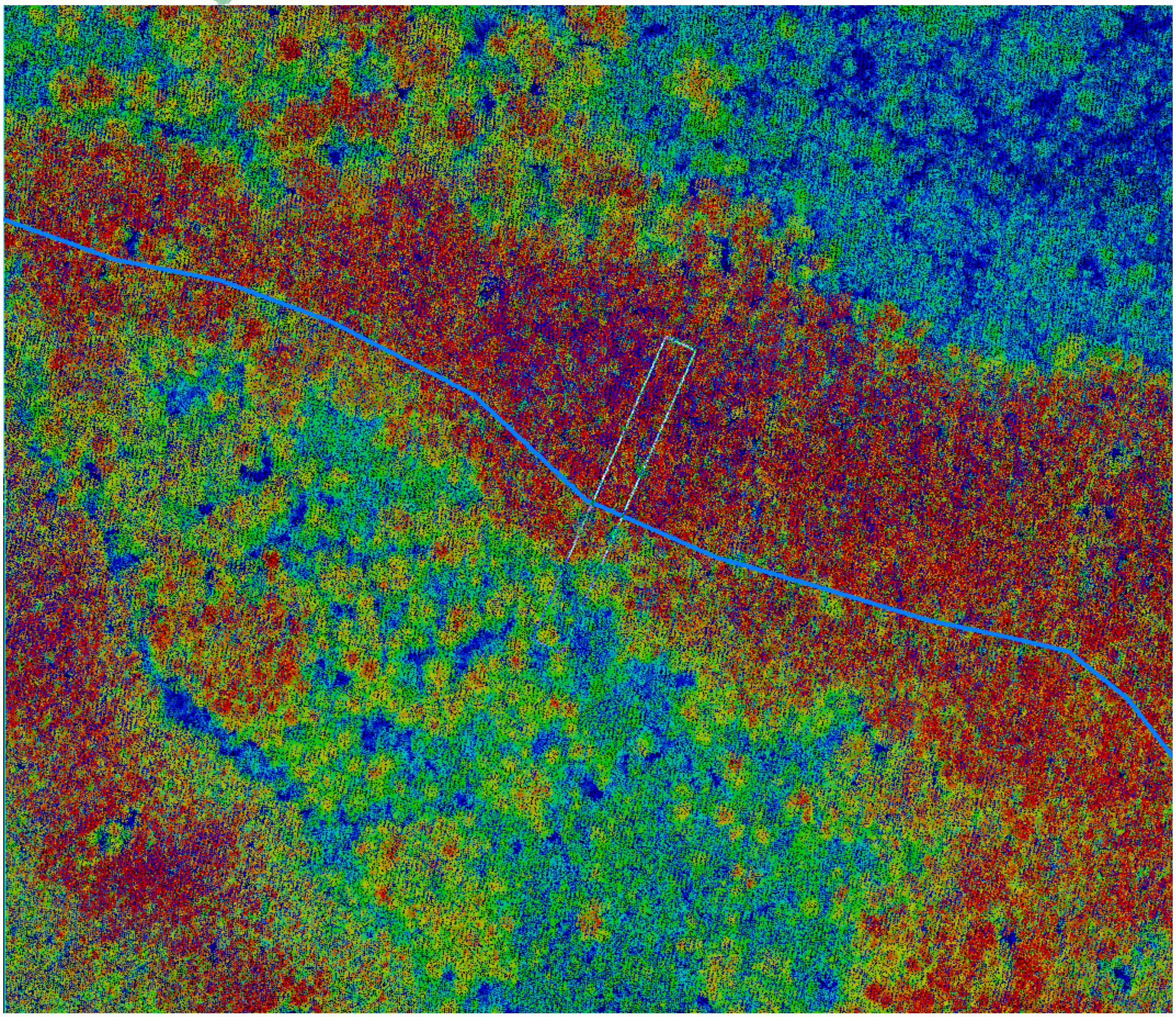
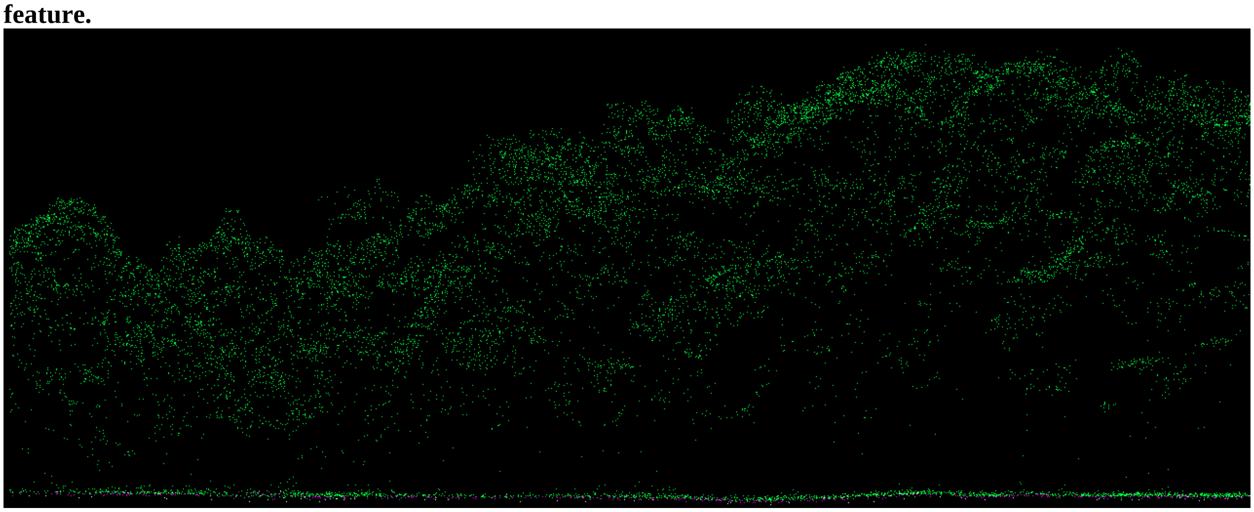


Figure 4. Full point cloud with profile (below) showing density of vegetation in the area of the dry drainage feature.



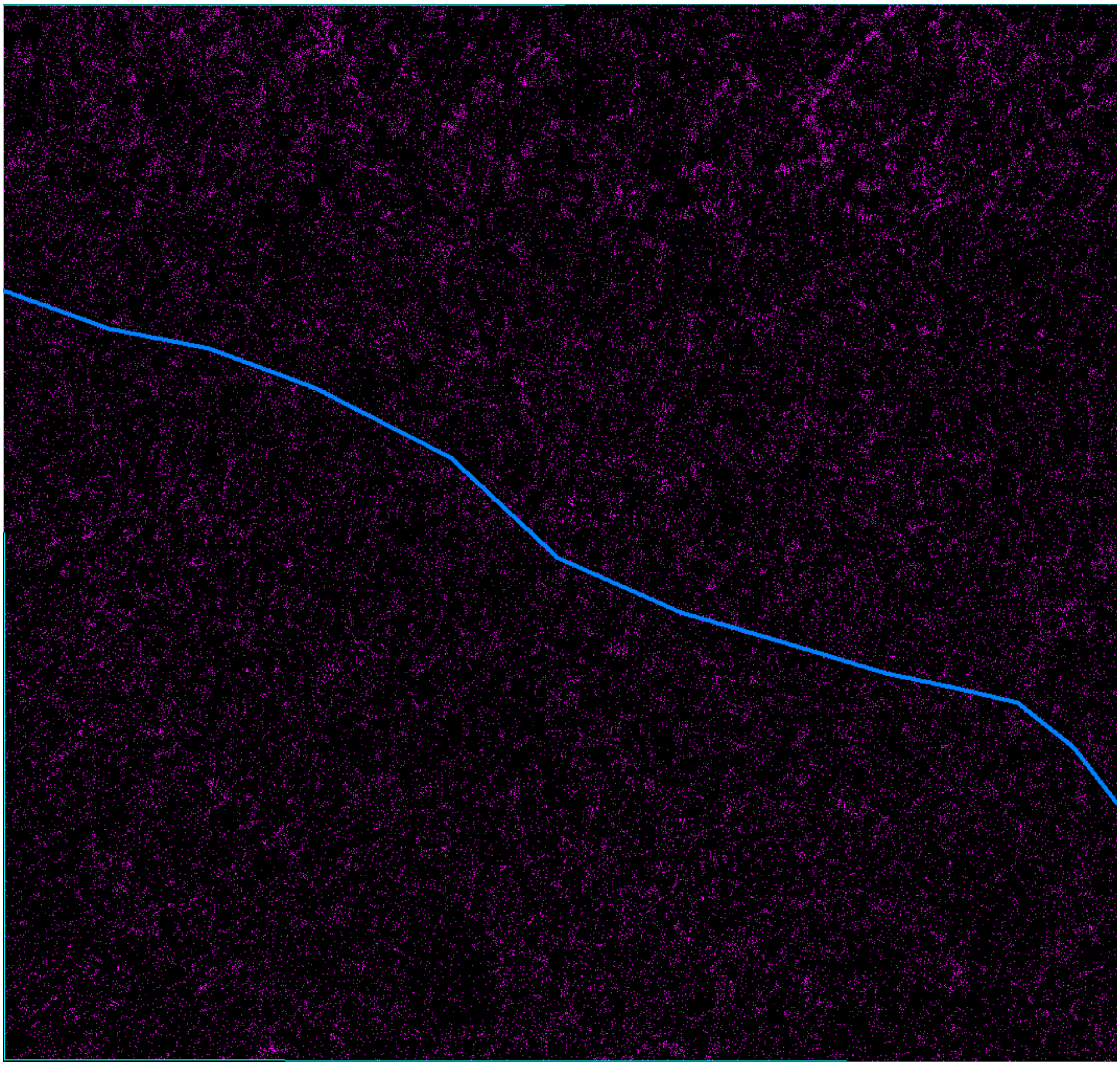


Figure 5. LAS Class 2 (ground) points showing the high density of points that penetrated the vegetation.

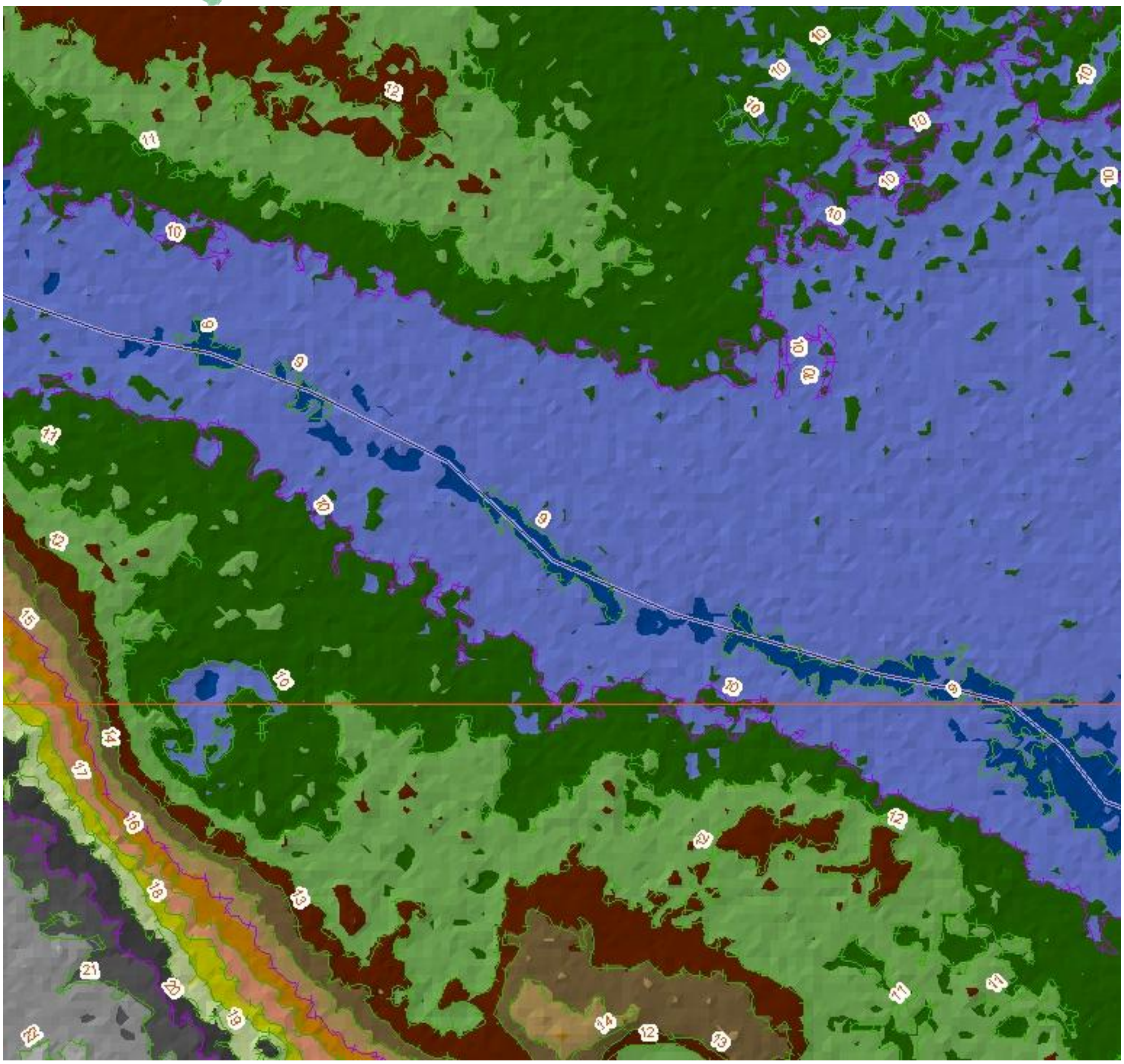


Figure 6. The ESRI Terrain is color-coded to depict the variable elevation bands. This clearly shows the lower, undulating elevations in the dry drainage feature.

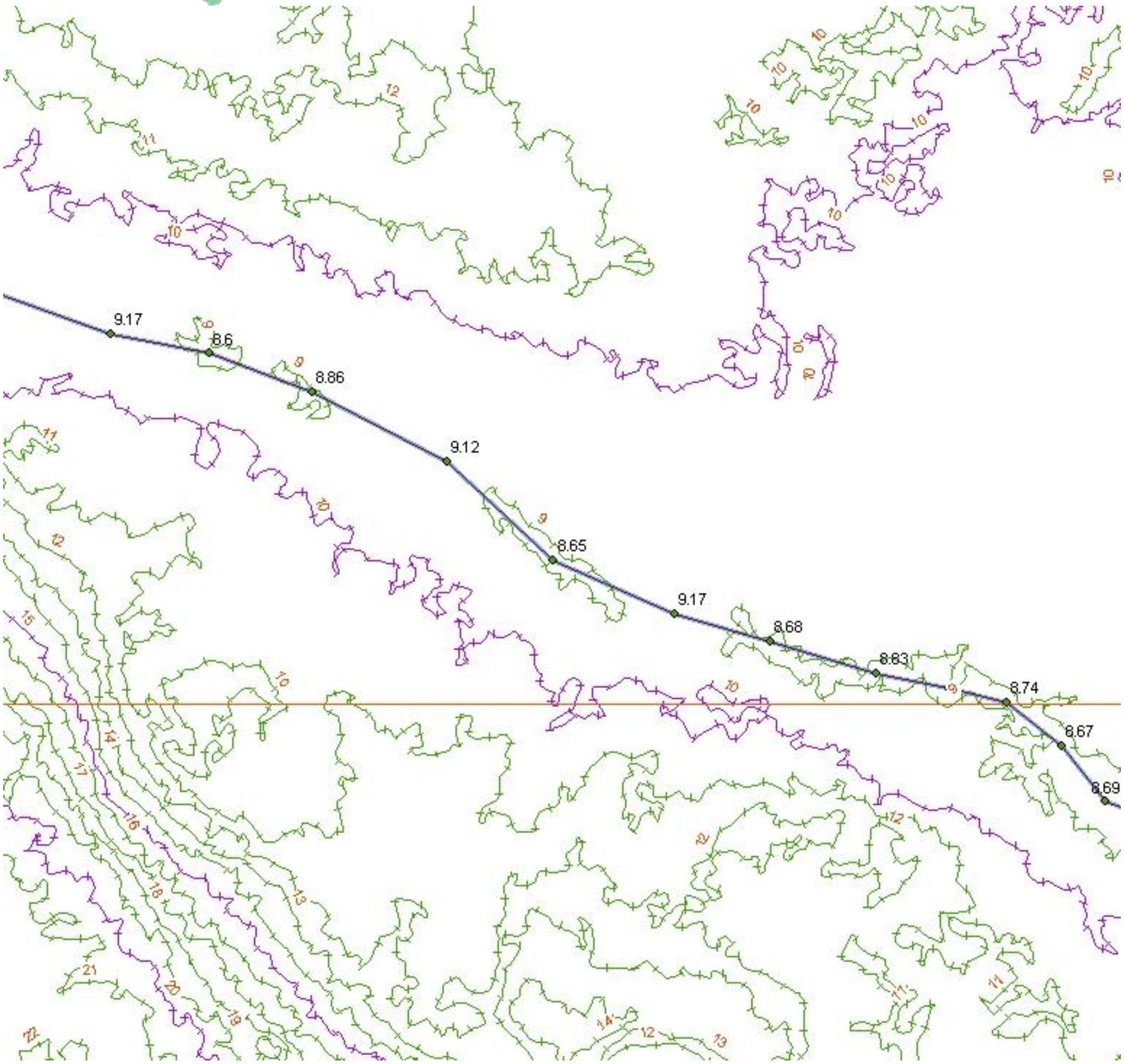


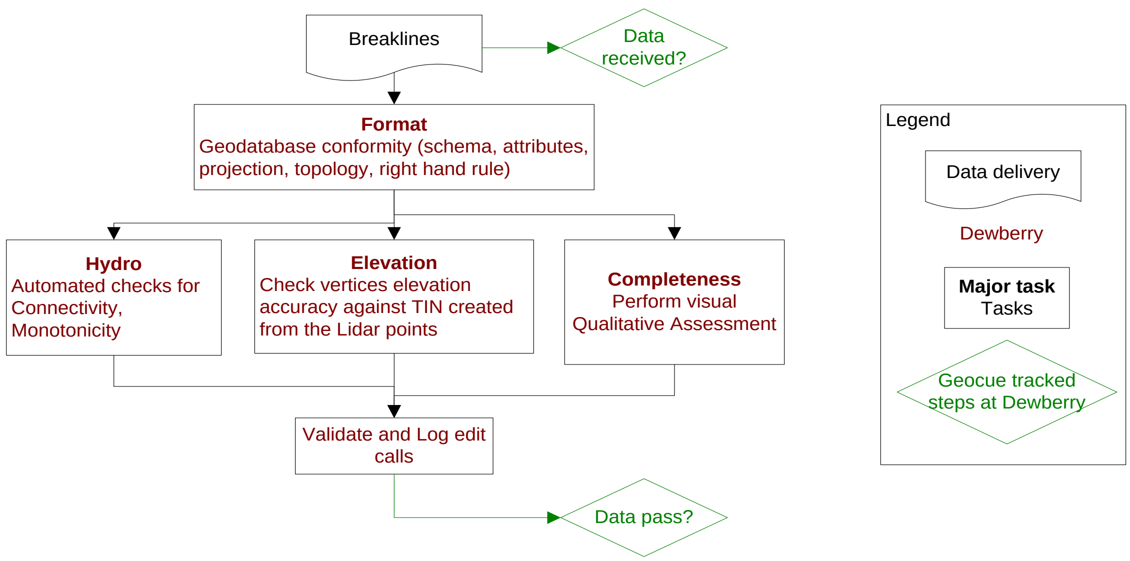
Figure 7. This figure shows variable "invert elevations" along the soft hydro breakline. It also shows "depression contours" where water would normally puddle if the drainage feature was only half dry. The soft hydro breakline passing through the "depression contours" clearly depict elevations lower than the 9-foot contour lines.

Contour Production Methodology

Sanborn used proprietary procedures to generate accurate contours from the LiDAR and breakline data. Using the LiDAR, a digital elevation model is filtered and further interpolated as a triangulated irregular network (TIN) of points. The TIN is rasterized to an ESRI GRID format and with the compiled breaklines, the 2-foot and 1-foot contours are generated and in accordance with the Data Dictionary at Appendix C. The contours conform to data format Requirements outlined by the FDEM Baseline Specifications.

Breakline Qualitative Assessments

Dewberry performed the breakline qualitative assessments. The following workflow diagram represents the steps taken by Dewberry to provide a thorough qualitative assessment of the breakline data.



In order to ensure a correct database format, Dewberry provided all subcontractors with geodatabase shells containing the required feature classes in the required format. Upon receipt of the data, Dewberry verified that the correct shell was used and validated the topology rules associated with it.

Feature Class	Rule	Feature Class
SOFTFEATURE	Must Not Intersect	
OVERPASS	Must Not Intersect	
ROADBREAKLINE	Must Not Intersect	
HYDROGRAPHIC...	Must Not Intersect	
SOFTFEATURE	Must Not Overlap With	ROADBREAKLINE
SOFTFEATURE	Must Not Overlap With	HYDROGRAPHICF
ROADBREAKLINE	Must Not Overlap With	HYDROGRAPHICF
SOFTFEATURE	Must Not Self-Intersect	
OVERPASS	Must Not Self-Intersect	
ROADBREAKLINE	Must Not Self-Intersect	
HYDROGRAPHIC...	Must Not Self-Intersect	

Figure 8. Breaklines topology rules

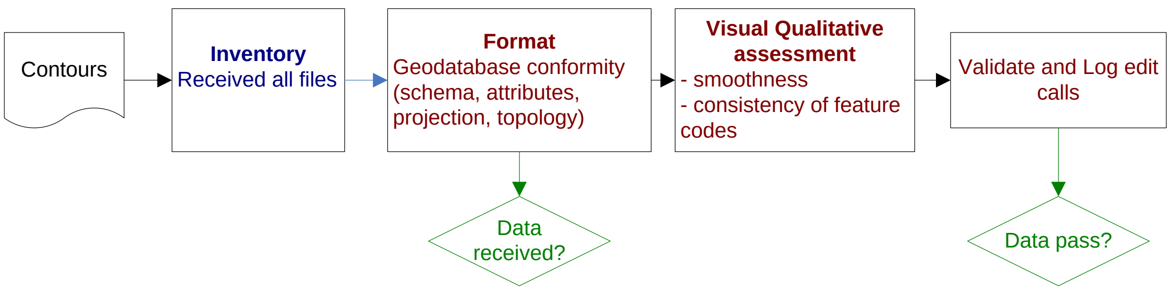
Then automated checks are applied on hydrofeatures to validate the 3D connectivity of the feature and the monotonicity of the hydrographic breaklines. Dewberry's major concern was that the hydrographic breaklines have a continuous flow downhill and that breaklines do not undulate. Error points are generated at each vertex not complying with the tested rules and these potential edit calls are then visually validated during the visual evaluation of the data. This step also helped validate that breakline vertices did not have excessive minimum or maximum elevations and that elevations are consistent with adjacent vertex elevations.

The next step is to compare the elevation of the breakline vertices against the elevation extracted from the TIN built from the LiDAR ground points, keeping in mind that a discrepancy is expected because of the hydro-enforcement applied to the breaklines and because of the interpolated imagery used to acquire the breaklines. A given tolerance is used to validate if the elevations do not differ too much from the LiDAR.

Dewberry's final check for the breaklines was to perform a full qualitative analysis of the breaklines. Dewberry compared the breaklines against LiDAR intensity images to ensure breaklines were captured in the required locations.

Contour Qualitative Assessments

Dewberry also performed the qualitative assessments of the contours using the following workflow.



Upon receipt of each delivery area, the first step performed by Dewberry was a series of data topology validations. Dewberry checked for the following instances in the data:

1. Contours must not overlap
2. Contours must not intersect
3. Contours must not have dangles (except at project boundary)
4. Contours must not self-overlap
5. Contours must not self-intersect

After the topology and geodatabase format validation was complete, Dewberry checked the elevation attribute of each contour to ensure NULL values are not included. Finally, Dewberry loaded the contour data plus the LiDAR intensity images into ArcGIS and performed a full qualitative review of the contour data for smoothness and consistency of feature codes.

Appendix H summarizes Dewberry's qualitative assessments of the breaklines and contours, with graphic examples of what the breaklines and contours look like.

Deliverables

Except for the Report of Geodetic Control Survey for LiDAR and Photogrammetry, dated March 13, 2008, which was delivered separately and pertains to all deliverables in the Florida Panhandle, the deliverables listed at Table 5 are included on the external hard drive that accompanies this report.

Table 5. Summary of Deliverables

Copies	Deliverable Description	Format	Location
2	Report of Geodetic Control Survey for LiDAR and Photogrammetry, Northwest Florida, dated 3/13/2008	Hardcopy and pdf	Submitted separately
1	Data Dictionary	pdf	Appendix C
3	LiDAR Processing Report	Hardcopy and pdf	Appendix D

3	LiDAR Vertical Accuracy Report	Hardcopy and pdf	Appendix F
1	LiDAR Qualitative Assessment Report	pdf	Appendix G
1	Breakline/Contour Qualitative Assessment Report	pdf	Appendix H
1	Breaklines, Contours, Network-Adjusted Control Points, Vertical accuracy checkpoints, Tiling Footprint, Lidar ground masspoints	Geodatabase	Submitted separately

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NOAA, 1997, *Guidelines for Establishing GPS-Derived Ellipsoid Heights (Standards: 2 cm and 5 cm),* NOAA Technical Memorandum NOS NGS-58, November, 1997.

General Notes

This report is incomplete without the external hard drives of the LiDAR masspoints, breaklines, contours, and control. See the Geodatabase structure at Appendix I.

This digital mapping data complies with the Federal Emergency Management Agency (FEMA) "Guidelines and Specifications for Flood Hazard Mapping Partners," Appendix A: *Guidance for Aerial Mapping and Surveying.*

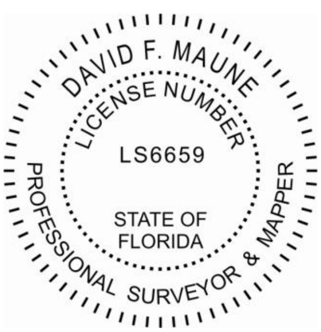
The LiDAR vertical accuracy report at Appendix F conforms with the National Standard for Spatial Data Accuracy (NSSDA).

The digital mapping data is certified to conform to Appendix B, *Terrestrial LiDAR Specifications*, of the "Florida Baseline Specifications for Orthophotography and LiDAR." This report is certified to conform with Chapter 61G17-6, Minimum Technical Standards, of the Florida Administrative Code, as pertains to a Specific Purpose LiDAR Survey.

THIS REPORT IS NOT VALID WITHOUT THE SIGNATURE AND RAISED SEAL OF A FLORIDA PROFESSIONAL SURVEYOR AND MAPPER IN RESPONSIBLE CHARGE.

Surveyor and Mapper in Responsible Charge:
David F. Maune, PhD, PSM, PS, GS, CP, CFM
Professional Surveyor and Mapper
License #LS6659

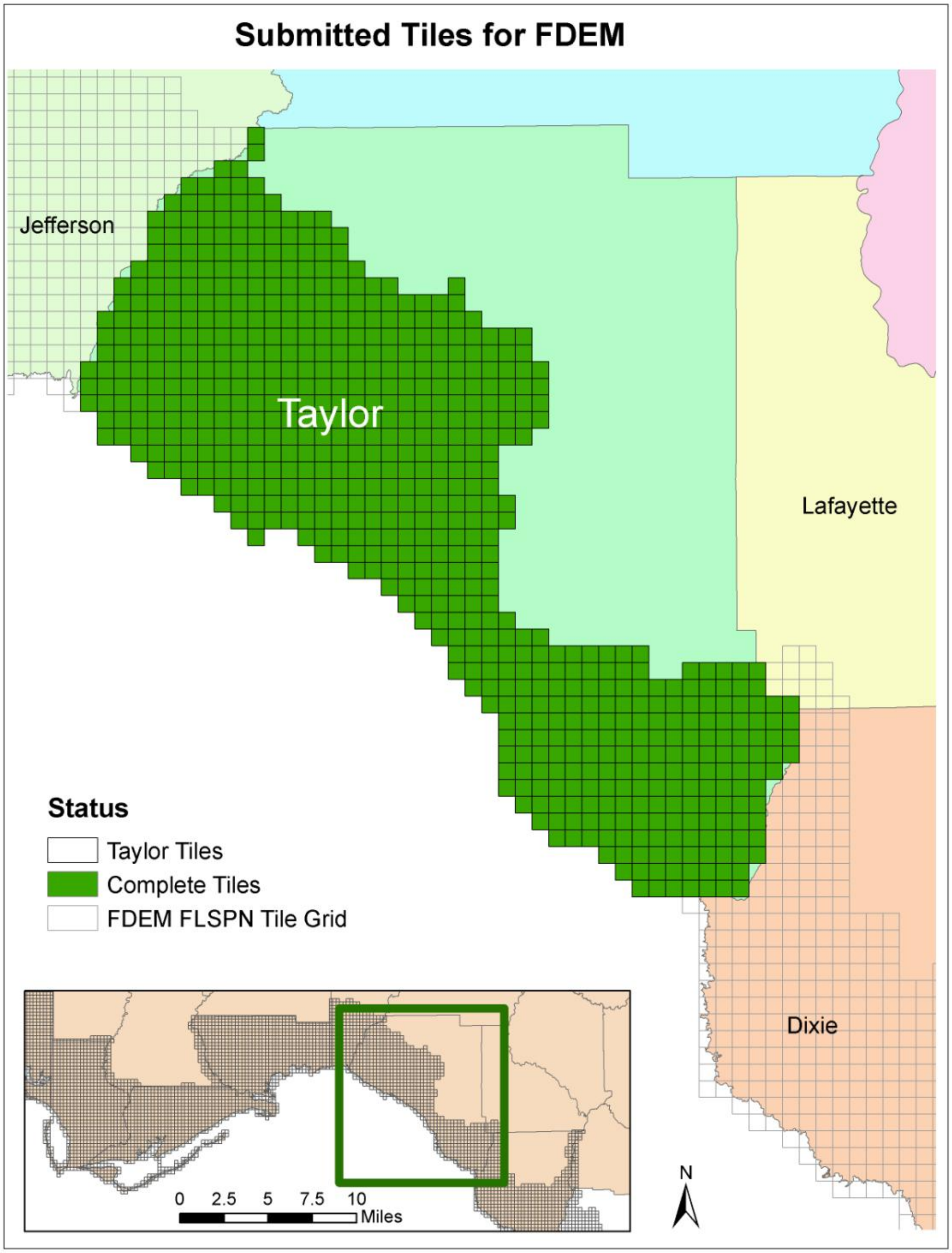
Signed: ________________________________ Date: ________________



List of Appendices

Appendix A: County Project Tiling Footprint: Taylor

692 complete tiles delivered



List of delivered complete tiles (692):

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075897_N

Appendix B: Taylor County Geodetic Control Points

Station	County	Longitude (DMS)	Latitude (DMS)	Ortho Height (meters)	Ellipsoid Height (meters)	Description
BD2495	Taylor	83 42 48.17557	30 2 38.76487	18.76	-8.88	RECOVERED NSRS STATION (SEE DATASHEET PID# BD2495)
BD2713	Taylor	83 34 43.81887	30 4 26.01888	12.811	-14.934	RECOVERED NSRS STATION (SEE DATASHEET PID# BD2713)
PRRY	Taylor	83 34 28.60998	30 4 40.11920	14.788	-12.951	NSRS CORS STATION (SEE DATASHEET PID# DE9140)
AI6399	Taylor	83 47 58.95454	30 8 33.43506	7.468	-20.051	RECOVERED NSRS STATION (SEE DATASHEET PID# AI6399)
AI6417	Taylor	83 39 32.74285	29 55 56.25752	3.752	-23.972	RECOVERED NSRS STATION (SEE DATASHEET PID# AI6417)
AI6424	Taylor	83 28 18.19658	29 44 44.89821	6.945	-20.828	RECOVERED NSRS STATION (SEE DATASHEET PID# AI6424)
FB175P15	Taylor	83 56 19.72448	30 8 35.94422	2.803	-24.665	SET SECONDARY MONUMENT
FB175P16	Taylor	83 54 14.96527	30 3 49.40316	1.673	-25.815	SET SECONDARY MONUMENT
FB175P34	Taylor	83 50 48.78120	30 1 24.56089	1.247	-26.29	SET SECONDARY MONUMENT
FB175P38	Taylor	83 44 37.68931	30 12 35.30583	11.267	-16.29	SET SECONDARY MONUMENT
FB175P39	Taylor	83 49 25.32445	30 18 10.25249	12.756	-14.81	SET SECONDARY MONUMENT
FB175P40	Taylor	83 38 59.33344	30 7 50.81318	9.469	-18.186	SET SECONDARY MONUMENT
FB175P41	Taylor	83 19 54.75002	29 49 50.85918	9.322	-18.444	SET SECONDARY MONUMENT
FB176P02	Taylor	83 34 48.61321	29 57 35.17582	12.142	-15.641	SET SECONDARY MONUMENT
FB176P03	Taylor	83 36 39.36313	29 52 39.87277	4.062	-23.72	SET SECONDARY MONUMENT
FB176P04	Taylor	83 27 58.68060	29 50 20.19914	9.763	-18.041	SET SECONDARY MONUMENT
FB178P68	Taylor	83 23 45.06127	29 40 25.25618	2.073	-25.623	SET SECONDARY MONUMENT
FB170P33	Taylor	83 20 47.03578	29 45 34.55057	5.317	-22.362	SET PRIMARY MONUMENT
FB170P34	Taylor	83 34 43.94352	29 48 17.85733	1.207	-26.577	SET PRIMARY MONUMENT
FB170P35	Taylor	83 53 5.50826	30 12 51.97503	8.766	-18.734	SET PRIMARY MONUMENT

Appendix C: Data Dictionary

LiDARgrammetry Data Dictionary
& Stereo Compilation Rules

FINAL

FDEM (Florida Department of Emergency Management)
January 25, 2008

Table of Contents

Horizontal and Vertical Datum

Horizontal datum shall be referenced to the appropriate Florida State Plane Coordinate System. The horizontal datum shall be North American Datum of 1983/HARN adjustment in US Survey Feet. The vertical datum shall be referenced to the North American Vertical Datum of 1988 (NAVD 88). Geoid03 shall be used to convert ellipsoidal heights to orthometric heights.

Coordinate System and Projection

All data shall be projected to the appropriate Florida State Plane Coordinate System Zone, Units in US Survey Feet.

Contour Topology Rules

The following contour topology rules have been incorporated into each geodatabase shell provided by PDS. The topology must be validated by each subcontractor prior to delivery to PDS. PDS shall further validate the topology before final submittal to FDEM.

Name: CONTOURS_Topology				Cluster Tolerance: 0.003 Maximum Generated Error Count: Undefined State: Analyzed without errors
Feature Class	**Weight**	**XY Rank**	**Z Rank**	**Event Notification**
CONTOUR_1FT	5	1	1	No
CONTOUR_2FT	5	1	1	No

Topology Rules

Name	Rule Type	Trigger Event	Origin (*FeatureClass::Subtype*)	Destination (*FeatureClass::Subtype*)
Must not intersect	The rule is a line-no intersection rule	No	CONTOUR_1FT::All	CONTOUR_1FT::All
Must not intersect	The rule is a line-no intersection rule	No	CONTOUR_2FT::All	CONTOUR_2FT::All
Must not self-intersect	The rule is a line-no self intersect rule	No	CONTOUR_2FT::All	CONTOUR_2FT::All
Must not self-intersect	The rule is a line-no self intersect rule	No	CONTOUR_1FT::All	CONTOUR_1FT::All

Breakline Topology Rules

The following breakline topology rules have been incorporated into each geodatabase shell provided by PDS. The topology must be validated by each subcontractor prior to delivery to PDS. PDS shall further validate the topology before final submittal to FDEM.

Name: BREAKLINES_Topology			Cluster Tolerance: 0.003 Maximum Generated Error Count: Undefined State: Analyzed without errors	
Feature Class	**Weight**	**XY Rank**	**Z Rank**	**Event Notification**
COASTALSHORELINE	5	1	1	No
HYDROGRAPHICFEATURE	5	1	1	No
OVERPASS	5	1	1	No
ROADBREAKLINE	5	1	1	No
SOFTFEATURE	5	1	1	No

Topology Rules

Name	Rule Type	Trigger Event	Origin (*FeatureClass::Subtype*)	Destination (*FeatureClass::Subtype*)
Must not intersect	The rule is a line-no intersection rule	No	SOFTFEATURE::All	SOFTFEATURE::All
Must not intersect	The rule is a line-no intersection rule	No	OVERPASS::All	OVERPASS::All
Must not intersect	The rule is a line-no intersection rule	No	ROADBREAKLINE::All	ROADBREAKLINE::All
Must not intersect	The rule is a line-no intersection rule	No	HYDROGRAPHICFEATURE::All	HYDROGRAPHICFEATURE::All
Must not intersect	The rule is a line-no intersection rule	No	COASTALSHORELINE::All	COASTALSHORELINE::All
Must not overlap	The rule is a line-no overlap line rule	No	SOFTFEATURE::All	ROADBREAKLINE::All
Must not overlap	The rule is a line-no overlap line rule	No	SOFTFEATURE::All	HYDROGRAPHICFEATURE::All
Must not overlap	The rule is a line-no overlap line rule	No	SOFTFEATURE::All	COASTALSHORELINE::All
Must not overlap	The rule is a line-no overlap line rule	No	ROADBREAKLINE::All	HYDROGRAPHICFEATURE::All
Must not overlap	The rule is a line-no overlap line rule	No	ROADBREAKLINE::All	COASTALSHORELINE::All
Must not overlap	The rule is a line-no overlap line rule	No	HYDROGRAPHICFEATURE::All	COASTALSHORELINE::All
Must not self-intersect	The rule is a line-no self intersect rule	No	SOFTFEATURE::All	SOFTFEATURE::All
Must not self-intersect	The rule is a line-no self intersect rule	No	OVERPASS::All	OVERPASS::All
Must not self-intersect	The rule is a line-no self intersect rule	No	ROADBREAKLINE::All	ROADBREAKLINE::All
Must not self-intersect	The rule is a line-no self intersect rule	No	HYDROGRAPHICFEATURE::All	HYDROGRAPHICFEATURE::All
Must not self-intersect	The rule is a line-no self intersect rule	No	COASTALSHORELINE::All	COASTALSHORELINE::All

Coastal Shoreline

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: COASTALSHORELINE
Contains Z Values: Yes
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Polygon
Annotation Subclass: None

Description

This polygon feature class will outline the land / water interface at the time of LiDAR acquisition.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
SHAPE_LENGTH	Double	Yes			0	0		Calculated by PDS
SHAPE_AREA	Double	Yes			0	0		Calculated by PDS
TYPE	Long Integer	No	1	Coast	0	0		Assigned by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Coastal Shoreline	The coastal breakline will delineate the land water interface using LiDAR data as reference. In flight line boundary areas with tidal variation the coastal shoreline may require some feathering or edge matching to ensure a smooth transition. Orthophotography will not be use to delineate this shoreline.	The feature shall be extracted at the apparent land/water interface, as determined by the LiDAR intensity data, to the extent of the tile boundaries. For the polygon closure vertices and segments, null values or a value of 0 are acceptable since this is not an actual shoreline. The digital orthophotography is not a suitable source for capturing this feature. Efforts should be taken to gradually feather the difference between tidal conditions of neighboring flights. Stair-stepping of the breakline feature will not be allowed. If it can be reasonably determined where the edge of water most probably falls, beneath the dock or pier, then the edge of water will be collected at the elevation of the water

			where it can be directly measured. If there is a clearly-indicated headwall or bulkhead adjacent to the dock or pier and it is evident that the waterline is most probably adjacent to the headwall or bulkhead, then the water line will follow the headwall or bulkhead at the elevation of the water where it can be directly measured. If there is no clear indication of the location of the water's edge beneath the dock or pier, then the edge of water will follow the outer edge of the dock or pier as it is adjacent to the water, at the measured elevation of the water. Breaklines shall snap and merge seamlessly with linear hydrographic features.

Linear Hydrographic Features

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: HYDROGRAPHICFEATURE
Contains Z Values: Yes
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Polyline
Annotation Subclass: None

Description

This polyline feature class will depict linear hydrographic features with a length of 0.5 miles or longer as breaklines.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
SHAPE_LENGTH	Double	Yes			0	0		Calculated by PDS
TYPE	Long Integer	No	1	HydroL	0	0		Assigned by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Single Line Feature	Linear hydrographic features such as streams, shorelines, canals, swales, embankments, etc. with an average width less than or equal to 8 feet. . In the case of embankments, if the feature forms a natural dual line channel, then capture it consistent with the capture rules. Other embankments fall into the soft breakline feature class	Capture linear hydro features as single breaklines. Average width shall be 8 feet or less to show as single line. Each vertex placed should maintain vertical integrity.
2	Dual Line Feature	Linear hydrographic features such as streams, shorelines, canals, swales, etc. with an average width greater than 8 feet. In the case of embankments, if the feature forms a natural dual line channel, then capture it consistent with the capture rules. Other embankments fall into the soft breakline feature class.	Capture features showing dual line (one on each side of the feature). Average width shall be great than 8 feet to show as a double line. Each vertex placed should maintain vertical integrity and data is not required to show “closed polygon”. These instructions are only for docks or piers that follow

			the coastline or water's edge, not for docks or piers that extend perpendicular from the land into the water. If it can be reasonably determined where the edge of water most probably falls, beneath the dock or pier, then the edge of water will be collected at the elevation of the water where it can be directly measured. If there is a clearly-indicated headwall or bulkhead adjacent to the dock or pier and it is evident that the waterline is most probably adjacent to the headwall or bulkhead, then the water line will follow the headwall or bulkhead at the elevation of the water where it can be directly measured. If there is no clear indication of the location of the water's edge beneath the dock or pier, then the edge of water will follow the outer edge of the dock or pier as it is adjacent to the water, at the measured elevation of the water.
3	Soft Hydro Single Line Feature	Linear hydro features with an average width less than 8 feet that compilation staff originally coded as soft features due to unclear definition of hydro feature, but that have been determined to be hydro features by FDEM. Connectivity and monotonicity are not enforced on these features.	Capture linear hydro features as single breaklines. Average width shall be 8 feet or less to show as single line.
4	Soft Hydro Dual Line Feature	Linear hydro features with an average width greater than 8 feet that compilation staff originally coded as soft features due to unclear definition of hydro feature, but that have been determined to be hydro features by FDEM. Connectivity and monotonicity are not enforced on these features.	Capture features showing dual line (one on each side of the feature). Average width shall be greater than 8 feet to show as a double line. Data is not required to show "closed polygon".

Note: Carry through bridges for all linear hydrographic features.

Closed Water Body Features

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: WATERBODY
Contains Z Values: Yes
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Polygon
Annotation Subclass: None

Description

This polygon feature class will depict closed water body features and will have the associated water elevation available as an attribute.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
SHAPE_LENGTH	Double	Yes			0	0		Calculated by PDS
SHAPE_AREA	Double	Yes			0	0		Calculated by PDS
WATERBODY_ELEVATION_MS	Double	Yes			0	0		Assigned by PDS
TYPE	Long Integer	No	1	HydroP	0	0		Assigned by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Water Body	Land/Water boundaries of constant elevation water bodies such as lakes, reservoirs, ponds, etc. Features shall be defined as closed polygons and contain an elevation value that reflects the best estimate of the water elevation at the time of data capture. Water body features will be captured for features one-half acres in size or greater. "Donuts" will exist where there are islands within a closed water body feature.	Water bodies shall be captured as closed polygons with the water feature to the right. The compiler shall take care to ensure that the z-value remains consistent for all vertices placed on the water body. The field "WATERBODY_ELEVATION_MS" shall be automatically computed from the z-value of the vertices. An Island within a Closed Water Body Feature will also have a "donut polygon" compiled in addition to an Island polygon. These instructions are only for docks or piers that follow

			the coastline or water's edge, not for docks or piers that extend perpendicular from the land into the water. If it can be reasonably determined where the edge of water most probably falls, beneath the dock or pier, then the edge of water will be collected at the elevation of the water where it can be directly measured. If there is a clearly-indicated headwall or bulkhead adjacent to the dock or pier and it is evident that the waterline is most probably adjacent to the headwall or bulkhead, then the water line will follow the headwall or bulkhead at the elevation of the water where it can be directly measured. If there is no clear indication of the location of the water's edge beneath the dock or pier, then the edge of water will follow the outer edge of the dock or pier as it is adjacent to the water, at the measured elevation of the water.

Road Features

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: ROADBREAKLINE
Contains Z Values: Yes
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Polyline
Annotation Subclass: None

Description

This polyline feature class will depict apparent edge or road pavement as breaklines but will not include bridges or overpasses.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
SHAPE_LENGTH	Double	Yes			0	0		Calculated by PDS
TYPE	Long Integer	No	1	Road	0	0		Assigned by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Edge of Pavement	Capture edge of pavement (non-paved or compact surfaces as open to compiler interpretability) on both sides of the road. Runways are not to be included.	DO NOT INCLUDE Bridges or Overpasses within this feature type. Capture apparent edge of pavement (including paved shoulders). Each vertex placed should maintain vertical integrity and data is not required to show “closed polygon”. Box culverts should be continued as edge of pavement unless a clear guardrail system is in place; in that case, feature should be shown as bridge / overpass.

Bridge and Overpass Features

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: OVERPASS
Contains Z Values: Yes
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Polyline
Annotation Subclass: None

Description

This polyline feature class will depict bridges and overpasses as separate entities from the edge of pavement feature class.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
SHAPE_LENGTH	Double	Yes			0	0		Calculated by PDS
TYPE	Long Integer	No	1	Bridge	0	0		Assigned by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Bridge Overpass	Feature should show edge of bridge or overpass.	Capture apparent edge of pavement on bridges or overpasses. Do not capture guard rails or non-drivable surfaces such as sidewalks. Capture edge of drivable pavement only. Each vertex placed should maintain vertical integrity and data is not required to show “closed polygon”. Box culverts should be captured in this feature class if a clear guardrail system is in place; otherwise, show as edge-of-pavement.

Soft Features

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: SOFTFEATURE
Contains Z Values: Yes
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Polyline
Annotation Subclass: None

Description

This polyline feature class will depict soft changes in the terrain to support better hydrological modeling of the LiDAR data and sub-sequent contours.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
SHAPE_LENGTH	Double	Yes			0	0		Calculated by PDS
TYPE	Long Integer	No	1	Soft	0	0		Assigned by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Soft Breakline	Supplemental breaklines where LiDAR mass points are not sufficient to create a hydrologically correct DTM. Soft features shall include ridges, valleys, top of banks, etc. Soft features may also include natural Embankments that act as small ponding areas. Top of Banks can also be included in the soft breakline class so long as it does not define the edge of a water feature.	Capture breaklines to depict soft changes in the elevation. If the elevation changes are easily visible, go light on the breakline capture. Each vertex placed should maintain vertical integrity.

Island Features

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: ISLAND
Contains Z Values: Yes
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Polygon
Annotation Subclass: None

Description

This polygon feature class will depict natural and man-made islands as closed polygons.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
SHAPE_LENGTH	Double	Yes			0	0		Calculated by PDS
SHAPE_AREA	Double	Yes			0	0		Calculated by PDS
TYPE	Long Integer	No	1	Island	0	0		Assigned by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Island	Apparent boundary of natural or man-made island feature captured with a constant elevation. Island features will be captured for features one-half acres in size or greater.	Island shall take precedence over Coastal Shore Line Features. Islands shall be captured as closed polygons with the land feature to the right. The compiler shall take care to ensure that the z-value remains consistent for all vertices placed around the island. These instructions are only for docks or piers that follow the coastline or water's edge, not for docks or piers that extend perpendicular from the land into the water. If it can be reasonably determined where the edge of water most probably falls, beneath the dock or pier, then the edge of water will be collected at the elevation of the water where it can be directly measured. If there is a clearly-indicated

			headwall or bulkhead adjacent to the dock or pier and it is evident that the waterline is most probably adjacent to the headwall or bulkhead, then the water line will follow the headwall or bulkhead at the elevation of the water where it can be directly measured. If there is no clear indication of the location of the water's edge beneath the dock or pier, then the edge of water will follow the outer edge of the dock or pier as it is adjacent to the water, at the measured elevation of the water.

Low Confidence Areas

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: CONFIDENCE
Contains Z Values: No
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Polygon
Annotation Subclass: None

Description

This polygon feature class will depict areas where the ground is obscured by dense vegetation meaning that the resultant contours may not meet the required accuracy specifications.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
SHAPE_LENGTH	Double	Yes			0	0		Calculated by PDS
SHAPE_AREA	Double	Yes			0	0		Calculated by PDS
TYPE	Long Integer	No	1	Obscure	0	0		Assigned by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Low Confidence Area	Apparent boundary of vegetated areas that are considered obscured to the extent that adequate vertical data cannot be clearly determined to accurately define the DTM. These features are for reference only to indicate areas where the vertical data may not meet the data accuracy requirements due to heavy vegetation.	Capture as closed polygon with the obscured area to the right of the line. Compiler does not need to worry about z-values of vertices; feature class will be 2-D only.

Note: Area must be ½ acre or larger. Only outline areas where you are not sure about vegetative penetration of the LiDAR data. This is not the same as a traditional obscured area.

Masspoints

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: MASSPOINT
Contains Z Values: Yes
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Point
Annotation Subclass: None

Description

This feature class depicts masspoints as determined by the LiDAR ground points (LAS Class 2).

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
TYPE	Long Integer	No	1	Masspoint	0	0		Assigned by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Masspoint	Only the bare earth classification (Class 2) shall be loaded into the MASSPOINT feature class.	None. Data should be loaded from LAS Class 2 (Ground)

1 Foot Contours

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: CONTOUR_1FT
Contains Z Values: No
Z Resolution: N/A
Z Tolerance: N/A

Feature Type: Polyline
Annotation Subclass: None

Description

This polyline feature class will depict 1' contours modeled from the LiDAR ground points and the supplemental breaklines.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
SHAPE_LENGTH	Double	Yes			0	0		Calculated by PDS
CONTOUR_TYPE_DESC	Long Integer	No		dCONTOURTYPE	0	0	50	Assigned by PDS
CONTOUR_ELEVATION_MS	Double	No			0	0		Calculated by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Intermediate	A contour line drawn between index contours. Depending on the contour interval there are three or four intermediate contours between the index contours.	They are normally continuous throughout a map, but may be dropped or joined with an index contour where the slope is steep and where there is insufficient space to show all of the intermediate lines.
2	Supplementary	Supplementary contours are used to portray important relief features that would otherwise not be shown by the index and intermediate contours (basic contours). They are normally added only in areas of low relief, but they may also be used in rugged terrain to emphasize features. Supplementary contours are shown as screened lines so that they are distinguishable from the basic contours, yet not	These dotted lines are placed in areas where elevation change is minimal. If there is a lot of space between Index and Intermediate Contours (as happens where the land is relatively flat), these lines are added to indicate that there *are* elevation measurements, even if they are few and far between. If the horizontal distance between two adjacent contours is

		unduly prominent on the published map.	larger than 1” at map scale (100’), then add appropriate supplemental contours from the 1FT_CONTOUR feature class. Supplemental contours do not have to be continuous but should have a minimum length of 200’.
3	Depression	Depression contours are closed contours that surround a basin or sink. They are shown by right-angle ticks placed on the contour lines, pointed inward (down slope). Fill contours are a special type of depression contours, used to indicate an area that has been filled to support a road or railway grade.	Use when appropriate.
4	Index	Index Contours are to be placed at every 5th contour interval (1, 5, 10, etc…)	No special rules
5	Intermediate Low Confidence	Intermediate contours (Code 1) that are located in low confidence area should be cut to the low confidence boundary and should be reclassified to this code.	No special collection rules are necessary as this is a geo-processing task.
6	Supplementary Low Confidence	Supplementary contours (Code 2) that are located in low confidence area should be cut to the low confidence boundary and should be reclassified to this code.	No special collection rules are necessary as this is a geo-processing task.
7	Depression Low Confidence	Depression contours (Code 3) that are located in low confidence area should be cut to the low confidence boundary and should be reclassified to this code.	No special collection rules are necessary as this is a geo-processing task.
8	Index Low Confidence	Index contours (Code 4) that are located in low confidence area should be cut to the low confidence boundary and should be reclassified to this code.	No special collection rules are necessary as this is a geo-processing task.

2 Foot Contours

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: CONTOUR_2FT
Contains Z Values: No
Z Resolution: N/A
Z Tolerance: N/A

Feature Type: Polyline
Annotation Subclass: None

Description

This polyline feature class will depict 1' contours modeled from the LiDAR ground points and the supplemental breaklines.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
SHAPE_LENGTH	Double	Yes			0	0		Calculated by PDS
CONTOUR_TYPE_DESC	Long Integer	No		dCONTOURTYPE	0	0	50	Assigned by PDS
CONTOUR_ELEVATION_MS	Double	No			0	0		Calculated by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Intermediate	A contour line drawn between index contours. Depending on the contour interval there are three or four intermediate contours between the index contours.	They are normally continuous throughout a map, but may be dropped or joined with an index contour where the slope is steep and where there is insufficient space to show all of the intermediate lines.
2	Supplementary	Supplementary contours are used to portray important relief features that would otherwise not be shown by the index and intermediate contours (basic contours). They are normally added only in areas of low relief, but they may also be used in rugged terrain to emphasize features. Supplementary contours are	These dotted lines are placed in areas where elevation change is minimal. If there is a lot of space between Index and Intermediate Contours (as happens where the land is relatively flat), these lines are added to indicate that there *are* elevation measurements, even if they are few and far between.

		shown as screened lines so that they are distinguishable from the basic contours, yet not unduly prominent on the published map.	If the horizontal distance between two adjacent contours is larger than 1” at map scale (100’), then add appropriate supplemental contours from the 1FT_CONTOUR feature class. Supplemental contours do not have to be continuous but should have a minimum length of 200’.
3	Depression	Depression contours are closed contours that surround a basin or sink. They are shown by right-angle ticks placed on the contour lines, pointed inward (down slope). Fill contours are a special type of depression contours, used to indicate an area that has been filled to support a road or railway grade.	Use when appropriate.
4	Index	Index Contours are to be placed at every 5th contour interval (1, 5, 10, etc…)	No special rules
5	Intermediate Low Confidence	Intermediate contours (Code 1) that are located in low confidence area should be cut to the low confidence boundary and should be reclassified to this code.	No special collection rules are necessary as this is a geo-processing task.
6	Supplementary Low Confidence	Supplementary contours (Code 2) that are located in low confidence area should be cut to the low confidence boundary and should be reclassified to this code.	No special collection rules are necessary as this is a geo-processing task.
7	Depression Low Confidence	Depression contours (Code 3) that are located in low confidence area should be cut to the low confidence boundary and should be reclassified to this code.	No special collection rules are necessary as this is a geo-processing task.
8	Index Low Confidence	Index contours (Code 4) that are located in low confidence area should be cut to the low confidence boundary and should be reclassified to this code.	No special collection rules are necessary as this is a geo-processing task.

Ground Control

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: GROUNDCONTROL
Contains Z Values: Yes
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Point
Annotation Subclass: None

Description

This feature class depicts the points used in the acquisition and calibration of the LiDAR and aerial photography collected by Aero-Metric, Sanborn and Terrapoint.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
TYPE	Long Integer	No	1	Control	0	0		Assigned by PDS
POINTID	String	Yes					12	Assigned by PDS
X_COORD	Double	Yes			0	0		Assigned by PDS
Y_COORD	Double	Yes			0	0		Assigned by PDS
Z_COORD	Double	Yes			0	0		Assigned by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Control Point	Primary or Secondary PDS control points used for either base station operations or in the calibration and adjustment of the control.	None.

Vertical Accuracy Test Points

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: VERTACCTESTPTS
Contains Z Values: Yes
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Point
Annotation Subclass: None

Description

This feature class depicts the points used by PDS to test the vertical accuracy of the data produced.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
POINTID	String	Yes					12	Assigned by PDS
X_COORD	Double	Yes			0	0		Assigned by PDS
Y_COORD	Double	Yes			0	0		Assigned by PDS
Z_COORD	Double	Yes			0	0		Assigned by PDS
LANDCOVER	Long Integer	No	1	dLANDCOVERTYPE	0	0		Assigned by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Bare-Earth and Low Grass	None.	None.
2	Brush Lands and Low Trees	None.	None.
3	Forested Areas Fully Covered by Trees	None.	None.
4	Urban Areas	None.	None.

Footprint (Tile Boundaries)

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: FOOTPRINT
Contains Z Values: No
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Polygon
Annotation Subclass: None

Description

This polygon feature class includes the Florida 5,000’ x 5,000’ tiles for each countywide geodatabase produced.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
SHAPE_LENGTH	Double	Yes			0	0		Calculated by PDS
SHAPE_AREA	Double	Yes			0	0		Calculated by PDS
CELLNUM	String	No			0	0	8	Assigned by PDS

Contact Information

Any questions regarding this document should be addressed to:

Brian Mayfield, C.P., GISP, G.L.S.
Associate / Sr. Project Manager
Dewberry
8401 Arlington Blvd.
Fairfax, VA 22031
(703) 849-0254 – voice
(703) 340-4141 – cell
bmayfield@dewberry.com

Dewberry
LiDAR Campaign
Final Report
For
FDEM – Taylor County
March 2008

Prepared by:
Sanborn
1935 Jamboree Dr., Suite 100
Colorado Springs, CO, 80920
Phone: (719) 593-0093
Fax: (719) 528-5093

EXECUTIVE SUMMARY

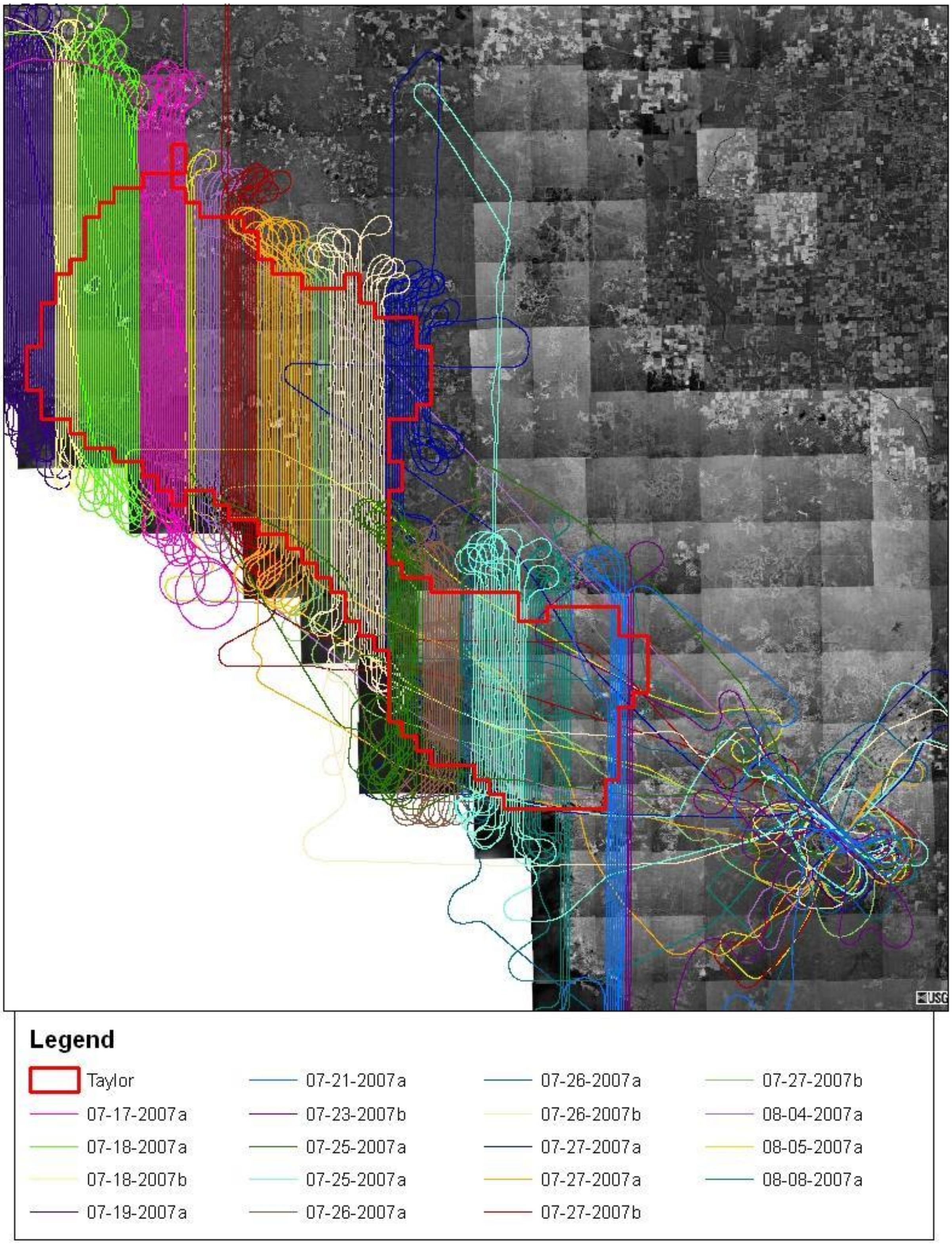
In the spring of 2007, Sanborn was contracted by Dewberry to execute a LiDAR (Light Detection and Ranging) survey campaign in the state of Florida. LiDAR data in the form of 3-dimensional positions of a dense set of mass points was collected for the 608 square miles of Taylor County. This data was used in the development of the bare-earth-classified elevation point data sets.

The flight line tracks for the LiDAR data acquisition are shown below, to include the flights used for runway calibrations (bore-sighting) at the airfield.

The Leica ALS-50 LiDAR system and the Optech ALTM 2050 LiDAR system was used to collect data for the survey campaign. The LiDAR system is calibrated by conducting flight passes over a known ground surface before and after each LiDAR mission. During final data processing, the calibration parameters are inserted into post-processing software.

The acquired LiDAR data was processed to obtain first and last return point data. The last return data was further filtered to yield a LiDAR surface representing the bare earth.

The contents of this report summarize the methods used to establish the base station coordinate check, perform the LiDAR data collection and post-processing as well as the results of these methods.



Legend
Taylor
07-17-2007a
07-18-2007a
07-18-2007b
07-19-2007a
07-21-2007a
07-23-2007b
07-25-2007a
07-25-2007a
07-26-2007a
07-26-2007a
07-26-2007b
07-27-2007a
07-27-2007a
07-27-2007b
07-27-2007b
08-04-2007a
08-05-2007a
08-08-2007a

INTRODUCTION

This report contains the technical write-up of the Dewberry LiDAR campaign, including system calibration techniques, the establishment of base stations by a differential GPS network survey, and the collection and post-processing of the LiDAR data.

1.1 Contact Information

Questions regarding the technical aspects of this report should be addressed to:

Sanborn
1935 Jamboree Drive, Suite 100
Colorado Springs, CO 80920

Attention: -------- Andy Lucero (Project Manager)
------- James Young (LiDAR General Manager)
Telephone: ------- 1–719-264-5602
FAX: ------------- 1–719-264-5637
email:-------------- jyoung@sanborn.com

1.2 Purpose of the LiDAR Acquisition

This LiDAR operation was designed to provide a highly detailed ground surface dataset to be used for the development of topographic, contour mapping and hydraulic modeling

1.3 Project Location

Taylor County, Florida

1.4 Project Scope, Specifications and Time Line

The summer of 2007 LiDAR Flight Acquisition required the collection of 608 square miles of Taylor County collected at a nominal point spacing of 0.7 meters and based on the Sanborn FEMA compliant LiDAR product specification.

Table 1: Project Specifications and Deliverable Coordinate and Datum Systems

Area (sq. mi)	608	**Product type**	Fema(F)	**Projection**	Florida State Plane
Vertical RMSE (CM)	Bare Earth 9.25cm	**Check Points required**	Yes	**Horizontal Datum Vertical Datum**	NAD83/Harn NAVD88
Horizontal RMSE (CM)	50cm	**Number Collected**	60	**Units**	US Survey Ft

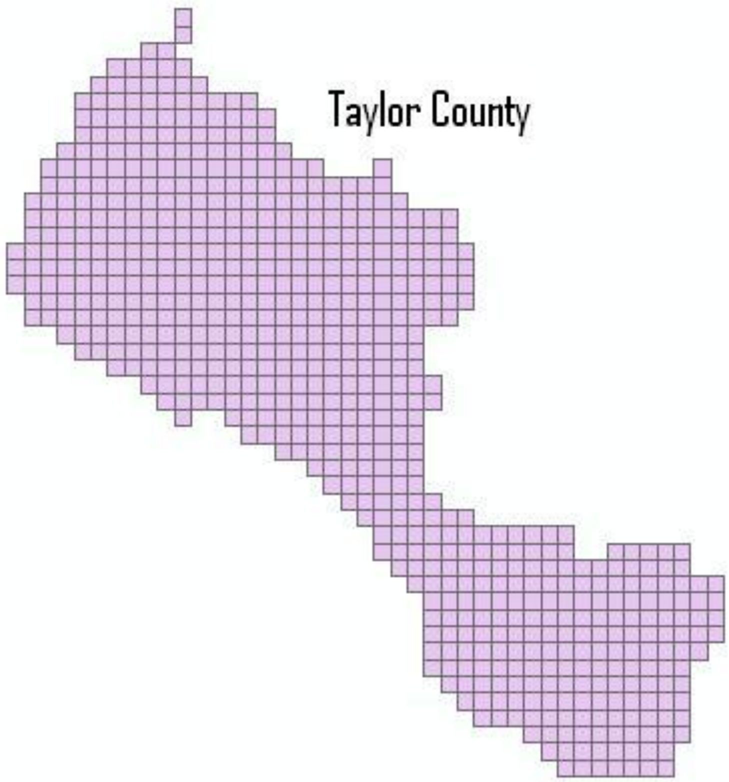


Figure 1: Area of Collection

2.1 Introduction

LiDAR calibrations are performed to determine and therefore eliminate systematic biases that occur within the hardware of the Leica ALS-50 system and the Optech ALTM 2050 system. Once the biases are determined they can be modeled out. The systematic biases are corrected for include scale, roll, and pitch.

The following procedures are intended to prevent operational errors in the field and office work, and are designed to detect inconsistencies. The emphasis is not only on the quality control (QC) aspects, but also on the documentation, i.e., on the quality assurance (QA).

2.2 Calibration Procedures

Sanborn performs two types of calibrations on its LiDAR system. The first is a building calibration, and it is done any time the LiDAR system has been moved from one plane to another. New calibration parameters are computed and compared with previous calibration runs. If there is any change, the new values are updated internally or during the LiDAR post-processing. These values are applied to all data collected with the plane/ALS-50/ALTM 2050 system configurations.

Once final processing calibration parameters are established from the building data, a precisely-surveyed surface is observed with the LiDAR system to check for stability in the system. This is done several times during each mission. An average of the systematic biases are applied on a per mission basis.

2.3 Building Calibration

Whenever the ALS-50 or ALTM 2050 is moved to a new aircraft, a building calibration is performed. The rooftop of a large, flat, rectangular building is surveyed on the ground using conventional survey methods, and used as the LiDAR calibration target. The aircraft flies several specified passes over the building with the ALS-50 system and the ALTM 2050 system set first in scan mode, then in profile mode, and finally in both scan and profile modes with the scan angle set to zero degrees.

Figure 2 shows a pass over the center of the building. The purpose of this pass is to identify a systematic bias in the scale of the system.

Figure 3 demonstrates a pass along a distinct edge of the building to verify the roll compensation performed by the Inertial Navigation System, INS.

Additionally, a pass is made in profile mode across the middle of the building to compensate for any bias in pitch.

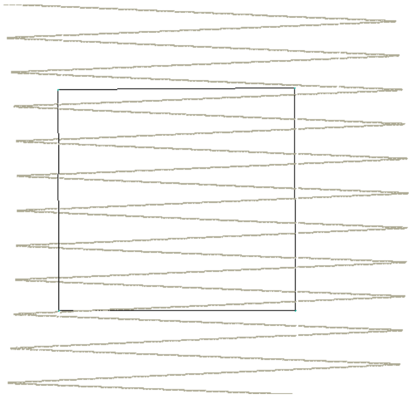


Figure 2: Calibration Pass 1

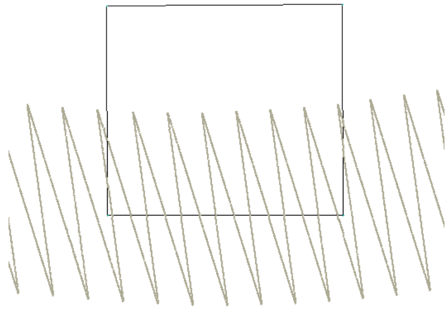


Figure 3: Calibration Pass 2

2.4 Runway Calibration, System Performance Validation

An active asphalt runway was precisely-surveyed at the Cross City Airport for Taylor County using kinematic GPS survey techniques (accuracy: ±3cm at 1σ, along each coordinate axis) to establish an accurate digital terrain model of the runway surface. The LiDAR system is flown at right angles over the runway several times and residuals are generated from the processed data. Figure 4 shows a typical pass over the runway surface.

Approximately 25,000 LiDAR points are observed with each pass. A Triangulated Irregular Network (TIN) surface is created from these passes. The ground control x,y,z points are then compared with the z of the LiDAR surface to compute vertical residuals of the LiDAR data. After careful analysis of noise associated with non-runway returns, any system bias is documented and removed from the process.

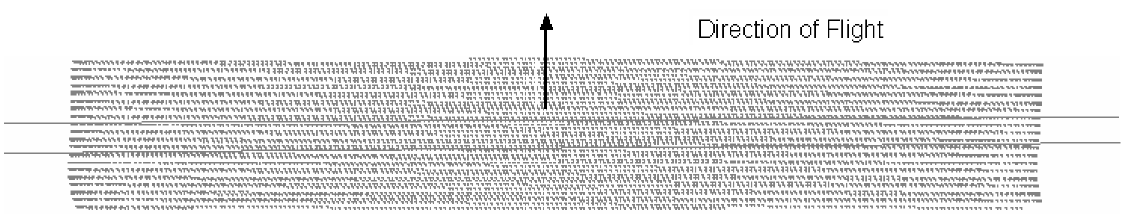


Figure 4: Runway Calibration

3 RUNWAY CALIBRATION, SYSTEM PERFORMANCE VALIDATION

3.1 Calibration Results

“Bore-sighting” and “runway calibration” are essentially the same thing, i.e., they determine if the LiDAR sensor has maintained its factory calibration and is still sensing the correct position on the ground, both vertically and horizontally. The LiDAR data captured over the building is used to determine whether there have been any changes to the alignment of the Inertial Measurement Unit, IMU, with respect to the laser system. The parameters are designed to eliminate systematic biases within certain system parameters.

The runway over-flights are intended to be a quality check on the calibration and to identify any system irregularities and the overall noise. IMU misalignments and internal system calibration parameters are verified by comparing the collected LiDAR points with the runway surface.

Figure 5 shows the typical results of a runway over-flight analysis. The X-axis represents the position along the runway. The overall statistics from this analysis provides evidence of the overall random noise in the data (typically, 7 cm standard deviation – an unbiased estimator, and 8 cm RMS which includes any biases) and indicates that the system is performing within specifications. As described in later sections of this report, this analysis will identify any peculiarities within the data along with mirror-angle scale errors (identified as a “smile” or “frown” in the data band) or roll biases.

> The calibration is done based on a kinematic survey on the runway. Given that the Kinematic survey RMSE is no better than 4 centimeters as a result of none exact height of the antenna and weight of the aircraft. Sanborn was required to do additional check points in the project area to meet the 9.25 centimeter vertical accuracy requirement knowing that the calibration site is only good to 4 centimeters RMSE. A z bump adjustment was made to the entire data set based on the survey points in the project area and the relative accuracy of the data to itself and in all areas.

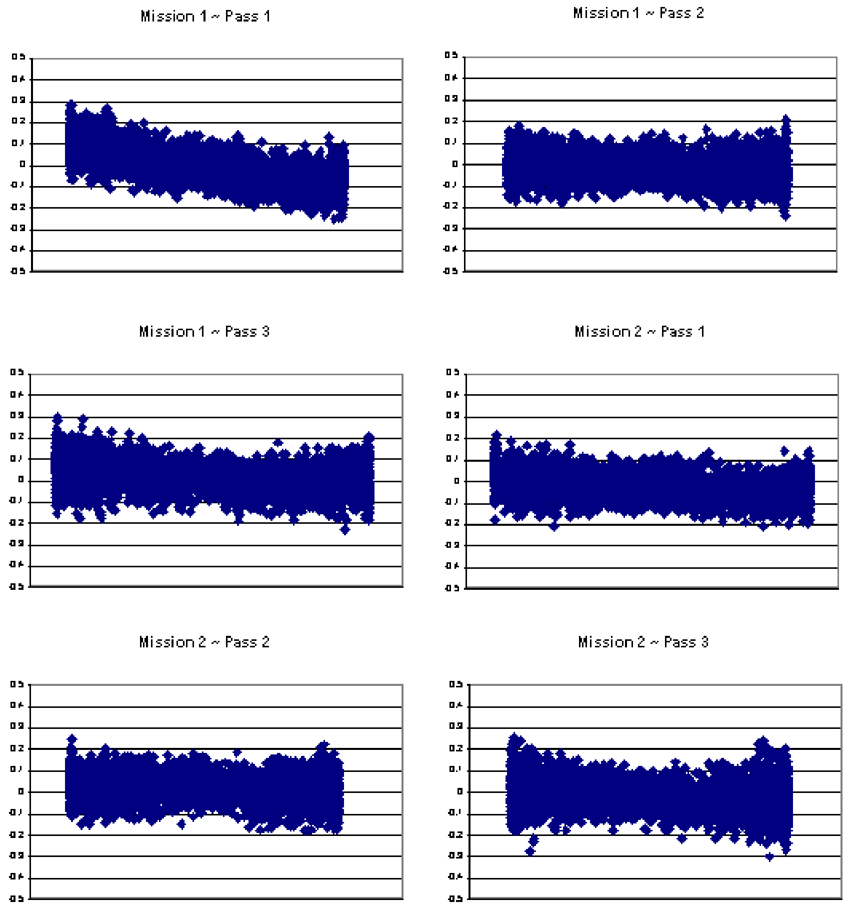


Figure 5: Runway Calibration Results

3.2 Daily Runway Performance/Data Validation Tests

Performance flights over the runway test field were performed before and after each mission. Table 2 shows the standard deviation and RMS values of the residuals between the test flights and the known surface of the test ranges for each pass. The maximum RMS value is 0.098 meters and the maximum standard deviation is 0.097 meters. The average RMS among all test flights is 0.055 meters.

Table 2: Runway Validation Results for Taylor County (Meters)

Mission	Passes	Standard Deviation	RMS
178a_Leica_40	4	0.034	0.038
199a_Leica_40	4	0.058	0.058
202a_Optech	4	0.069	0.077
204a_A1	4	0.058	0.058
206a_Optech	4	0.076	0.077
206a_Leica_40	4	0.040	0.053
207a_Leica_40	4	0.041	0.079
207a_Optech	4	0.091	0.091
207a_A1	4	0.044	0.044
207b_Leica_40	4	0.070	0.078
208a_Leica_40	4	0.038	0.044
208a_Optech	4	0.086	0.092
208a_Leica_49	4	0.065	0.078
208a_A1	4	0.055	0.055
208b_Leica_40	4	0.055	0.055
216a_Leica_40	4	0.062	0.088
217a_Leica_40	4	0.097	0.098
220a_Leica_40	4	0.063	0.065

3.3 Horizontal Validation

The horizontal accuracy was checked within the calibration site and the project area. Five random tiles within each county were selected and five calibrations within each county were selected for the different missions. The horizontal accuracy was checked at both center and edge of the flight line swath in the calibration lines. In the project area the horizontal accuracy was check in the over lapping areas of these tiles. Locations for each check was randomly selected based on like features in a single flightline overlap or corresponding calibration lines. For example building corner locations were identified and differences where measured in reference to each other. Given that the calibration lines were flown in opposing directions and an additional line was flown perpendicular to these opposing lines, this would indicate a valid horizontal position to the absolute location of the position. If there was an error greater than stated in the specifications, the location directional miss-alignment would be greater than the specified RMSE in either northing or easting. The difference was check and the RMSE of all differences were computed and reported in Tables 3 & 4 below. Based on the results of Table 3 & 4 it has been determined that the horizontal accuracy has been met.

Table 3: Horizontal Validation Results for Taylor County (Centimeters)

Taylor County			
Tile	**Northing Offset (cm)**	**Easting Offset (cm)**	**Center/Edge**
60762	21.22	21.05	C
60223	48.9	39.96	E
55344	26.66	18.62	C
58581	47	43.6	E
62902	28.16	42.49	C
RMSE	**34.388**	**33.144**	
Calibration Mission	**Northing Offset (cm)**	**Easting Offset (cm)**	**Center/Edge**
Day178a	12.23	24.84	E
Day208a	32.46	31.12	E
Day199a	28.23	19.99	E
Day220a	43.79	38.28	E
Day207b	39.47	47.45	E
RMSE	**31.236**	**32.336**	

Table 4: Combined Horizontal Validation Results for Taylor County (Centimeters)

Tile/Mission	Northing (cm)	Easting (cm)	Center/Edge
60762	21.22	21.05	C
60223	48.9	39.96	E
55344	26.66	18.62	C
58581	47	43.6	E
62902	28.16	42.49	C
Day178a	12.23	24.84	E
Day208a	32.46	31.12	E
Day199a	28.23	19.99	E
Day220a	43.79	38.28	E
Day207b	39.47	47.45	E
RMSE	**32.812**	**32.74**	

4 LiDAR FLIGHT AND SYSTEM REPORT

4.1 Introduction

This section addresses LiDAR system, flight reporting and data acquisition methodology used during the collection of the Taylor County campaign. Although Sanborn conducts all LiDAR with the same rigorous and strict procedures and processes, all LiDAR collections are unique.

4.2 Field Work Procedures

A minimum of two GPS base stations were set up, with one receiver located at the airport set up on AR1838, and the secondary GPS receiver placed at survey control point BD2495, which is within the project area or within the required baseline specifications of the project.

Pre-flight checks such as cleaning the sensor head glass are performed. A four minute INS initialization is conducted on the ground, with the engines running, prior to flight, to establish fine-alignment of the INS. GPS ambiguities are resolved by flying within ten kilometers of the base stations.

The flight missions were typically four or five hours in duration including runway calibration flights flown at the beginning and the end of each mission. During the data collection, the operator recorded information on log sheets which includes weather conditions, LiDAR operation parameters, and flight line statistics. Near the end of the mission GPS ambiguities are again resolved by flying within ten kilometers of the base stations, to aid in post-processing.

Table 5 and 6 shows the planned LiDAR acquisition parameters with a flying height of 800 meters above ground level (AGL) for both Leica and Optech on a mission to mission basis.

Table 5: LiDAR Leica Acquisition Parameters

Average Altitude	800 Meters AGL
Airspeed	~120 Knots
Scan Frequency	36 Hertz
Scan Width Half Angle	20 Degrees
Pulse Rate	50,000 Hertz

Table 6: LiDAR Optech Acquisition Parameters

Average Altitude	800 Meters AGL
Airspeed	~120 Knots
Scan Frequency	40 Hertz
Scan Width Half Angle	16 Degrees
Pulse Rate	50,000 Hertz

Preliminary data processing was performed in the field immediately following the missions for quality control of GPS data and to ensure sufficient overlap between flight lines. Any problematic data could then be re-flown immediately as required. Final data processing was completed in the Colorado Springs office.

Table 7: Collection Dates, Times, Average Per Flight Collection Parameters and PDOP

Mission	Date	Sensor	Start Time	End Time	Altitude (m)	Airspeed (Knots)	Scan Angle	Scan Rate	Pulse Rate	PDOP
178a	Jun 27	Leica	00:47	5:37	800	120	40˚	36	50000	1.1
199a	Jul 18	Leica	7:15	12:53	800	120	40˚	36	50000	1.3
202a	Jul 21	Optech	18:19	21:21	800	120	32˚	40	50000	1.9
204a	Jul 23	Optech	16:52	19:33	800	120	32˚	40	50000	1.2
206a	Jul 25	Leica	18:47	23:20	800	120	40˚	36	50000	1.5
206a	Jul 25	Optech	19:59	00:05	800	120	32˚	40	50000	1.7
207a	Jul 26	Leica	1:03	3:30	800	120	40˚	36	50000	1.4
207a	Jul 26	Optech	22:29	02:08	800	120	32˚	40	50000	1.8
207a	Jul 26	Optech	22:49	02:27	800	120	32˚	40	50000	1.5
207b	Jul 26	Leica	23:30	5:09	800	120	40˚	36	50000	1.1
208a	Jul 27	Leica	1:14	6:18	800	120	40˚	36	50000	1.6
208a	Jul 27	Leica	7:11	10:52	800	120	40˚	36	50000	1.2
208a	Jul 27	Optech	15:59	16:42	800	120	32˚	40	50000	1.5
208a	Jul 27	Optech	21.11	01:01	800	120	32˚	40	50000	1.8
208b	Jul 27	Leica	23:03	3:29	800	120	40˚	36	50000	1.0
216a	Aug 4	Leica	20:56	23:46	800	120	40˚	36	50000	1.3
217a	Aug 5	Leica	00:55	2:47	800	120	40˚	36	50000	1.4
220a	Aug 8	Leica	2:08	6:10	800	120	40˚	36	50000	1.7

4.3 Final LiDAR Processing

Final post-processing of LiDAR data involves several steps. The airborne GPS data was post-processed using Waypoint's GravNAV™ software (version 7.5). A fixed-bias carrier phase solution was computed in both the forward and reverse chronological directions. The data was processed for both base stations and combined. In the event that the solution worsened as a result of the combination of both solutions the best of both solutions was used to yield more accurate data. LiDAR acquisition was limited to periods when the PDOP was less than 3.2.

The GPS trajectory was combined with the raw IMU data and post-processed using Applanix Inc.'s POSPROC (version 4.3) Kalman Filtering software. This results in a two-fold improvement in the attitude accuracies over the real-time INS data. The best estimated trajectory (BET) and refined attitude data are then re-introduced into the LEICA ALS post processor for the Leica system and the REALM Survey Suite OPTECH for the Optech system to compute the laser point-positions. The trajectory is then combined with the attitude data and laser range measurements to produce the 3-dimensional coordinates of the mass points.

All return values are produced within ALS Post processing software for the Leica system and within REALM Survey Suite OPTECH software for the Optech system. The multi-return information is processed to obtain the "Bare Earth Dataset" as a deliverable. All LiDAR data is processed using the binary LAS format 1.1 file format.

LiDAR filtering was accomplished using TerraSolid, TerraScan LiDAR processing and modeling software. The filtering process reclassifies all the data into classes with in the LAS formatted file based scheme set using the LAS format 1.1 specifications or by the client. For FDEM the classification specifications are ground, default, noise, water and overlap. (Classes: 1, 2, 7, 9 and 12) Once the data is classified, the entire data set is reviewed and manually edited for anomalies that are outside the required guidelines of the product specification or contract guidelines, whichever apply. Table 8 indicates the required product specifications.

The coordinate and datum transformations are then applied to the data set to reflect the required deliverable projection, coordinate and datum systems as provided in the contract.

The client required deliverables are then generated. At this time, a final QC process is undertaken to validate all deliverables for the project. Prior to release of data for delivery, Sanborn's Quality control/ quality assurance department reviews the data and then releases it for delivery.

Table 8: Processing Accuracies and Requirements

Accuracy of LiDAR Data (H)	50 cm RMSE
Accuracy of LiDAR data in bare areas	9.25 cm RMSE
Accuracy of LiDAR data in vegetated areas	18.5 cm RMSE
Percent of artifacts removed (terrain and vegetation dependent)	95%
Percent of all outliers removed	95%
Percent of all vegetation removed	95%
Percent of all buildings removed	98%

5 GEODETIC BASE NETWORK

5.1 Network Scope

During the LiDAR campaign, the geodetic control survey and final coordinates were provided to Sanborn by the PDS team. For Taylor County the Sanborn crew set up on NGS points BD2495 and AR1838. These two points were tied into the fully constrained network that was provided.

5.2 Final LiDAR Verification

The LiDAR data was evaluated using a collection of 60 GPS surveyed checkpoints. 20 points were collected in each bare earth, low grass, and urban vegetation classes, see Figure 6 for diagram. For Taylor County the standard deviation is 0.306 feet and the root mean squared is 0.301 feet. The LiDAR data was compared to each of these classes yielding much better result than was required for the project. Table 9 indicates the results for Taylor County and each point including the overall results as it compares to the LiDAR data set.

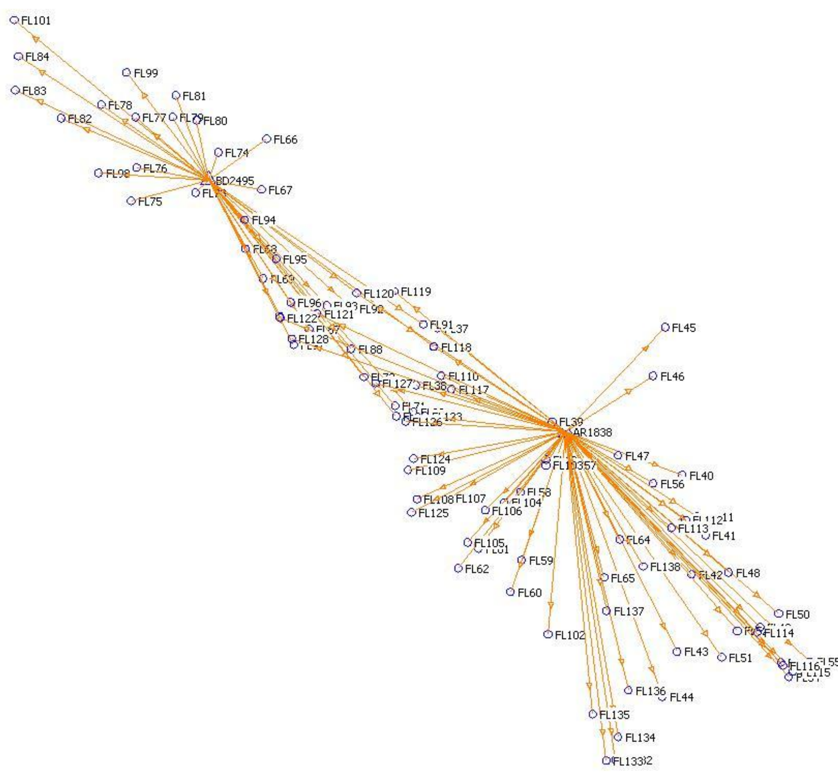


Figure 6: FDEM Survey Checkpoint Diagram

Table 9: FDEM Taylor County Checkpoint Results (US Survey Feet)

Number	Easting	Northing	Known Z	Laser Z	Dz
66	2210132.825	373358.858	9.974	10.520	+0.546
79	2301661.176	268690.600	26.739	27.270	+0.531
76	2246688.717	324776.707	11.188	11.680	+0.492
128	2261910.813	290851.352	5.709	6.090	+0.381
67	2223218.770	395858.051	26.181	26.530	+0.349
101	2262905.730	287601.303	3.707	4.020	+0.313
127	2307957.037	265042.874	26.739	27.040	+0.301
72	2217383.739	380568.205	61.548	61.820	+0.272
100	2261803.554	311338.794	28.478	28.750	+0.272
88	2271693.938	295959.094	25.000	25.190	+0.190
73	2250335.225	402644.728	36.647	36.820	+0.173
121	2276237.509	304840.627	29.199	29.330	+0.131
122	2255683.997	302868.046	6.693	6.820	+0.127
91	2328779.478	248902.174	16.831	16.900	+0.069
74	2246775.033	374615.097	34.121	34.160	+0.039
81	2211540.010	413737.703	31.463	31.500	+0.037
77	2255480.386	303613.443	6.759	6.760	+0.001
99	2254156.967	335698.226	43.241	43.240	-0.001
78	2318643.548	252325.648	17.487	17.430	-0.057
120	2298625.507	315561.790	34.153	34.030	-0.123
75	2237204.939	341558.839	22.703	22.520	-0.183
87	2298634.106	315551.672	34.186	33.970	-0.216
82	2200229.804	427958.579	34.449	34.200	-0.249
7	2330568.407	263750.578	19.783	19.530	-0.253
90	2319188.435	246643.115	6.955	6.700	-0.255
94	2281828.762	308988.433	30.676	30.410	-0.266
80	2198228.212	416054.411	30.381	30.070	-0.311
93	2296175.172	307023.323	32.316	32.000	-0.316
89	2294841.518	284433.649	30.774	30.440	-0.334
83	2136014.656	416754.568	8.366	7.990	-0.376
96	2173110.853	441417.752	32.546	32.040	-0.506
68	2173996.712	369745.912	5.906	5.350	-0.556

Average dz	+0.007
Minimum dz	-0.556
Maximum dz	+0.546
Average magnitude	0.257
Root mean square	0.301
Std deviation	0.306

6 GROUND CONTROL REPORT

6.1 Introduction

This section addresses Ground Control reporting in the Ellipsoid model used as part of the collection and the Geoid model used to compute orthometric heights.

6.2 Horizontal Datum

The horizontal datum associated with the LiDAR data is NAD83 (1993)/HARN, as realized by the physical NGS control monuments used to constrain the survey control network.

6.3 Vertical Datum

The vertical datum associated with the LiDAR data is the NAVD88, as realized by the physical NGS benchmarks used to constrain the survey control network.

Appendix E: QA/QC Checkpoints and Accuracy Spreadsheets

Point Number	Land Cover Class		SPCS NAD83/99 North Zone		NAVD88	LIDAR-Z	ΔZ
			Easting-X (Ft)	Northing-Y (Ft)	Survey-Z (Ft)		
TA002M3	1	BE & Low Grass	2,136,516.46	417,778.85	5.30	4.90	-0.40
TA002M8	1	BE & Low Grass	2,136,398.08	417,656.54	6.09	5.68	-0.41
* TA003M4	1	BE & Low Grass	2,149,840.48	430,378.57	12.77	12.14	-0.63
** TA003M8	1	BE & Low Grass	2,149,705.20	430,401.00	14.10	13.44	-0.66
**TA004M1	1	BE & Low Grass	2,165,336.37	442,276.85	29.43	28.46	-0.97
*TA004M2	1	BE & Low Grass	2,165,322.77	442,322.25	29.07	28.20	-0.87
*TA005M1	1	BE & Low Grass	2,186,616.83	454,266.01	37.49	36.85	-0.64
**TA005M6	1	BE & Low Grass	2,186,806.26	454,242.29	38.74	38.10	-0.64
*TA007M9	1	BE & Low Grass	2,157,964.39	416,673.54	12.10	11.45	-0.65
*TA008M1	1	BE & Low Grass	2,178,805.12	428,619.56	26.45	25.93	-0.52
TA008M2	1	BE & Low Grass	2,178,820.16	428,577.07	26.28	25.84	-0.44
**TA009M6	1	BE & Low Grass	2,191,782.52	420,437.93	29.27	28.71	-0.56
TA009M7	1	BE & Low Grass	2,191,795.60	420,471.78	25.50	25.07	-0.43
TA010M4	1	BE & Low Grass	2,206,903.53	411,033.63	30.60	30.07	-0.53
TA010M6	1	BE & Low Grass	2,206,792.41	410,942.70	30.25	29.90	-0.35
TA011M8	1	BE & Low Grass	2,223,438.96	400,689.39	25.12	25.16	0.04
TA012M3	1	BE & Low Grass	2,233,487.11	395,345.42	26.24	26.29	0.05
**TA013M5	1	BE & Low Grass	2,175,206.43	373,079.96	6.09	5.54	-0.55
TA014M3	1	BE & Low Grass	2,201,924.87	369,831.84	6.40	N/A	-0.45
TA015M1	1	BE & Low Grass	2,218,856.51	380,503.72	31.22	30.99	-0.23
TA016M7	1	BE & Low Grass	2,252,863.08	381,215.81	34.44	34.43	-0.01
TA017M4	1	BE & Low Grass	2,261,761.60	387,643.36	41.54	41.26	-0.28
TA017M7	1	BE & Low Grass	2,261,728.09	387,674.77	41.27	41.05	-0.22
TA018M2	1	BE & Low Grass	2,266,354.95	402,054.74	47.78	47.70	-0.08
TA019M6	1	BE & Low Grass	2,258,065.53	413,156.08	41.41	41.03	-0.38
TA020M1	1	BE & Low Grass	2,237,457.72	416,927.63	37.20	36.92	-0.28
TA020M4	1	BE & Low Grass	2,237,470.02	417,005.38	35.20	35.43	0.23
TA021M8	1	BE & Low Grass	2,247,867.34	401,630.27	32.81	33.02	0.21
TA022M5	1	BE & Low Grass	2,240,895.86	362,953.82	31.02	31.39	0.37
TA023M2	1	BE & Low Grass	2,262,672.61	320,172.91	31.52	31.73	0.21
TA023M3	1	BE & Low Grass	2,262,654.58	320,237.68	30.76	31.22	0.46
TA024M7	1	BE & Low Grass	2,183,019.81	416,273.55	20.74	20.38	-0.36
TA025M1	1	BE & Low Grass	2,245,412.45	322,956.22	7.39	7.04	-0.35
TA026M4	1	BE & Low Grass	2,248,570.43	310,448.01	4.25	4.25	0.00
TA027M6	1	BE & Low Grass	2,255,468.42	304,430.83	5.49	5.66	0.17
TA028M6	1	BE & Low Grass	2,262,086.01	290,308.84	3.28	3.55	0.27
TA029M1	1	BE & Low Grass	2,276,071.34	304,785.43	30.70	30.73	0.03
TA029M6	1	BE & Low Grass	2,276,255.08	304,887.25	28.97	29.07	0.10
TA030M1	1	BE & Low Grass	2,287,148.13	311,191.23	32.16	32.10	-0.06
TA030M7	1	BE & Low Grass	2,287,065.87	311,214.43	31.63	31.61	-0.02
TA031M2	1	BE & Low Grass	2,298,599.54	315,583.67	34.77	34.49	-0.28
TA031M7	1	BE & Low Grass	2,298,675.77	315,667.11	34.28	34.18	-0.10
TA032M1	1	BE & Low Grass	2,294,804.71	284,448.33	30.93	30.52	-0.41
*TA033M2	1	BE & Low Grass	2,304,862.92	284,579.02	29.67	29.00	-0.68
TA034M7	1	BE & Low Grass	2,311,643.41	260,448.73	24.75	24.69	-0.06
TA037M6	1	BE & Low Grass	2,332,675.18	275,052.25	22.43	22.47	0.04
TA038M4	1	BE & Low Grass	2,341,170.93	285,021.61	23.26	23.68	0.41
TA039M6	1	BE & Low Grass	2,327,251.87	284,902.16	25.22	24.86	-0.36
TA040M4	1	BE & Low Grass	2,322,290.69	312,756.72	34.53	34.05	-0.48
TA002M6	2	Brush & Low Trees	2,136,471.33	417,674.10	6.11	5.78	-0.33
TA003M3	2	Brush & Low Trees	2,149,856.35	430,326.36	14.04	13.33	-0.71
TA004M3	2	Brush & Low Trees	2,165,313.13	442,348.50	29.53	28.99	-0.54
TA005M3	2	Brush & Low Trees	2,186,677.86	454,219.92	37.71	37.25	-0.46
TA005M7	2	Brush & Low Trees	2,186,832.68	454,214.56	37.70	37.43	-0.27

TA006M4	2	Brush & Low Trees	2,156,984.36	387,468.06	5.40	4.75	-0.66
TA006M7	2	Brush & Low Trees	2,157,000.17	387,577.65	5.59	4.75	-0.84
TA007M7	2	Brush & Low Trees	2,157,963.51	416,619.59	12.82	12.18	-0.64
TA008M8	2	Brush & Low Trees	2,178,917.54	428,485.12	25.43	25.17	-0.27
TA009M4	2	Brush & Low Trees	2,191,646.41	420,486.86	28.19	28.25	0.05
TA009M5	2	Brush & Low Trees	2,191,752.54	420,420.57	27.85	28.29	0.43
TA011M1	2	Brush & Low Trees	2,223,539.23	400,527.44	27.25	27.52	0.27
TA012M5	2	Brush & Low Trees	2,233,659.49	395,359.70	27.11	27.16	0.05
TA013M2	2	Brush & Low Trees	2,175,191.69	372,846.49	5.14	4.70	-0.44
TA013M4	2	Brush & Low Trees	2,175,205.25	373,022.01	6.07	5.53	-0.54
TA014M7	2	Brush & Low Trees	2,201,942.08	369,640.00	5.01	5.15	0.14
TA015M7	2	Brush & Low Trees	2,219,013.65	380,683.09	27.90	27.74	-0.16
TA016M4	2	Brush & Low Trees	2,252,905.95	381,256.36	34.75	34.53	-0.22
TA018M4	2	Brush & Low Trees	2,266,414.76	402,191.72	45.14	45.37	0.23
TA019M7	2	Brush & Low Trees	2,258,077.10	413,195.54	41.31	40.96	-0.35
TA020M3	2	Brush & Low Trees	2,237,550.89	416,949.41	37.73	37.39	-0.34
TA021M3	2	Brush & Low Trees	2,247,693.25	401,682.24	33.10	33.47	0.37
TA022M7	2	Brush & Low Trees	2,240,980.92	363,034.78	31.46	32.39	0.93
TA023M7	2	Brush & Low Trees	2,262,625.99	320,421.61	29.05	29.28	0.23
TA024M5	2	Brush & Low Trees	2,183,065.59	416,282.55	21.83	21.46	-0.37
TA025M3	2	Brush & Low Trees	2,245,484.09	323,015.90	4.91	4.72	-0.19
TA026M3	2	Brush & Low Trees	2,248,580.97	310,370.21	4.79	4.93	0.14
TA027M1	2	Brush & Low Trees	2,255,546.27	304,590.76	3.95	4.41	0.46
TA028M2	2	Brush & Low Trees	2,262,128.55	290,479.88	2.74	3.26	0.52
TA029M5	2	Brush & Low Trees	2,276,254.87	304,824.09	28.89	29.14	0.25
TA030M3	2	Brush & Low Trees	2,287,133.96	311,213.83	32.12	32.46	0.34
TA031M3	2	Brush & Low Trees	2,298,594.06	315,556.67	34.67	34.48	-0.19
TA032M5	2	Brush & Low Trees	2,294,839.01	284,338.18	32.38	32.20	-0.18
TA033M5	2	Brush & Low Trees	2,304,603.80	284,512.88	29.76	30.20	0.44
TA034M4	2	Brush & Low Trees	2,311,698.18	260,598.14	26.46	26.50	0.04
TA035M9	2	Brush & Low Trees	2,318,429.40	252,406.01	18.06	17.72	-0.34
TA037M4	2	Brush & Low Trees	2,332,718.85	274,923.56	19.17	19.18	0.01
TA039M4	2	Brush & Low Trees	2,327,126.33	284,875.62	25.39	24.82	-0.57
TA040M5	2	Brush & Low Trees	2,322,339.39	312,738.01	30.98	30.41	-0.57
TA002M5	3	Forested	2,136,442.48	417,729.42	5.78	5.49	-0.29
TA003M6	3	Forested	2,149,747.64	430,405.19	12.71	12.08	-0.63
TA004M7	3	Forested	2,165,437.75	442,483.35	29.13	29.01	-0.12
TA005M5	3	Forested	2,186,789.57	454,206.51	36.50	36.08	-0.42
TA006M8	3	Forested	2,157,098.64	387,574.17	5.89	5.15	-0.74
TA007M3	3	Forested	2,157,939.62	416,463.94	12.96	12.67	-0.29
TA008M6	3	Forested	2,178,898.37	428,584.05	22.34	22.46	0.12
TA010M5	3	Forested	2,206,947.51	411,028.88	30.71	30.11	-0.60
TA011M6	3	Forested	2,223,431.69	400,589.08	26.46	26.95	0.49
TA012M8	3	Forested	2,233,494.01	395,203.05	26.14	26.69	0.55
TA013M3	3	Forested	2,175,197.28	372,952.98	5.57	5.02	-0.55
TA014M4	3	Forested	2,201,907.61	369,763.61	5.28	4.96	-0.32
TA015M4	3	Forested	2,218,937.55	380,492.00	30.09	29.32	-0.77
TA016M8	3	Forested	2,252,807.11	381,196.24	33.69	33.68	-0.01
TA017M6	3	Forested	2,261,785.76	387,683.00	41.52	41.28	-0.24
TA018M7	3	Forested	2,266,241.29	402,190.49	46.78	46.78	0.00
TA019M3	3	Forested	2,257,988.83	413,029.37	43.54	43.14	-0.40
TA021M11	3	Forested	2,247,820.78	401,710.04	31.04	32.24	1.20
TA022M3	3	Forested	2,240,785.99	362,964.78	31.76	32.58	0.82
TA023M1	3	Forested	2,262,707.74	320,177.53	31.57	31.77	0.20
TA024M9	3	Forested	2,182,979.93	416,178.52	22.94	23.09	0.15
TA025M4	3	Forested	2,245,457.86	323,083.69	4.73	4.72	-0.01
TA026M6	3	Forested	2,248,569.23	310,567.06	4.84	4.85	0.01
TA027M3	3	Forested	2,255,575.34	304,554.89	5.90	5.48	-0.42
TA028M5	3	Forested	2,262,159.88	290,389.99	4.03	3.16	-0.87
TA029M7	3	Forested	2,276,279.87	304,913.45	29.90	30.39	0.49
TA030M2	3	Forested	2,287,157.84	311,222.15	31.99	32.37	0.38

TA031M5	3	Forested	2,298,593.98	315,635.44	34.77	35.08	0.31
TA032M3	3	Forested	2,294,758.13	284,370.51	30.77	30.57	-0.20
TA033M6	3	Forested	2,304,581.12	284,560.35	30.18	30.21	0.03
TA034M5	3	Forested	2,311,669.63	260,507.23	25.83	25.43	-0.40
TA035M1	3	Forested	2,318,552.36	252,159.36	14.83	14.28	-0.55
TA035M6	3	Forested	2,318,663.35	252,208.99	17.35	17.51	0.16
TA037M8	3	Forested	2,332,595.05	274,958.16	19.93	19.67	-0.26
TA038M6	3	Forested	2,341,225.79	285,187.60	18.96	19.37	0.41
TA039M5	3	Forested	2,327,189.43	284,873.37	25.49	25.99	0.50
TA040M3	3	Forested	2,322,261.59	312,839.82	31.13	30.83	-0.30
TA006M6	4	Urban	2,157,071.92	387,562.13	6.84	6.07	-0.77
TA007M8	4	Urban	2,157,996.48	416,643.87	14.07	13.34	-0.73
TA010M3	4	Urban	2,206,884.38	410,982.32	32.18	31.50	-0.68
TA011M7	4	Urban	2,223,417.98	400,654.77	31.20	30.09	-1.11
TA012M6	4	Urban	2,233,650.61	395,292.89	29.31	28.84	-0.47
TA014M1	4	Urban	2,201,953.69	369,872.56	7.30	6.86	-0.44
TA015M3	4	Urban	2,218,879.60	380,578.80	31.90	31.43	-0.47
TA016M3	4	Urban	2,253,004.65	381,267.66	36.48	36.29	-0.19
TA017M1	4	Urban	2,261,880.48	387,613.03	42.10	41.55	-0.55
TA018M6	4	Urban	2,266,304.08	402,222.15	46.63	46.01	-0.63
TA019M2	4	Urban	2,258,056.67	412,998.53	44.89	44.03	-0.86
TA020M2	4	Urban	2,237,493.40	416,932.16	37.25	36.92	-0.33
TA021M2	4	Urban	2,247,721.85	401,625.87	33.79	33.69	-0.10
TA022M6	4	Urban	2,240,919.04	363,046.52	33.15	33.36	0.21
TA024M8	4	Urban	2,183,010.81	416,229.20	23.55	22.99	-0.56
TA025M2	4	Urban	2,245,434.47	323,016.09	7.24	6.80	-0.44
TA026M2	4	Urban	2,248,631.68	310,361.65	4.96	4.86	-0.10
TA027M9	4	Urban	2,255,524.39	304,394.85	7.62	7.65	0.03
TA028M7	4	Urban	2,262,163.20	290,285.71	4.88	5.01	0.13
TA034M1	4	Urban	2,311,848.77	260,574.28	26.71	26.65	-0.06
TA035M8	4	Urban	2,318,518.84	252,399.97	17.71	17.05	-0.66
TA037M7	4	Urban	2,332,714.64	275,114.71	22.78	22.97	0.19
TA038M7	4	Urban	2,341,276.76	285,138.04	23.34	23.34	0.00
TA040M1	4	Urban	2,322,188.08	312,869.95	35.27	34.41	-0.86

The following points did not meet the location criterion for CAT 1 - moved to CAT 2 (high grass/weeds)

Point No	Land Cover Class	LiDAR - Z	Survey - Z	ΔZ	ΔZ*2	ABS ΔZ
TA003M4	1	12.14	12.77	-0.63	0.40	0.63
TA004M2	1	28.20	29.07	-0.87	0.76	0.87
TA005M1	1	36.85	37.49	-0.64	0.40	0.64
TA007M9	1	11.45	12.10	-0.65	0.42	0.65
TA008M1	1	25.93	26.45	-0.52	0.27	0.52
TA033M2	1	29.00	29.67	-0.68	0.46	0.68

The following points on dirt roads did not meet the location criterion for CAT 1 and were not used at all

Point No	Land Cover Class	LiDAR - Z	Survey - Z	ΔZ	ΔZ*2	ABS ΔZ
TA003M8	1	13.44	14.10	-0.66	0.43	0.66
TA004M1	1	28.46	29.43	-0.97	0.95	0.97
TA005M6	1	38.10	38.74	-0.64	0.40	0.64
TA009M6	1	28.71	29.27	-0.56	0.32	0.56
TA013M5	1	5.54	6.09	-0.55	0.30	0.55

100 % of Totals	# of Points	RMSE (ft) Spec = 0.61 (BE = 0.30)	Mean (ft)	Median (ft)	Min (ft)	Max (ft)
Consolidated	144	0.44	-0.17	-0.23	-1.11	1.20
BE & Low Grass	38	0.30	-0.12	-0.19	-0.53	0.46
Brush & Low Trees	45	0.46	-0.18	-0.27	-0.87	0.93
Forested	37	0.47	-0.07	-0.12	-0.87	1.20
Urban	24	0.53	-0.39	-0.46	-1.11	0.21

Land Cover Category	# of Points	FVA — Fundamental Vertical Accuracy (RMSEz x 1.9600) Spec = 0.60 ft	CVA — Consolidated Vertical Accuracy (95th Percentile) Spec = 1.19 ft	SVA — Supplemental Vertical Accuracy (95th Percentile) Target = 1.19 ft
Consolidated	144		0.84	
BE & Low Grass	38	0.58		0.46
Brush & Low Trees	45			0.82
Forested	37			0.83
Urban	24			0.86

Taylor County - Vertical Accuracy Assessment for Category 1 Points						
Point No	Land Cover Class	LiDAR TIN - Z	Survey - Z	ΔZ	ΔZ^2	ABS ΔZ
TA002M3	1	4.90	5.30	-0.40	0.16	0.40
TA002M8	1	5.68	6.09	-0.41	0.17	0.41
TA008M2	1	25.84	26.28	-0.44	0.20	0.44
TA009M7	1	25.07	25.50	-0.43	0.18	0.43
TA010M4	1	30.07	30.60	-0.53	0.28	0.53
TA010M6	1	29.90	30.25	-0.35	0.13	0.35
TA011M8	1	25.16	25.12	0.04	0.00	0.04
TA012M3	1	26.29	26.24	0.05	0.00	0.05
TA014M3	1	5.95	6.40	-0.45	0.21	0.45
TA015M1	1	30.99	31.22	-0.23	0.05	0.23
TA016M7	1	34.43	34.44	-0.01	0.00	0.01
TA017M4	1	41.26	41.54	-0.28	0.08	0.28
TA017M7	1	41.05	41.27	-0.22	0.05	0.22
TA018M2	1	47.70	47.78	-0.08	0.01	0.08
TA019M6	1	41.03	41.41	-0.38	0.15	0.38
TA020M1	1	36.92	37.20	-0.28	0.08	0.28
TA020M4	1	35.43	35.20	0.23	0.05	0.23
TA021M8	1	33.02	32.81	0.21	0.04	0.21
TA022M5	1	31.39	31.02	0.37	0.13	0.37
TA023M2	1	31.73	31.52	0.21	0.04	0.21
TA023M3	1	31.22	30.76	0.46	0.21	0.46
TA024M7	1	20.38	20.74	-0.36	0.13	0.36
TA025M1	1	7.04	7.39	-0.35	0.12	0.35
TA026M4	1	4.25	4.25	0.00	0.00	0.00
TA027M6	1	5.66	5.49	0.17	0.03	0.17
TA028M6	1	3.55	3.28	0.27	0.07	0.27
TA029M1	1	30.73	30.70	0.03	0.00	0.03
TA029M6	1	29.07	28.97	0.10	0.01	0.10
TA030M1	1	32.10	32.16	-0.06	0.00	0.06
TA030M7	1	31.61	31.63	-0.02	0.00	0.02
TA031M2	1	34.49	34.77	-0.28	0.08	0.28
TA031M7	1	34.18	34.28	-0.10	0.01	0.10
TA032M1	1	30.52	30.93	-0.41	0.17	0.41
TA034M7	1	24.69	24.75	-0.06	0.00	0.06
TA037M6	1	22.47	22.43	0.04	0.00	0.04
TA038M4	1	23.68	23.26	0.41	0.17	0.41
TA039M6	1	24.86	25.22	-0.36	0.13	0.36
TA040M4	1	34.05	34.53	-0.48	0.23	0.48
	Geo-Referencing			sum of dz²	3.38	
	Horiz	NAD83(1992) NZ		count	38.00	
	Vert.	NAVD88 (Geoid99)		sum dz2/count	0.09	
	Units	US Survey Feet		RMSE	0.30	

				1.96 * RMSE	0.58	
	RMSE Calculation			mean	-0.12	
	Square Root of $\sum(Zn\text{-}Z'n)^2/N$			median	-0.09	
	Zn = LiDAR Dem Heights			skew	0.38	
	Z'n = Checkpoint Heights			std dev	0.28	
	N = The number of check points			**95th percentile**	**0.46**	
Ground Cover CAT	**CAT Description**	**Survey CAT**	**Surv. CAT Ground Cover Equivalent**		**DZ MIN**	**DZ MAX**
CAT 1	BE & Low Grass	GND 1, DRD, MGF	GND 1 = Ground - BE & Low Grass		-0.53	0.46
CAT 2	Brush & Low Trees	GND 2	GND 2 = Ground - Brush & Low Trees			
CAT 3	Forested	GND 3	GND 3 = Ground - Forested			
CAT 4	Urban	PVM 4	DRD = Ground - Dirt/Clay Road			
			PVM = Pavement (Asphalt/Concrete)			
			MGF= Well Maintained Ground Feature			
Land Cover Categories and Accuracy Criteria			**Computed Accuracies**			
Ground Cover CAT	**RMSEz (Ft) ≤**	**ACCURACYz (Ft) ≤**	**Actual RMSEz**	**95% Acc Z**	**95th Percentile**	
CAT 1	0.30	0.60	0.30	0.58	0.46	
CAT 2	0.61	1.19				
CAT 3	0.61	1.19				
CAT 4	0.61	1.19				
COMBINED	0.61	1.19				
The following points did not meet the location criterion for CAT 1 - moved to CAT 2 (high grass/weeds)						
Point No	**Land Cover Class**	**LiDAR - Z**	**Survey - Z**	**ΔZ**	**ΔZ^2**	**ABS ΔZ**
TA003M4	1	12.14	12.77	-0.63	0.40	0.63
TA004M2	1	28.20	29.07	-0.87	0.76	0.87
TA005M1	1	36.85	37.49	-0.64	0.40	0.64
TA007M9	1	11.45	12.10	-0.65	0.42	0.65
TA008M1	1	25.93	26.45	-0.52	0.27	0.52
TA033M2	1	29.00	29.67	-0.68	0.46	0.68
The following points on dirt roads did not meet the location criterion for CAT 1 and were not used at all						
Point No	**Land Cover Class**	**LiDAR - Z**	**Survey - Z**	**ΔZ**	**ΔZ^2**	**ABS ΔZ**
TA003M8	1	13.44	14.10	-0.66	0.43	0.66
TA004M1	1	28.46	29.43	-0.97	0.95	0.97
TA005M6	1	38.10	38.74	-0.64	0.40	0.64
TA009M6	1	28.71	29.27	-0.56	0.32	0.56
TA013M5	1	5.54	6.09	-0.55	0.03	0.55

Taylor County - Vertical Accuracy Assessment for Category 2 Points						
PID	Land Cover Cat.	LiDAR TIN - Z	Survey Height	DELTA Z	DZ*2	ABS DZ
TA002M6	2	5.78	6.11	-0.33	0.11	0.33
TA003M3	2	13.33	14.04	-0.71	0.51	0.71
TA004M3	2	28.99	29.53	-0.54	0.29	0.54
TA005M3	2	37.25	37.71	-0.46	0.21	0.46
TA005M7	2	37.43	37.70	-0.27	0.07	0.27
TA006M4	2	4.75	5.40	-0.66	0.43	0.66
TA006M7	2	4.75	5.59	-0.84	0.71	0.84
TA007M7	2	12.18	12.82	-0.64	0.41	0.64
TA008M8	2	25.17	25.43	-0.27	0.07	0.27
TA009M4	2	28.25	28.19	0.05	0.00	0.05
TA009M5	2	28.29	27.85	0.43	0.19	0.43
TA011M1	2	27.52	27.25	0.27	0.07	0.27
TA012M5	2	27.16	27.11	0.05	0.00	0.05
TA013M2	2	4.70	5.14	-0.44	0.19	0.44
TA013M4	2	5.53	6.07	-0.54	0.29	0.54
TA014M7	2	5.15	5.01	0.14	0.02	0.14
TA015M7	2	27.74	27.90	-0.16	0.03	0.16
TA016M4	2	34.53	34.75	-0.22	0.05	0.22
TA018M4	2	45.37	45.14	0.23	0.05	0.23
TA019M7	2	40.96	41.31	-0.35	0.12	0.35
TA020M3	2	37.39	37.73	-0.34	0.12	0.34
TA021M3	2	33.47	33.10	0.37	0.13	0.37
TA022M7	2	32.39	31.46	0.93	0.87	0.93
TA023M7	2	29.28	29.05	0.23	0.05	0.23
TA024M5	2	21.46	21.83	-0.37	0.14	0.37
TA025M3	2	4.72	4.91	-0.19	0.04	0.19
TA026M3	2	4.93	4.79	0.14	0.02	0.14
TA027M1	2	4.41	3.95	0.46	0.21	0.46
TA028M2	2	3.26	2.74	0.52	0.27	0.52
TA029M5	2	29.14	28.89	0.25	0.06	0.25
TA030M3	2	32.46	32.12	0.34	0.12	0.34
TA031M3	2	34.48	34.67	-0.19	0.03	0.19
TA032M5	2	32.20	32.38	-0.18	0.03	0.18
TA033M5	2	30.20	29.76	0.44	0.19	0.44
TA034M4	2	26.50	26.46	0.04	0.00	0.04
TA035M9	2	17.72	18.06	-0.34	0.12	0.34
TA037M4	2	19.18	19.17	0.01	0.00	0.01
TA039M4	2	24.82	25.39	-0.57	0.32	0.57
TA040M5	2	30.41	30.98	-0.57	0.32	0.57
TA003M4	2	12.14	12.77	-0.63	0.40	0.63
TA004M2	2	28.20	29.07	-0.87	0.76	0.87
TA005M1	2	36.85	37.49	-0.64	0.40	0.64
TA007M9	2	11.45	12.10	-0.65	0.42	0.65
TA008M1	2	25.93	26.45	-0.52	0.27	0.52

TA033M2	2	29.00	29.67	-0.68	0.46	0.68
	Geo-Referencing			sum of dz²	9.58	
	Horiz	NAD83(1992) NZ		count	45.00	
	Vert.	NAVD88 (Geoid99)		sum dz2/count	0.21	
	Units	US Survey Feet		RMSE	0.46	
				1.96 * RMSE	0.90	
	RMSE Calculation			mean	-0.18	
	Square Root of ∑(Zn-Z'n)²/N			median	-0.27	
	Zn = LiDAR Dem Heights			skew	0.47	
	Z'n = Checkpoint Heights			std dev	0.43	
	N = The number of check points			**95th percentile**	**0.82**	
Ground Cover CAT	**CAT Description**	**Survey CAT**	**Surv. CAT Ground Cover Equivalent**		**DZ MIN**	**DZ MAX**
CAT 1	BE & Low Grass	GND 1, DRD, MGF	GND 1 = Ground - BE & Low Grass		-0.87	0.93
CAT 2	Brush & Low Trees	GND 2	GND 2 = Ground - Brush & Low Trees			
CAT 3	Forested	GND 3	GND 3 = Ground - Forested			
CAT 4	Urban	PVM 4	DRD = Ground - Dirt/Clay Road			
			PVM = Pavement (Asphalt/Concrete)			
			MGF= Well Maintained Ground Feature			
Land Cover Categories and Accuracy Criteria			**Computed Accuracies**			
Ground Cover CAT	**RMSEz (Ft) ≤**	**ACCURACYz (Ft) ≤**	**Actual RMSEz**	**95% Acc Z**	**95th Percentile**	
CAT 1	0.30	0.60				
CAT 2	0.61	1.19	0.46	0.90	0.82	
CAT 3	0.61	1.19				
CAT 4	0.61	1.19				
COMBINED	0.61	1.19				

Taylor County - Vertical Accuracy Assessment for Category 3 Points						
PID	Land Cover Cat.	DTM Height	Survey Height	DELTA Z	DZ^2	ABS DZ
TA002M5	3	5.49	5.78	-0.29	0.09	0.29
TA003M6	3	12.08	12.71	-0.63	0.39	0.63
TA004M7	3	29.01	29.13	-0.12	0.01	0.12
TA005M5	3	36.08	36.50	-0.42	0.17	0.42
TA006M8	3	5.15	5.89	-0.74	0.55	0.74
TA007M3	3	12.67	12.96	-0.29	0.08	0.29
TA008M6	3	22.46	22.34	0.12	0.01	0.12
TA010M5	3	30.11	30.71	-0.60	0.36	0.60
TA011M6	3	26.95	26.46	0.49	0.24	0.49
TA012M8	3	26.69	26.14	0.55	0.31	0.55
TA013M3	3	5.02	5.57	-0.55	0.30	0.55
TA014M4	3	4.96	5.28	-0.32	0.10	0.32
TA015M4	3	29.32	30.09	-0.77	0.60	0.77
TA016M8	3	33.68	33.69	-0.01	0.00	0.01
TA017M6	3	41.28	41.52	-0.24	0.06	0.24
TA018M7	3	46.78	46.78	0.00	0.00	0.00
TA019M3	3	43.14	43.54	-0.40	0.16	0.40
TA021M11	3	32.24	31.04	1.20	1.44	1.20
TA022M3	3	32.58	31.76	0.82	0.68	0.82
TA023M1	3	31.77	31.57	0.20	0.04	0.20
TA024M9	3	23.09	22.94	0.15	0.02	0.15
TA025M4	3	4.72	4.73	-0.01	0.00	0.01
TA026M6	3	4.85	4.84	0.01	0.00	0.01
TA027M3	3	5.48	5.90	-0.42	0.17	0.42
TA028M5	3	3.16	4.03	-0.87	0.76	0.87
TA029M7	3	30.39	29.90	0.49	0.24	0.49
TA030M2	3	32.37	31.99	0.38	0.14	0.38
TA031M5	3	35.08	34.77	0.31	0.10	0.31
TA032M3	3	30.57	30.77	-0.20	0.04	0.20
TA033M6	3	30.21	30.18	0.03	0.00	0.03
TA034M5	3	25.43	25.83	-0.40	0.16	0.40
TA035M1	3	14.28	14.83	-0.55	0.30	0.55
TA035M6	3	17.51	17.35	0.16	0.03	0.16
TA037M8	3	19.67	19.93	-0.26	0.07	0.26
TA038M6	3	19.37	18.96	0.41	0.17	0.41
TA039M5	3	25.99	25.49	0.50	0.25	0.50
TA040M3	3	30.83	31.13	-0.30	0.09	0.30
	Geo-Referencing			sum of dz²	8.14	
	Horiz	NAD83(1992) NZ		count	37.00	
	Vert.	NAVD88 (Geoid99)		sum dz2/count	0.22	
	Units	US Survey Feet		RMSE	0.47	
				1.96 * RMSE	0.92	

	RMSE Calculation			mean	-0.07	
	Square Root of $\sum(Zn-Z'n)^2/N$			median	-0.12	
	Zn = LiDAR Dem Heights			skew	0.54	
	Z'n = Checkpoint Heights			std dev	0.47	
	N = The number of check points			**95th percentile**	**0.83**	
Ground Cover CAT	**CAT Description**	**Survey CAT**	**Surv. CAT Ground Cover Equivalent**		**DZ MIN**	**DZ MAX**
CAT 1	BE & Low Grass	GND 1, DRD, MGF	GND 1 = Ground - BE & Low Grass		-0.87	1.20
CAT 2	Brush & Low Trees	GND 2	GND 2 = Ground - Brush & Low Trees			
CAT 3	Forested	GND 3	GND 3 = Ground - Forested			
CAT 4	Urban	PVM 4	DRD = Ground - Dirt/Clay Road			
			PVM = Pavement (Asphalt/Concrete)			
			MGF= Well Maintained Ground Feature			
Land Cover Categories and Accuracy Criteria			**Computed Accuracies**			
Ground Cover CAT	**RMSEz (Ft) ≤**	**ACCURACYz (Ft) ≤**	**Actual RMSEz**	**95% Acc Z**	**95th Percentile**	
CAT 1	0.30	0.60				
CAT 2	0.61	1.19				
CAT 3	0.61	1.19	0.47	0.92	0.83	
CAT 4	0.61	1.19				
COMBINED	0.61	1.19				

Taylor County - Vertical Accuracy Assessment for Category 4 Points						
PID	Land Cover Cat.	DTM Height	Survey Height	DELTA Z	DZ*2	ABS DZ
TA006M6	4	6.07	6.84	-0.77	0.59	0.77
TA007M8	4	13.34	14.07	-0.73	0.54	0.73
TA010M3	4	31.50	32.18	-0.68	0.46	0.68
TA011M7	4	30.09	31.20	-1.11	1.23	1.11
TA012M6	4	28.84	29.31	-0.47	0.22	0.47
TA014M1	4	6.86	7.30	-0.44	0.19	0.44
TA015M3	4	31.43	31.90	-0.47	0.22	0.47
TA016M3	4	36.29	36.48	-0.19	0.04	0.19
TA017M1	4	41.55	42.10	-0.55	0.30	0.55
TA018M6	4	46.01	46.63	-0.63	0.39	0.63
TA019M2	4	44.03	44.89	-0.86	0.74	0.86
TA020M2	4	36.92	37.25	-0.33	0.11	0.33
TA021M2	4	33.69	33.79	-0.10	0.01	0.10
TA022M6	4	33.36	33.15	0.21	0.04	0.21
TA024M8	4	22.99	23.55	-0.56	0.32	0.56
TA025M2	4	6.80	7.24	-0.44	0.19	0.44
TA026M2	4	4.86	4.96	-0.10	0.01	0.10
TA027M9	4	7.65	7.62	0.03	0.00	0.03
TA028M7	4	5.01	4.88	0.13	0.02	0.13
TA034M1	4	26.65	26.71	-0.06	0.00	0.06
TA035M8	4	17.05	17.71	-0.66	0.43	0.66
TA037M7	4	22.97	22.78	0.19	0.04	0.19
TA038M7	4	23.34	23.34	0.00	0.00	0.00
TA040M1	4	34.41	35.27	-0.86	0.75	0.86
	Geo-Referencing			sum of dz²	6.84	
	Horiz	NAD83(1992) NZ		count	24.00	
	Vert.	NAVD88 (Geoid99)		sum dz2/count	0.29	
	Units	US Survey Feet		RMSE	0.53	
				1.96 * RMSE	1.05	
	RMSE Calculation			mean	-0.39	
	Square Root of ∑(Zn-Z'n)²/N			median	-0.46	
	Zn = LiDAR Dem Heights			skew	0.07	
	Z'n = Checkpoint Heights			std dev	0.37	
	N = The number of check points			**95th percentile**	**0.86**	
Ground Cover CAT	**CAT Description**	**Survey CAT**	**Surv. CAT Ground Cover Equivalent**		**DZ MIN**	**DZ MAX**
CAT 1	BE & Low Grass	GND 1, DRD, MGF	GND 1 = Ground - BE & Low Grass		-1.11	0.21
CAT 2	Brush & Low Trees	GND 2	GND 2 = Ground - Brush & Low Trees			
CAT 3	Forested	GND 3	GND 3 = Ground - Forested			
CAT 4	Urban	PVM 4	DRD = Ground - Dirt/Clay Road			

			PVM = Pavement (Asphalt/Concrete)			
			MGF= Well Maintained Ground Feature			
Land Cover Categories and Accuracy Criteria			**Computed Accuracies**			
Ground Cover CAT	**RMSEz (Ft) ≤**	**ACCURACYz (Ft) ≤**	**Actual RMSEz**	**95% Acc Z**	**95th Percentile**	
CAT 1	0.30	0.60				
CAT 2	0.61	1.19				
CAT 3	0.61	1.19				
CAT 4	0.61	1.19	0.53	1.05	0.86	
COMBINED	0.61	1.19				

Taylor County - Vertical Accuracy Assessment for All Categories Combined						
PID	Land Cover Cat.	DTM Height	Survey Height	DELTA Z	DZ^2	ABS DZ
TA002M3	1	4.90	5.30	-0.40	0.16	0.40
TA002M8	1	5.68	6.09	-0.41	0.17	0.41
TA008M2	1	25.84	26.28	-0.44	0.20	0.44
TA009M7	1	25.07	25.50	-0.43	0.18	0.43
TA010M4	1	30.07	30.60	-0.53	0.28	0.53
TA010M6	1	29.90	30.25	-0.35	0.13	0.35
TA011M8	1	25.16	25.12	0.04	0.00	0.04
TA012M3	1	26.29	26.24	0.05	0.00	0.05
TA014M3	1	5.95	6.40	-0.45	0.21	0.45
TA015M1	1	30.99	31.22	-0.23	0.05	0.23
TA016M7	1	34.43	34.44	-0.01	0.00	0.01
TA017M4	1	41.26	41.54	-0.28	0.08	0.28
TA017M7	1	41.05	41.27	-0.22	0.05	0.22
TA018M2	1	47.70	47.78	-0.08	0.01	0.08
TA019M6	1	41.03	41.41	-0.38	0.15	0.38
TA020M1	1	36.92	37.20	-0.28	0.08	0.28
TA020M4	1	35.43	35.20	0.23	0.05	0.23
TA021M8	1	33.02	32.81	0.21	0.04	0.21
TA022M5	1	31.39	31.02	0.37	0.13	0.37
TA023M2	1	31.73	31.52	0.21	0.04	0.21
TA023M3	1	31.22	30.76	0.46	0.21	0.46
TA024M7	1	20.38	20.74	-0.36	0.13	0.36
TA025M1	1	7.04	7.39	-0.35	0.12	0.35
TA026M4	1	4.25	4.25	0.00	0.00	0.00
TA027M6	1	5.66	5.49	0.17	0.03	0.17
TA028M6	1	3.55	3.28	0.27	0.07	0.27
TA029M1	1	30.73	30.70	0.03	0.00	0.03
TA029M6	1	29.07	28.97	0.10	0.01	0.10
TA030M1	1	32.10	32.16	-0.06	0.00	0.06
TA030M7	1	31.61	31.63	-0.02	0.00	0.02
TA031M2	1	34.49	34.77	-0.28	0.08	0.28
TA031M7	1	34.18	34.28	-0.10	0.01	0.10
TA032M1	1	30.52	30.93	-0.41	0.17	0.41
TA034M7	1	24.69	24.75	-0.06	0.00	0.06
TA037M6	1	22.47	22.43	0.04	0.00	0.04
TA038M4	1	23.68	23.26	0.41	0.17	0.41
TA039M6	1	24.86	25.22	-0.36	0.13	0.36
TA040M4	1	34.05	34.53	-0.48	0.23	0.48
TA002M6	2	5.78	6.11	-0.33	0.11	0.33
TA003M3	2	13.33	14.04	-0.71	0.51	0.71
TA004M3	2	28.99	29.53	-0.54	0.29	0.54
TA005M3	2	37.25	37.71	-0.46	0.21	0.46
TA005M7	2	37.43	37.70	-0.27	0.07	0.27
TA006M4	2	4.75	5.40	-0.66	0.43	0.66

TA006M7	2	4.75	5.59	-0.84	0.71	0.84
TA007M7	2	12.18	12.82	-0.64	0.41	0.64
TA008M8	2	25.17	25.43	-0.27	0.07	0.27
TA009M4	2	28.25	28.19	0.05	0.00	0.05
TA009M5	2	28.29	27.85	0.43	0.19	0.43
TA011M1	2	27.52	27.25	0.27	0.07	0.27
TA012M5	2	27.16	27.11	0.05	0.00	0.05
TA013M2	2	4.70	5.14	-0.44	0.19	0.44
TA013M4	2	5.53	6.07	-0.54	0.29	0.54
TA014M7	2	5.15	5.01	0.14	0.02	0.14
TA015M7	2	27.74	27.90	-0.16	0.03	0.16
TA016M4	2	34.53	34.75	-0.22	0.05	0.22
TA018M4	2	45.37	45.14	0.23	0.05	0.23
TA019M7	2	40.96	41.31	-0.35	0.12	0.35
TA020M3	2	37.39	37.73	-0.34	0.12	0.34
TA021M3	2	33.47	33.10	0.37	0.13	0.37
TA022M7	2	32.39	31.46	0.93	0.87	0.93
TA023M7	2	29.28	29.05	0.23	0.05	0.23
TA024M5	2	21.46	21.83	-0.37	0.14	0.37
TA025M3	2	4.72	4.91	-0.19	0.04	0.19
TA026M3	2	4.93	4.79	0.14	0.02	0.14
TA027M1	2	4.41	3.95	0.46	0.21	0.46
TA028M2	2	3.26	2.74	0.52	0.27	0.52
TA029M5	2	29.14	28.89	0.25	0.06	0.25
TA030M3	2	32.46	32.12	0.34	0.12	0.34
TA031M3	2	34.48	34.67	-0.19	0.03	0.19
TA032M5	2	32.20	32.38	-0.18	0.03	0.18
TA033M5	2	30.20	29.76	0.44	0.19	0.44
TA034M4	2	26.50	26.46	0.04	0.00	0.04
TA035M9	2	17.72	18.06	-0.34	0.12	0.34
TA037M4	2	19.18	19.17	0.01	0.00	0.01
TA039M4	2	24.82	25.39	-0.57	0.32	0.57
TA040M5	2	30.41	30.98	-0.57	0.32	0.57
TA003M4	2	12.14	12.77	-0.63	0.40	0.63
TA004M2	2	28.20	29.07	-0.87	0.76	0.87
TA005M1	2	36.85	37.49	-0.64	0.40	0.64
TA007M9	2	11.45	12.10	-0.65	0.42	0.65
TA008M1	2	25.93	26.45	-0.52	0.27	0.52
TA033M2	2	29.00	29.67	-0.68	0.46	0.68
TA002M5	3	5.49	5.78	-0.29	0.09	0.29
TA003M6	3	12.08	12.71	-0.63	0.39	0.63
TA004M7	3	29.01	29.13	-0.12	0.01	0.12
TA005M5	3	36.08	36.50	-0.42	0.17	0.42
TA006M8	3	5.15	5.89	-0.74	0.55	0.74
TA007M3	3	12.67	12.96	-0.29	0.08	0.29
TA008M6	3	22.46	22.34	0.12	0.01	0.12
TA010M5	3	30.11	30.71	-0.60	0.36	0.60

TA011M6	3	26.95	26.46	0.49	0.24	0.49
TA012M8	3	26.69	26.14	0.55	0.31	0.55
TA013M3	3	5.02	5.57	-0.55	0.30	0.55
TA014M4	3	4.96	5.28	-0.32	0.10	0.32
TA015M4	3	29.32	30.09	-0.77	0.60	0.77
TA016M8	3	33.68	33.69	-0.01	0.00	0.01
TA017M6	3	41.28	41.52	-0.24	0.06	0.24
TA018M7	3	46.78	46.78	0.00	0.00	0.00
TA019M3	3	43.14	43.54	-0.40	0.16	0.40
TA021M11	3	32.24	31.04	1.20	1.44	1.20
TA022M3	3	32.58	31.76	0.82	0.68	0.82
TA023M1	3	31.77	31.57	0.20	0.04	0.20
TA024M9	3	23.09	22.94	0.15	0.02	0.15
TA025M4	3	4.72	4.73	-0.01	0.00	0.01
TA026M6	3	4.85	4.84	0.01	0.00	0.01
TA027M3	3	5.48	5.90	-0.42	0.17	0.42
TA028M5	3	3.16	4.03	-0.87	0.76	0.87
TA029M7	3	30.39	29.90	0.49	0.24	0.49
TA030M2	3	32.37	31.99	0.38	0.14	0.38
TA031M5	3	35.08	34.77	0.31	0.10	0.31
TA032M3	3	30.57	30.77	-0.20	0.04	0.20
TA033M6	3	30.21	30.18	0.03	0.00	0.03
TA034M5	3	25.43	25.83	-0.40	0.16	0.40
TA035M1	3	14.28	14.83	-0.55	0.30	0.55
TA035M6	3	17.51	17.35	0.16	0.03	0.16
TA037M8	3	19.67	19.93	-0.26	0.07	0.26
TA038M6	3	19.37	18.96	0.41	0.17	0.41
TA039M5	3	25.99	25.49	0.50	0.25	0.50
TA040M3	3	30.83	31.13	-0.30	0.09	0.30
TA006M6	4	6.07	6.84	-0.77	0.59	0.77
TA007M8	4	13.34	14.07	-0.73	0.54	0.73
TA010M3	4	31.50	32.18	-0.68	0.46	0.68
TA011M7	4	30.09	31.20	-1.11	1.23	1.11
TA012M6	4	28.84	29.31	-0.47	0.22	0.47
TA014M1	4	6.86	7.30	-0.44	0.19	0.44
TA015M3	4	31.43	31.90	-0.47	0.22	0.47
TA016M3	4	36.29	36.48	-0.19	0.04	0.19
TA017M1	4	41.55	42.10	-0.55	0.30	0.55
TA018M6	4	46.01	46.63	-0.63	0.39	0.63
TA019M2	4	44.03	44.89	-0.86	0.74	0.86
TA020M2	4	36.92	37.25	-0.33	0.11	0.33
TA021M2	4	33.69	33.79	-0.10	0.01	0.10
TA022M6	4	33.36	33.15	0.21	0.04	0.21
TA024M8	4	22.99	23.55	-0.56	0.32	0.56
TA025M2	4	6.80	7.24	-0.44	0.19	0.44
TA026M2	4	4.86	4.96	-0.10	0.01	0.10
TA027M9	4	7.65	7.62	0.03	0.00	0.03

TA028M7	4	5.01	4.88	0.13	0.02	0.13
TA034M1	4	26.65	26.71	-0.06	0.00	0.06
TA035M8	4	17.05	17.71	-0.66	0.43	0.66
TA037M7	4	22.97	22.78	0.19	0.04	0.19
TA038M7	4	23.34	23.34	0.00	0.00	0.00
TA040M1	4	34.41	35.27	-0.86	0.75	0.86
	Geo-Referencing			sum of dz^2	27.95	
	Horiz	NAD83(1992) NZ		count	144.00	
	Vert.	NAVD88 (Geoid99)		sum dz2/count	0.19	
	Units	US Survey Feet		RMSE	0.44	
				1.96 * RMSE	0.86	
	RMSE Calculation			mean	-0.17	
	Square Root of $\sum(Zn-Z'n)^2/N$			median	-0.23	
	Zn = LiDAR Dem Heights			skew	0.43	
	Z'n = Checkpoint Heights			std dev	0.41	
	N = The number of check points			**95th percentile**	**0.84**	
Ground Cover CAT	**CAT Description**	**Survey CAT**	**Surv. CAT Ground Cover Equivalent**		**DZ MIN**	**DZ MAX**
CAT 1	BE & Low Grass	GND 1, DRD, MGF	GND 1 = Ground - BE & Low Grass		-1.11	1.20
CAT 2	Brush & Low Trees	GND 2	GND 2 = Ground - Brush & Low Trees			
CAT 3	Forested	GND 3	GND 3 = Ground - Forested			
CAT 4	Urban	PVM 4	DRD = Ground - Dirt/Clay Road			
			PVM = Pavement (Asphalt/Concrete)			
			MGF= Well Maintained Ground Feature			
Land Cover Categories and Accuracy Criteria			**Computed Accuracies**			
Ground Cover CAT	**RMSEz (Ft) ≤**	**ACCURACYz (Ft) ≤**	**RMSEz**	**95% Acc Z**	**95th Percentile**	
CAT 1	0.30	0.60	0.30	0.58	0.46	
CAT 2	0.61	1.19	0.46	0.90	0.82	
CAT 3	0.61	1.19	0.47	0.92	0.83	
CAT 4	0.61	1.19	0.53	1.05	0.86	
COMBINED	0.61	1.19	0.44	0.86	0.84	
Calculation of Estimated and Actual Number of Check Points and Clusters for This County Area						
Total Number of Tiles This County Area	**Square Miles Per 5K Tile**	**Total Square Miles This County Area**	**Number of Check Points per Sq. Mi.**	**Estimated Number of Check Points**	**Estimated Number of Point Clusters**	**Actual No. of Points / Clusters**
696	0.897	624	4.17	150	37	144 / 40

The following points did not meet the location criterion for CAT 1 - moved to CAT 2 (high grass/weeds)						
Point No	Land Cover Class	LiDAR - Z	Survey - Z	ΔZ	ΔZ*2	ABS ΔZ
TA003M4	1	12.14	12.77	-0.63	0.40	0.63
TA004M2	1	28.20	29.07	-0.87	0.76	0.87
TA005M1	1	36.85	37.49	-0.64	0.40	0.64
TA007M9	1	11.45	12.10	-0.65	0.42	0.65
TA008M1	1	25.93	26.45	-0.52	0.27	0.52
TA033M2	1	29.00	29.67	-0.68	0.46	0.68
The following points on dirt roads did not meet the location criterion for CAT 1 and were not used at all						
Point No	Land Cover Class	LiDAR - Z	Survey - Z	ΔZ	ΔZ*2	ABS ΔZ
TA003M8	1	13.44	14.10	-0.66	0.43	0.66
TA004M1	1	28.46	29.43	-0.97	0.95	0.97
TA005M6	1	38.10	38.74	-0.64	0.40	0.64
TA009M6	1	28.71	29.27	-0.56	0.32	0.56
TA013M5	1	5.54	6.09	-0.55	0.03	0.55

Appendix F: LiDAR Vertical Accuracy Report

Vertical Accuracy Assessment Report
2007 LiDAR Bare-Earth Dataset for
Taylor County, Florida

Date: August 8, 2008

References: A — State of Florida Division of Emergency Management (FDEM), Contract Number 07-HS-34-14-00-22-469, Task Order Number 20070525-492718a
B — Part 3: *National Standard for Spatial Data Accuracy (NSSDA)*, "Geospatial Positioning Accuracy Standards," published by the Federal Geographic Data Committee (FGDC), 1998
C — Appendix A, *Guidance for Aerial Mapping and Surveying*, "Guidelines and Specifications for Flood Hazard Mapping Partners," published by the Federal Emergency Management Agency (FEMA), April 2003
D — *Guidelines for Digital Elevation Data*, Version 1.0, published by the National Digital Elevation Program (NDEP), May 10, 2004
E — *ASPRS Guidelines, Vertical Accuracy Reporting for Lidar Data*, published by the American Society for Photogrammetry and Remote Sensing (ASPRS), May 24, 2004

Background
FDEM Guidance: Reference A tasked PDS to validate the bare-earth LiDAR dataset of Taylor County, FL, both quantitatively (for accuracy) and qualitatively (for usability). This report addresses the vertical accuracy assessment only, for which FDEM's major specifications are summarized as follows:

- Vertical accuracy: $\leq$ 0.30 feet $RMSE_z$ = $\leq$ 0.60 feet vertical accuracy at 95% confidence level, tested in flat, non-vegetated terrain only, employing NSSDA procedures in Reference B.
- Validation that the data also satisfies FEMA requirements in Reference C.
- Vertical units (orthometric heights) are in US Survey Feet, NAVD88.

NSSDA Guidance: Section 3.2.2 of Reference B specifies: "A minimum of 20 check points shall be tested, distributed to reflect the geographic area of interest and the distribution of error in the dataset. When 20 points are tested, the 95% confidence level allows one point to fail the threshold given in product specifications."

FEMA Guidance: Section A.8.6 of Reference C specifies the following LiDAR testing requirement for data to be used by the National Flood Insurance Program (NFIP): "For the NFIP, TINs (and DEMs derived there from) should normally have a maximum RMSE of 18.5 centimeters, equivalent to 2-foot contours, in flat terrain; and a maximum RMSE of 37 centimeters, equivalent to 4-foot contours, in rolling to hilly terrain. The Mapping Partner shall field verify the vertical accuracy of this TIN to ensure that the 18.5- or 37.0-centimeter RMSE requirement is satisfied for all major vegetation categories that predominate within the floodplain being studied … The assigned Mapping Partner shall separately evaluate and report on the TIN accuracy for the main categories of ground cover in the study area, including the following: [followed by explanations of seven potential categories]… Ground cover Categories 1 through 5 are fairly common everywhere … The assigned Mapping Partner shall select a minimum of 20 test points for each major vegetation category identified. Therefore, a minimum of 60 test points shall be selected for three (minimum) major land cover categories, 80 test points for four major categories, and so on."

Note: for this project PDS followed the FDEM guidelines in Reference A, which stipulates that the vertical accuracy report will be based on a minimum of 30 ground measurements for each of four land cover categories, totaling 120 test points for each 500 square mile area of new topographic data collection. Note the area covered in Taylor County contained 692 tiles and there is an average of 30 checkpoints established in each land cover category. The land cover measurements distributed through each project area will be collected for each of the following land cover categories:

1. Bare-earth and low grass
2. Brush Lands and low trees
3. Forested areas fully covered by trees
4. Urban areas

NDEP and ASPRS Guidance: NDEP guidelines (Reference D) and ASPRS guidelines (Reference E) also recommend a minimum of 60 checkpoints, with up to 100 points preferred. (These guidelines are referenced because FEMA's next update to Appendix A will include these newer NDEP and ASPRS guidelines, now recognizing that vertical errors for LiDAR bare-earth datasets in vegetated terrain do not necessarily follow a normal error distribution as assumed by the NSSDA.)

Vertical Accuracy Test Procedures

Ground Truth Surveys: The PDS team established a primary geodetic network covering approximately 6,000 square miles along the panhandle area of Northwest Florida to provide accurate and consistent control throughout the project area, which includes Taylor County. The Primary Network was used to establish base stations to support airborne GPS data acquisition. Two Secondary control networks were established to support the measurement of checkpoints used in the accuracy validation process for newly generated LiDAR and Orthophotography.

Assessment Procedures and Results: The LiDAR accuracy assessment for Taylor County was performed in accordance with References D and E which assume that LiDAR errors in some land cover categories may not follow a normal error distribution. This assessment was also performed in accordance with References B and C which assume that LiDAR bare-earth datasets errors do follow a normal error distribution. Comparisons between the two methods help determine the degree to which *systematic errors* may exist in Taylor County's four major land cover categories: (1) bare-earth and low grass, (2) brush lands and low trees, (3) forested areas fully covered by trees, (4) urban areas. When a LiDAR bare-earth dataset passes testing by both methods, compared with criteria specified in Reference A, the dataset clearly passes all vertical accuracy testing criteria for a digital terrain model (DTM) suitable for FDEM and FEMA requirements.

The relevant testing criteria, as stipulated in Reference A is summarized in Table 1.

Table 1 — DTM Acceptance Criteria for Taylor County

Quantitative Criteria	Measure of Acceptability
Fundamental Vertical Accuracy (FVA) in open terrain only = 95% confidence level	0.60 ft (0.30 ft $RMSE_z$ x 1.96000) for open terrain only
Supplemental Vertical Accuracy (SVA) in individual land cover categories = 95% confidence level	1.19 ft (based on 95^{th} percentile per land cover category)
Consolidated Vertical Accuracy (CVA) in all land cover categories combined = 95% confidence lever	1.19 ft (based on combined 95^{th} percentile)

Vertical Accuracy Testing in Accordance with NDEP and ASPRS Procedures

References D and E specify the mandatory determination of Fundamental Vertical Accuracy (FVA) and the optional determination of Supplemental Vertical Accuracy (SVA) and Consolidated Vertical Accuracy (CVA). FVA determines how well the LiDAR sensor performed in category (1), open terrain, where errors are random and normally distributed; whereas SVA determines how well the vegetation classification algorithms worked in land cover categories (2) and (3) where LiDAR elevations are often higher than surveyed elevations and category (4) where LiDAR elevations are often lower.

FVA is determined with check points located only in land cover category (1), open terrain (grass, dirt, sand, and/or rocks), where there is a very high probability that the LiDAR sensor will have detected the bare-earth ground surface and where random errors are expected to follow a normal error distribution. The FVA determines how well the calibrated LiDAR sensor performed. With a normal error distribution, the vertical accuracy at the 95% confidence level is computed as the vertical root mean square error ($RMSE_z$) of the checkpoints x 1.9600, as specified in Reference B. For Taylor County, for which floodplains are essentially flat, FDEM required the FVA to be 0.60 ft (18.29 cm) at the 95% confidence level (based on an $RMSE_z$ of 0.30 ft (9.14 cm), equivalent to 1 ft contours).

CVA is determined with all checkpoints in all land cover categories combined where there is a possibility that the LiDAR sensor and post-processing may yield elevation errors that do not follow a normal error distribution. CVA at the 95% confidence level equals the 95th percentile error for all checkpoints in all land cover categories combined. FDEM's CVA standard is 1.19 ft at the 95% confidence level. The CVA is accompanied by a listing of the 5% outliers that are larger than the 95th percentile used to compute the CVA; these are always the largest outliers that may depart from a normal error distribution. Here, $Accuracy_z$ differs from CVA because $Accuracy_z$ assumes elevation errors follow a normal error distribution where RMSE procedures are valid, whereas CVA assumes LiDAR errors may not follow a normal error distribution in vegetated categories, making the RMSE process invalid.

SVA is determined separately for each individual land cover category, again recognizing that the LiDAR sensor and post-processing may yield elevation errors that do not follow a normal error distribution, and where discrepancies can be used to identify the nature of systematic errors by land cover category. For each land cover category, the SVA at the 95% confidence level equals the 95th percentile error for all checkpoints in each individual land cover category. SVA statistics are calculated individually for bare-earth and low grass, brush lands and low trees, forested areas, and urban areas, in order to facilitate the analysis of the data based on each of these land cover categories that exist within Taylor County. The SVA criteria in Table 1 (1.19 ft at the 95% confidence level for each category) are target values only and are not mandatory; it is common for some SVA criteria to fail individual target values, yet satisfy FEMA's mandatory CVA criterion.

<u>QA/QC Steps</u>: The primary QA/QC steps used by PDS were as follows:

1. PDS surveyed "ground truth" QA/QC vertical checkpoints in accordance with guidance in references B, C, D and E. Figure 1 shows the location of "cluster areas" where PDS attempted to survey a minimum of 20 QA/QC checkpoints in each of the four land cover categories. Some clusters may not include points from all cover categories. The final totals were 38 checkpoints in bare-earth and low grass; 45 checkpoints in brush and low trees; 37 checkpoints in forested areas; and 24 checkpoints in urban areas, for a total of 144 checkpoints.
2. Next, PDS interpolated the bare-earth LiDAR DTM to provide the z-value for each of the 144 checkpoints.
3. PDS then computed the associated z-value differences between the interpolated z-value from the LiDAR data and the ground truth survey checkpoints and computed the FVA, CVA and SVA values using procedures in References D and E.

4. The data were analyzed by PDS to assess the accuracy of the data. The review process examined the various accuracy parameters as defined by FDEM guidelines. Also, the overall descriptive statistics of each dataset were computed to assess any trends or anomalies. The following tables, graphs and figures illustrate the data quality.

Figure 1 shows the location of the QA/QC checkpoint clusters within Taylor County. Each point represents a checkpoint cluster. There are nominally four checkpoints in each cluster, one per land cover category.

Figure 1 — Location of QA/QC Checkpoint Clusters for Taylor County

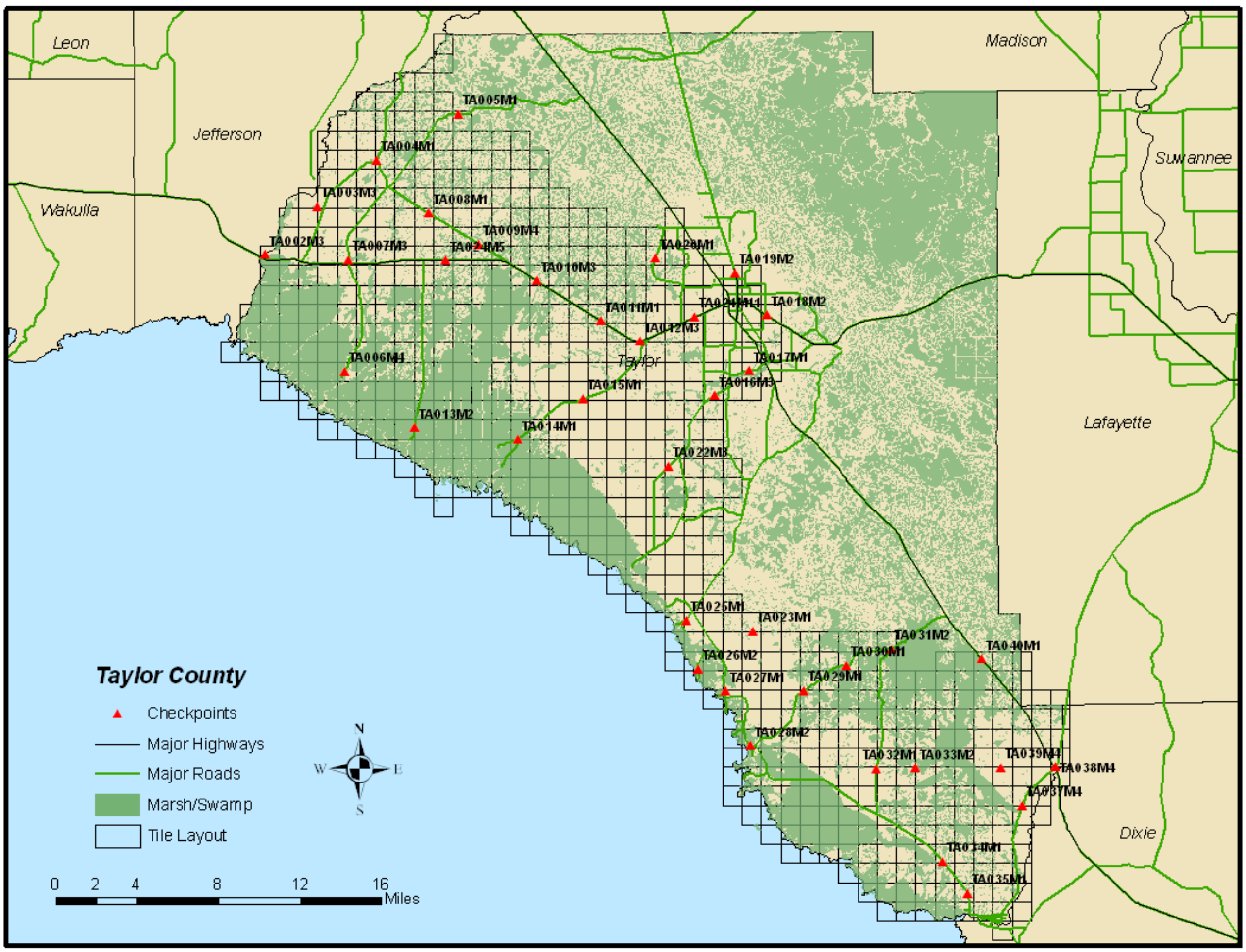


Table 2 summarizes the vertical accuracy by fundamental, consolidated and supplemental methods:

Table 2 — FVA, CVA and SVA Vertical Accuracy at 95% Confidence Level

Land Cover Category	# of Points	FVA — Fundamental Vertical Accuracy ($RMSE_z$ x 1.9600) Spec = 0.60 ft	CVA — Consolidated Vertical Accuracy (95th Percentile) Spec = 1.19 ft	SVA — Supplemental Vertical Accuracy (95th Percentile) Target = 1.19 ft
Total Combined	144		0.84	
BE & Low Grass	38	0.58		0.46
Brush & Low Trees	45			0.82
Forested	37			0.83
Urban	24			0.86

Fundamental and Consolidated Vertical Accuracy at 95% confidence level, using NDEP/ASPRS methodology:

The $RMSE_z$ in bare-earth and low grass was within the target criteria of 0.30 ft, and the FVA tested 0.58 ft at the 95% confidence level in open terrain, based on $RMSE_z$ x 1.9600.

Compared with the 1.19 ft specification, CVA tested 0.84 ft at the 95% confidence level in bare-earth and low grass, brush and low trees, forested, and urban areas combined, based on the 95th Percentile. Table 3 lists the 5% outliers larger than the 95th percentile error; whereas 5% of the points (7 points) could have exceeded the 1.19 ft criterion, only one point actually exceeded this criterion.

Table 3 — 5% Outliers Larger than 95th Percentile

<table>
<tr><th>Land Cover Category</th><th>Elevation Diff. (ft)</th><td rowspan="8">Only one point (TA021M11) exceeded the 1.19 ft 95th percentile criteria</td></tr>
<tr><td>Forested</td><td>1.20</td></tr>
<tr><td></td><td></td></tr>
<tr><td></td><td></td></tr>
<tr><td></td><td></td></tr>
<tr><td></td><td></td></tr>
<tr><td></td><td></td></tr>
<tr><td></td><td></td></tr>
</table>

Compared with the 1.19 ft SVA target values, SVA tested 0..46 ft at the 95% confidence level in bare-earth and low grass; 0.82 ft in brush and low trees; 0.83 ft in forested areas; and 0.86 ft in urban areas, based on the 95th Percentile. Each of the four land cover categories were well within the target value of 1.19 ft.

Figure 2 illustrates the SVA by specific land cover category.

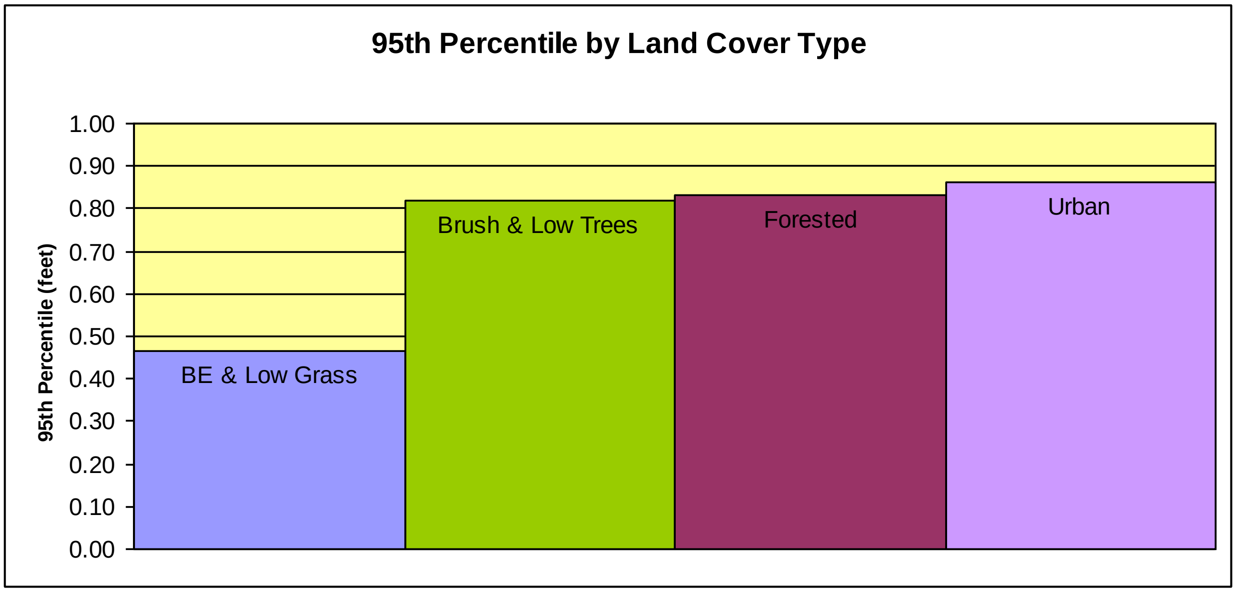


Figure 2 — Graph of SVA Values by Land Cover

Figure 3 illustrates the magnitude of the differences between the QA/QC checkpoints and LiDAR data by specific land cover category and sorted from lowest to highest. This shows a normal distribution of points in brush and low grass. All other land cover classifications indicate a negative skew.

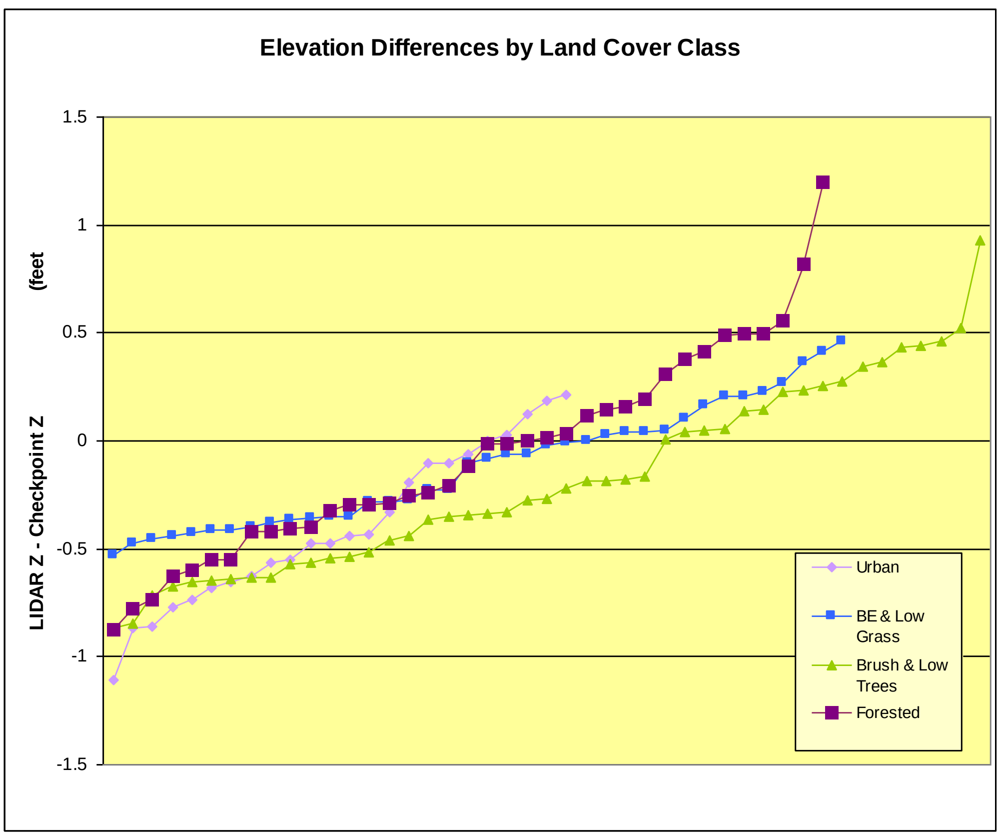


Figure 3 – Magnitude of Elevation Discrepancies, Sorted from Largest Negative to Largest Positive

The NSSDA and FEMA guidelines were both published before it was recognized that LiDAR errors do not always follow a normal error distribution. Future changes to these FGDC and FEMA documents are expected to follow the lead of the NDEP and ASPRS. Nevertheless, to comply with FEMA's current guidelines in Reference C, $RMSE_z$ statistics were computed in all four land cover categories, individually and combined, as well as other statistics that FEMA recommends to help identify any unusual characteristics in the LiDAR data. These statistics are summarized in Figures 4 and 5 and Table 4 below, consistent with Section A.8.6.3 of Reference C.

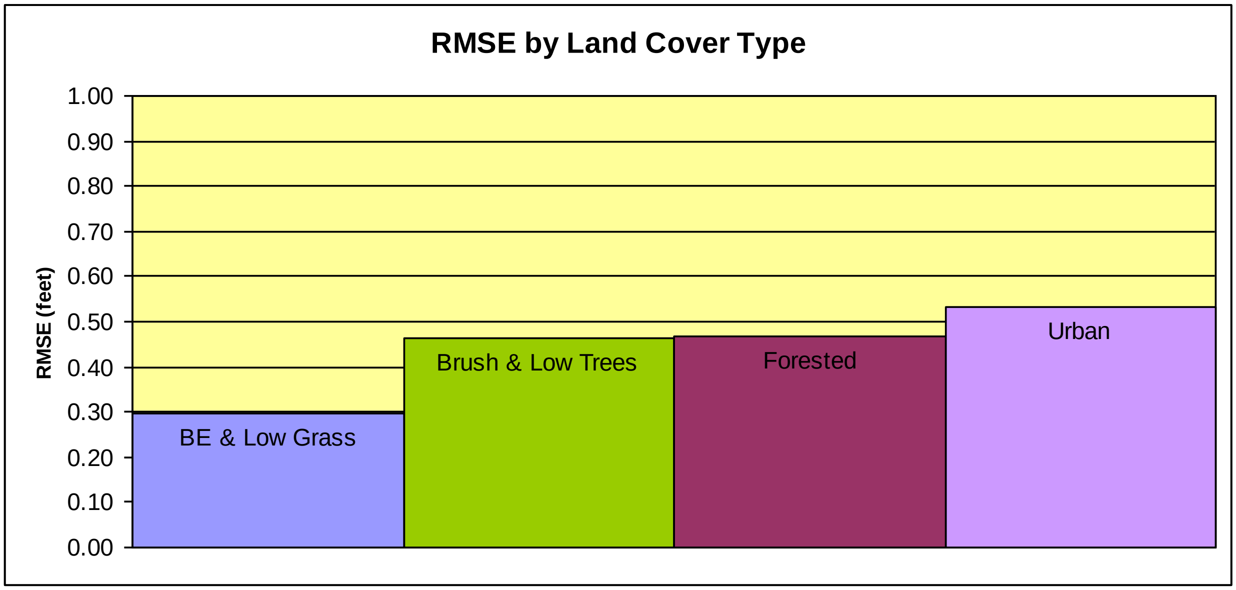


Figure 4 — $RMSE_z$ statistics by Land Cover Category

Table 4 — Overall Descriptive Statistics by Land Cover Category and Consolidated

Descriptive Statistics							
Land Cover Category	**Points**	**RMSE (feet)**	**Mean Error (feet)**	**Median Error (feet)**	**SKEW**	**STDEV (feet)**	**95th Percentile (feet)**
Consolidated	144	0.44	-0.17	-0.23	0.43	0.41	0.84
BE & Low Grass	38	0.30	-0.12	-0.09	0.38	0.28	0.46
Brush & Low Trees	45	0.46	-0.18	-0.27	0.47	0.43	0.82
Forested	37	0.47	-0.07	-0.12	0.54	0.47	0.83
Urban	24	0.53	-0.39	-0.46	0.07	0.37	0.86

Fundamental and Consolidated Vertical Accuracy at 95% confidence level, using NSSDA/FEMA methodology:

Although the NSSDA and FEMA guidelines predated FVA and CVA terminology, vertical accuracy at the 95% confidence level (called $Accuracy_z$) is computed by the formula $RMSE_z$ x 1.9600. $Accuracy_z$ in open terrain = 0.30 ft x 1.9600 = 0.58 ft, satisfying the 0.60 ft FVA standard. $Accuracy_z$ in consolidated categories = 0.44 ft x 1.9600 = 0.86 ft, satisfying the 1.19 ft CVA standard.

Figure 5 illustrates a histogram of the associated elevation discrepancies between the QA/QC checkpoints and elevations interpolated from the LiDAR triangulated irregular network (TIN). The frequency shows the number of discrepancies within each band of elevation differences. Although the discrepancies vary between a low of --1.11 ft and a high of +1.20 ft, the histogram shows that the majority of the discrepancies are skewed on the negative side of what would be a “bell curve,” with mean of zero, if the data were truly normally distributed. Typically the discrepancies tend to skew a bit more to the positive side, because discrepancies in vegetation are typically positive. The negative skew difference in this case, though minor, may indicate a slight systematic error. However they could also be influenced by the addition of 8 ortho checkpoints that were added to the urban classification, as these points are all on dark pavement which has a tendency to produce minor negative values due to light absorption. We saw no cause for concern, based on the fact that the majority of checkpoints were well within the vertical accuracy criterion.

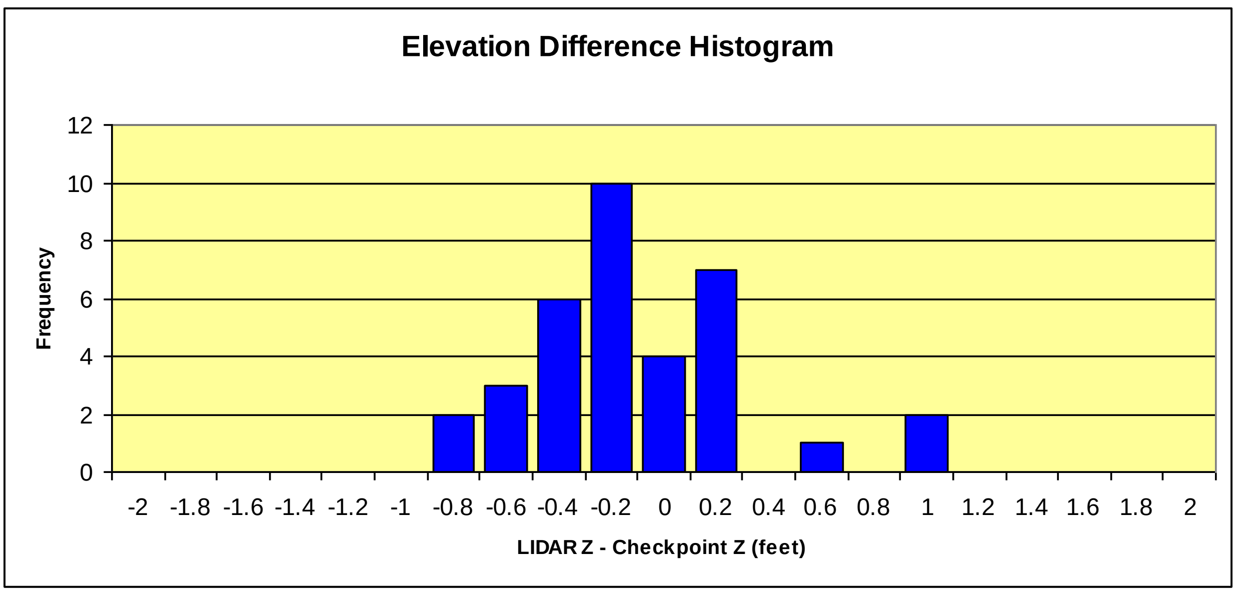


Figure 5 — Histogram of Elevation Discrepancies within 0.10 m Bands

Checkpoints That Were Not Used

Many of the Category 1, bare-earth and low grass, checkpoints were located on dirt roads and just adjacent to dirt roads. Typically these point locations do not make good Category 1 checkpoints, as they are often too close to road side drainage ditches that cause abrupt changes on the terrain surface, which would require breaklines. Additionally, the dirt/sand roads that receive the heaviest usage also receive the most frequent maintenance in the form adding material and/or grading. Thus there is always a question of doubt as to whether to road condition remained identical during the 1-2 month lag between LiDAR acquisition and check point surveys. Figures 6 – 16 show a total of 11 Category 1 checkpoints did not meet the location criterion for bare-earth/low grass:

The points in Figures 6 - 10, which were classified as CAT 1, did not meet the location specification for bare-earth and low grass – these points were reclassified as CAT 2 points and were used in the vertical accuracy assessment:

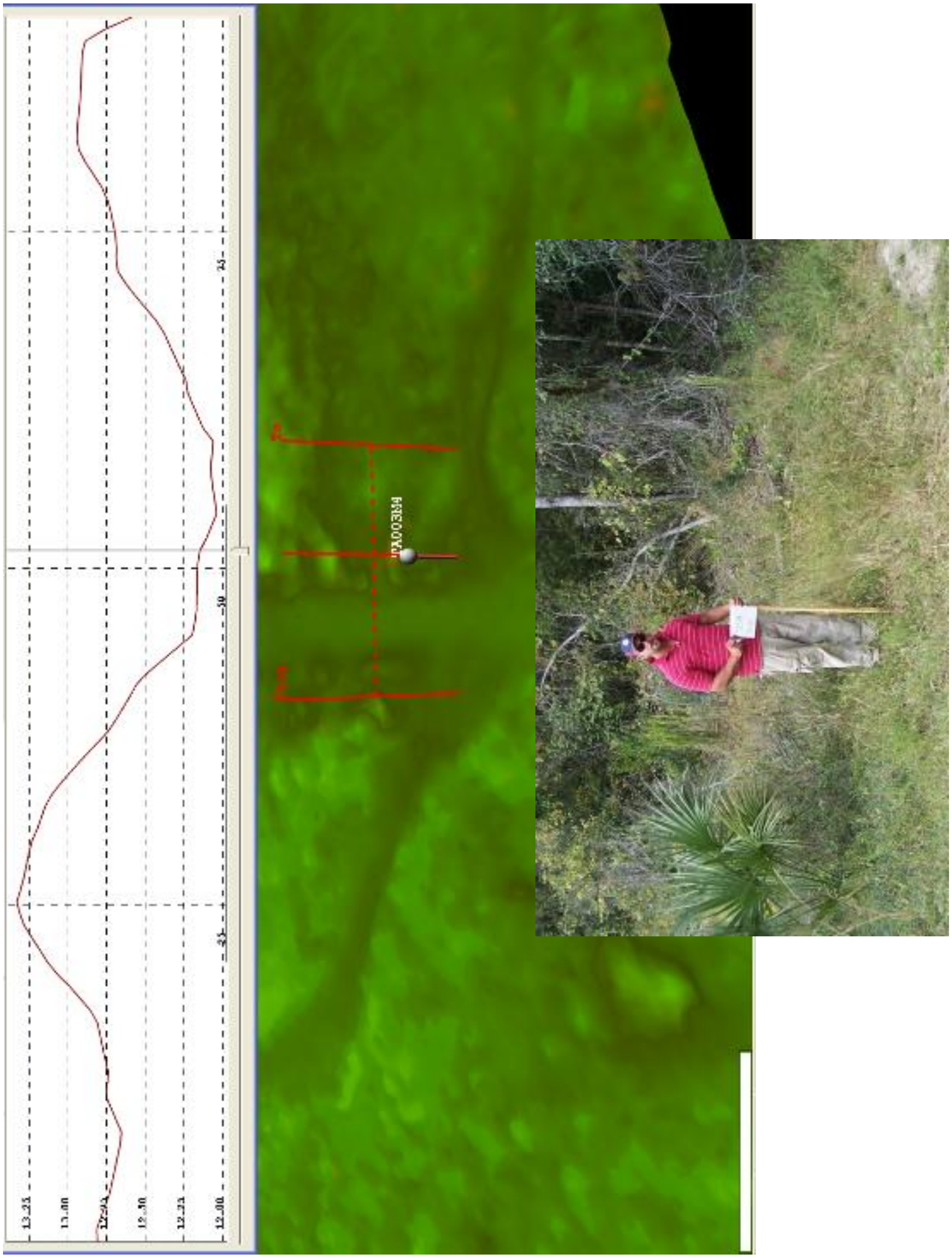


Figure 6 – TA003M4, Uneven Ground and High Grass, Reclassified to Category 2

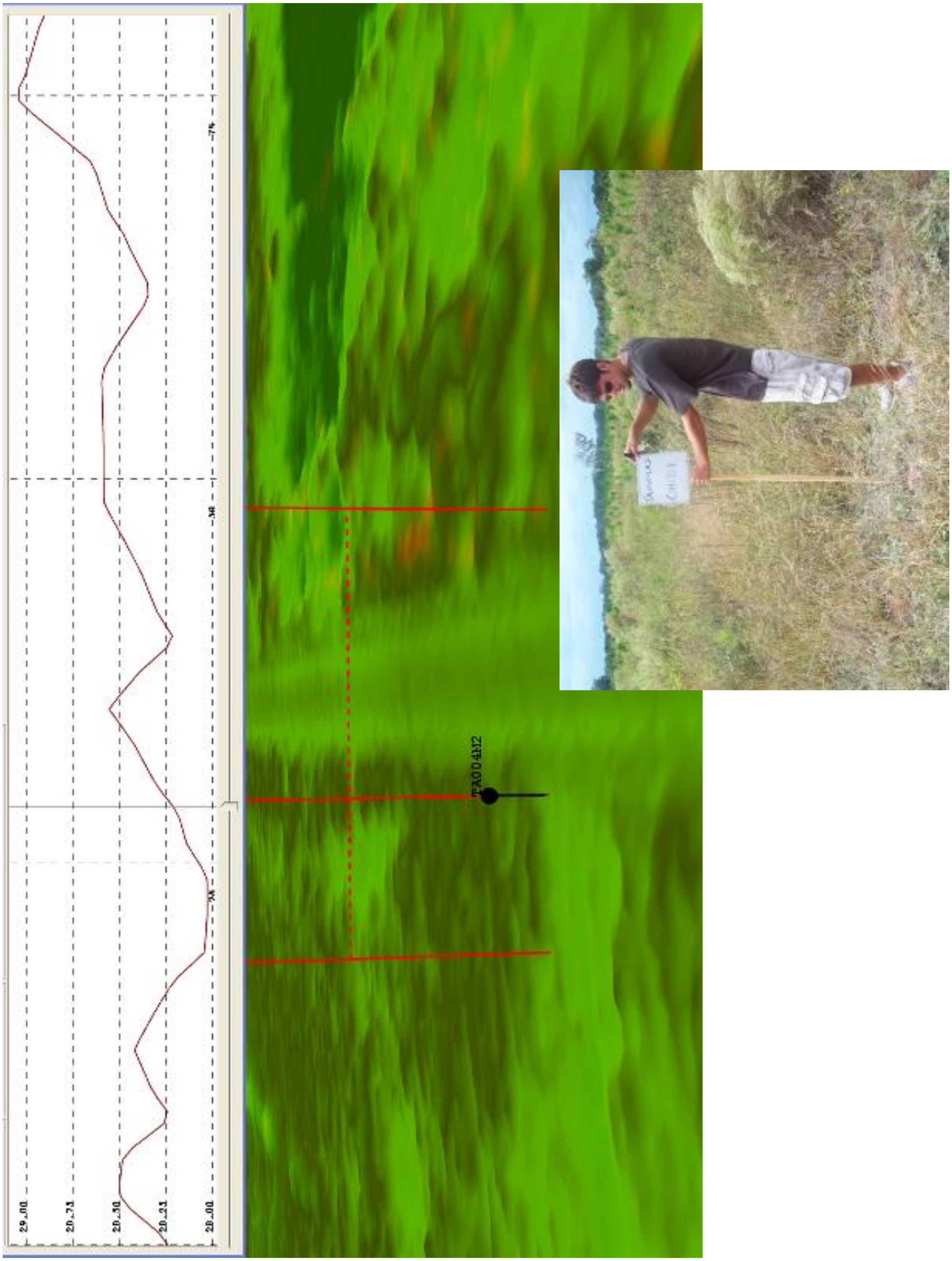


Figure 7 – TA004A2, High Grass, Reclassified to Category 2

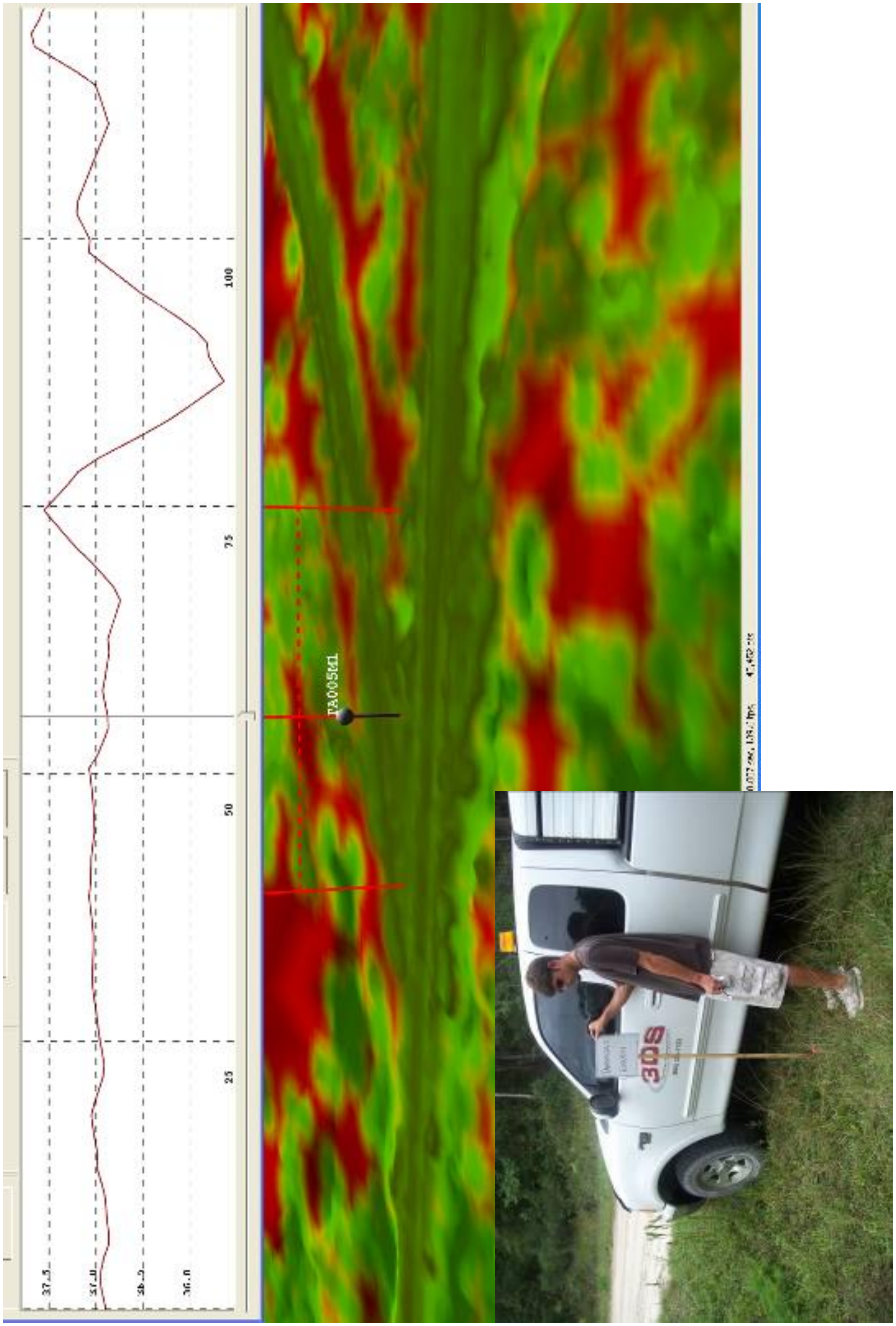


Figure 8 — Checkpoint TA005M1, Uneven Terrain, Reclassified to CAT 2

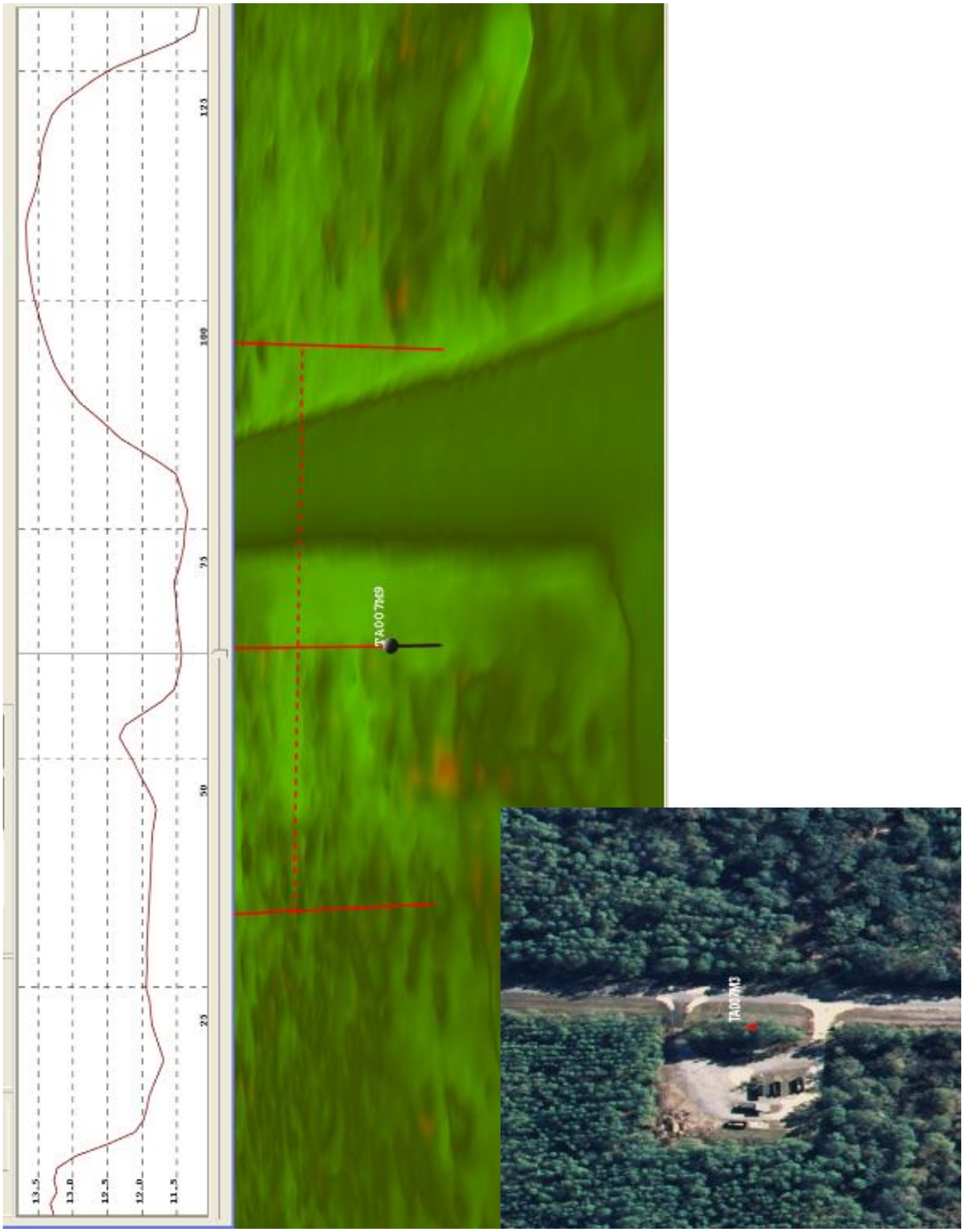


Figure 9 – TA007M9, Uneven Terrain, Reclassified to Category 2

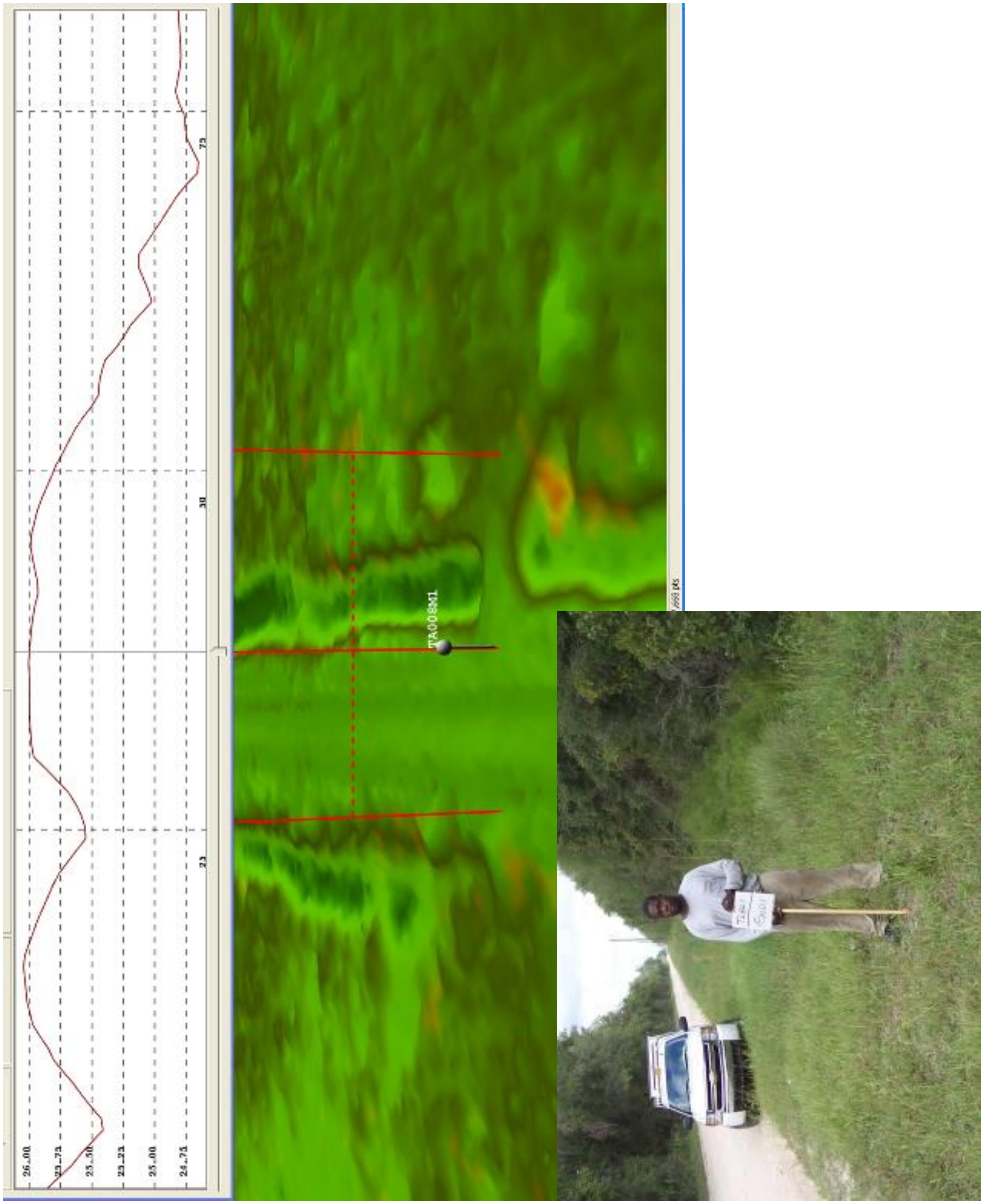


Figure 10 - TA008M1, High Grass, Reclassified to Category 2

The points in Figures 11 - 16, which were classified as CAT 1, were located on dirt/sand roads and did not meet the location specification for bare-earth and low grass – these points were not used in the vertical accuracy assessment:

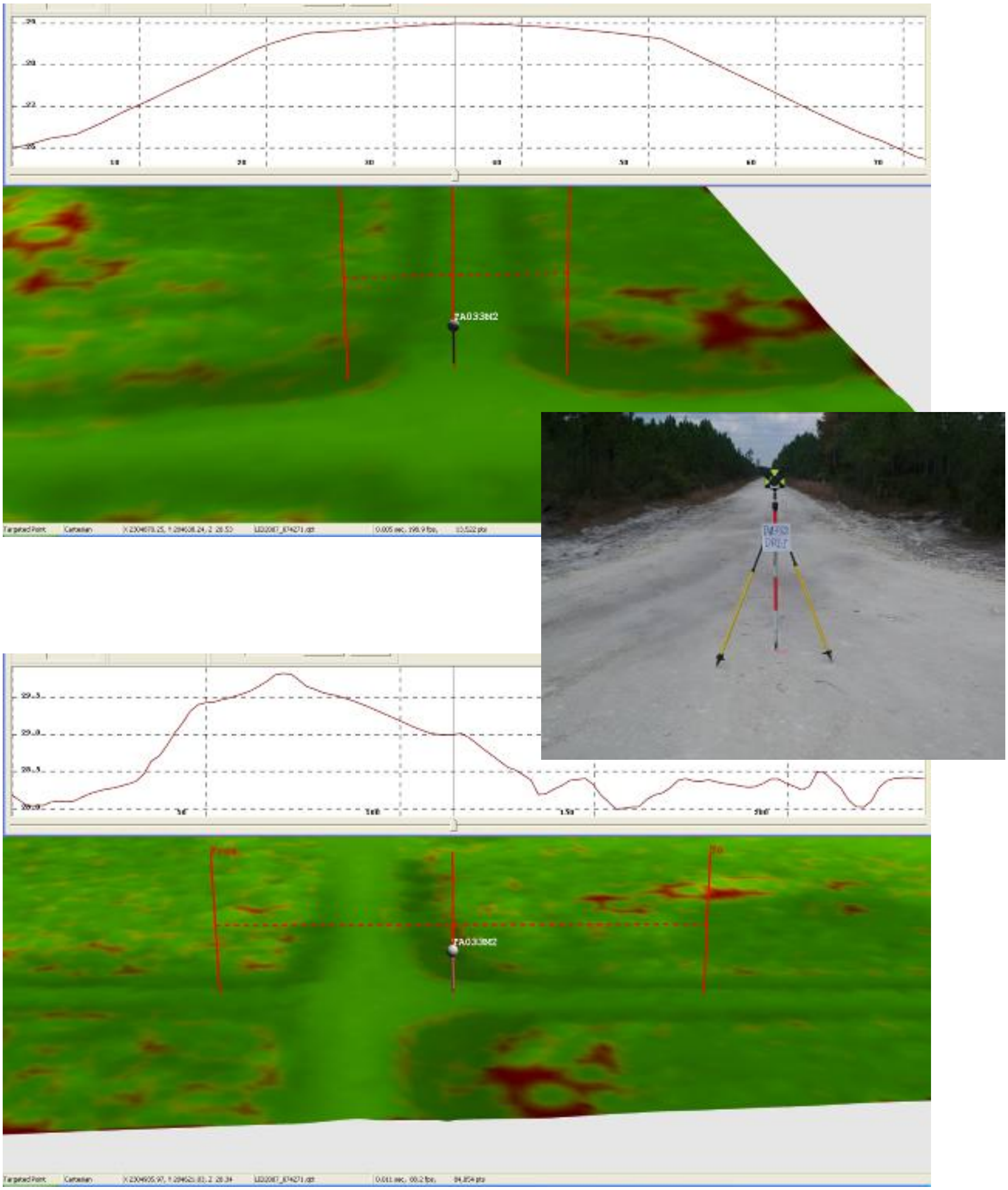


Figure 11 – TA033M2, Uneven Terrain, Not Used

Figure 12 — Checkpoint TA003M8, Uneven Terrain and High Weeds Either Side of Road, Not Used

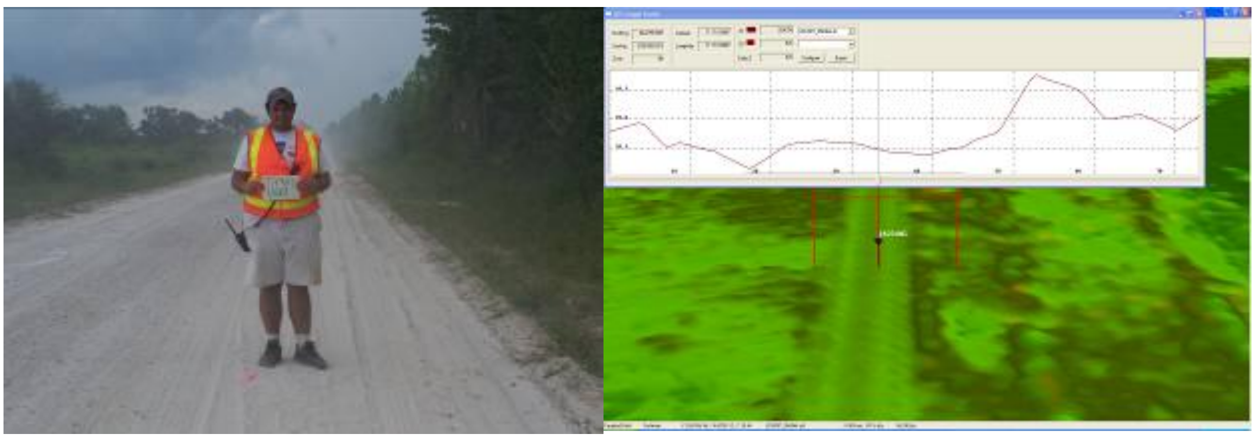


Figure 13 — Checkpoint TA004M1, Uneven Terrain, Not Used

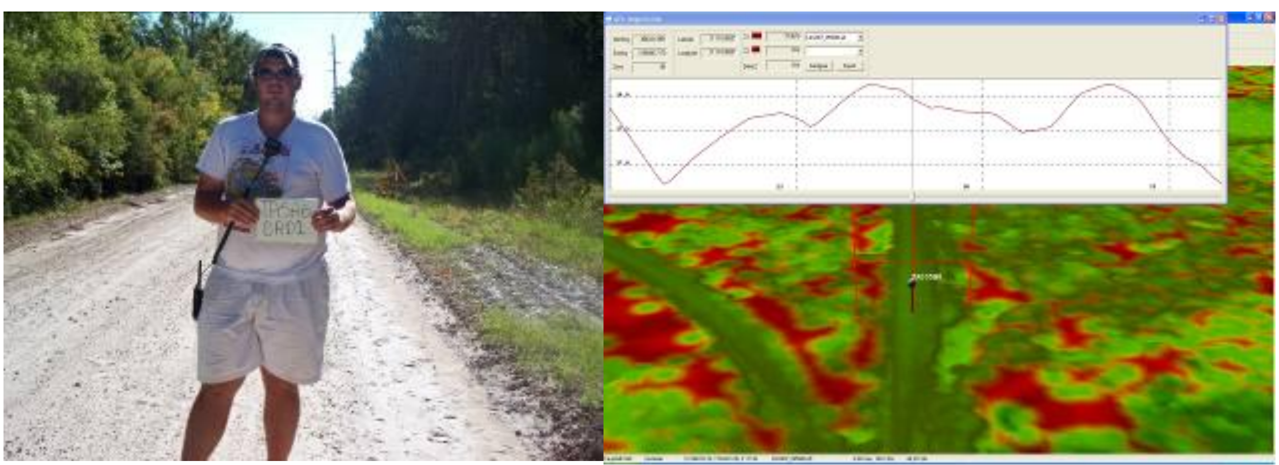


Figure 14 — Checkpoint TA005M6, Uneven Terrain, Not Used

Figure 15 — Checkpoint TA009M6, Uneven Terrain, Not Used

Figure 16 — Checkpoint TA013M5, Uneven Terrain and Trees on Either Edge of Road, Not Used

Conclusions

Based on the vertical accuracy testing conducted by PDS, the undersigned certifies that the LiDAR dataset for Taylor County, Florida satisfies the criteria established by Reference A:

- **Based on NSSDA, FEMA, NDEP and ASPRS methodology: Tested 0.58' vertical accuracy at 95% confidence level in open terrain.**

- **Based on NSSDA, FEMA, NDEP and ASPRS methodology: Tested 0.84' vertical accuracy at 95% confidence level in all land cover categories combined.**

David F. Maune, Ph.D., PSM, PS, GS, CP
QA/QC Manager

Appendix G: LiDAR Qualitative Assessment Report

References:

A ─ State of Florida Division of Emergency Management (FDEM), Contract Number 07-HS-34-14-00-22-469, Task Order Number 20070525-492718a

B ─ Part 3: *National Standard for Spatial Data Accuracy (NSSDA)*, "Geospatial Positioning Accuracy Standards," published by the Federal Geographic Data Committee (FGDC), 1998

C ─ Appendix A, *Guidance for Aerial Mapping and Surveying*, "Guidelines and Specifications for Flood Hazard Mapping Partners," published by the Federal Emergency Management Agency (FEMA), April 2003

D ─ *Guidelines for Digital Elevation Data*, Version 1.0, published by the National Digital Elevation Program (NDEP), May 10, 2004

E ─ *ASPRS Guidelines, Vertical Accuracy Reporting for LiDAR Data*, published by the American Society for Photogrammetry and Remote Sensing (ASPRS), May 24, 2004

Qualitative Assessment

The PDS qualitative assessment utilizes a combination of statistical analysis and interpretative methodology to assess the quality of the data for a bare-earth digital terrain model (DTM). This process looks for anomalies in the data and also identifies areas where man-made structures or vegetation points may not have been classified properly to produce a bare-earth model. Overall the data are of good quality and should satisfy most users for an accurate bare-earth elevation data product.

Overview

Within this review of the LiDAR data, two fundamental questions were addressed:

- Did the LiDAR system perform to specifications?
- Did the vegetation removal process yield desirable results for the intended bare-earth terrain product?

Mapping standards today address the quality of data by quantitative methods. If the data are tested and found to be within the desired accuracy standard, then the data set is typically accepted. Now with the proliferation of LiDAR, new issues arise due to the vast amount of data. Unlike photogrammetrically-derived DEMs where point spacing can be eight meters or more, the nominal LiDAR point spacing for this project was 0.7 meters, and with the PDS team's 50% sidelap between flightlines, the nominal overall point density was designed to be approximately 4 points per square meter. The end result is that millions of elevation points are measured to a level of accuracy previously unseen for traditional, elevation mapping technologies, and vegetated areas are measured that would be nearly impossible to survey by other means. The downside is that with millions of points, the data set is statistically bound to have some errors both in the measurement process and in the artifact removal process.

As previously stated, the quantitative analysis addresses the quality of the data based on absolute accuracy. This accuracy is directly tied to the comparison of the discreet measurement of the survey checkpoints and that of the interpolated value within the three closest LiDAR points that constitute the vertices of a three-dimensional triangular face of the TIN. Therefore, the end result is that only a small sample of the LiDAR data is actually tested. However there is an increased level of confidence with LiDAR data due to the relative accuracy. This relative accuracy in turn is based on how well one LiDAR point "fits" in comparison to the next contiguous LiDAR measurement. Once the absolute and relative accuracy has been ascertained, the next stage is to address the cleanliness of the data for a bare-earth DTM.

By using survey checkpoints to compare the data, the absolute accuracy is verified, but this also allows us to understand if the artifact removal process was performed correctly. To reiterate the quantitative approach, if the LiDAR sensor operated correctly over open terrain areas, then it most likely operated correctly over the vegetated areas. This does not mean that the bare-earth was measured, but that the elevations surveyed are most likely accurate (including elevations of treetops, rooftops, etc.). In the event that the LiDAR pulse filtered through the vegetation and was able to measure the true surface (as well as measurements on the surrounding vegetation) then the level of accuracy of the vegetation removal process can be tested as a by-product.

To fully address the data for overall accuracy and quality, the level of cleanliness (or removal of above-ground artifacts) is paramount. Since there are currently no effective automated testing procedures to measure cleanliness, PDS employs a combination of statistical and visualization processes. This includes creating pseudo image products such as LiDAR orthos produced from the intensity returns, Triangular Irregular Network (TIN)'s, Digital Elevation Models (DEM) and 3-dimensional models. By creating multiple images and using overlay techniques, not only can potential errors be found, but the PDS team can also find where the data meets and exceeds expectations. This report will present representative examples where the LiDAR and post processing had issues as well as examples of where the LiDAR performed well.

Analysis

Process

PDS utilizes GeoCue software products as the primary geospatial process management system. GeoCue is a three tier, multi-user architecture that uses .NET technology from Microsoft. .NET technology provides the real-time notification system that updates users with real-time project status, regardless of who makes changes to project entities. GeoCue uses database technology for sorting project metadata. PDS uses Microsoft SQL Server as the database of choice.

The PDS qualitative assessment process flow for Taylor County, FL incorporated the following reviews:

1. *Statistical Analysis*- A statistical analysis routine was run on the .LAS files upon receipt to verify that the .LAS files met project specifications. This routine checked for the presence of Variable Length Records, verified .LAS classifications, verified header records for min/max x,y,z, and parsed the .LAS point file to confirm that the min/max x,y,z matched the header records. These statistics were run on the all-return point data set as well as the bare-earth point data set for every deliverable tile.
    a. All LAS files contained Variable Length Records with georeferencing information.
    b. All LiDAR points in the LAS files were classified in accordance with project specifications: Class 1 - Unclassified, Class 2 - Ground, Class 7 - Noise, and Class 9 - Water. No records were present in Class 12 - Overlap as Sanborn utilized all points in the overlap areas in the terrain files.
    c. Min/max x,y,z values matched the header files.

2. *Spatial Reference Checks*- The .LAS files were imported into the GeoCue processing environment. As part of the URS process workflow the GeoCue import produced a minimum bounding polygon for each data file. This minimum bounding polygon was one of the tools used in conjunction with the statistical analysis to verify spatial reference integrity. No issues were identified with the spatial referencing of this dataset.

3. *Data Void/ Gap Checks*-The imported .LAS files were used to create LiDAR “orthos”. The LiDAR orthos were one of the tools used to verify data coverage and point density, to check for data voids or gaps, and to use as reference data during checks for data anomalies and artifacts. This product is not intended to be a project deliverable. The orthos were derived from the Full Point Cloud elevations and LiDAR pulse return intensity values. The intensity values were used as delivered with no normalization applied. Due to the point density of the Florida Baseline Specifications, the orthos were produced at a 1.2m pixel for the entire area of interest (see Figure 1).

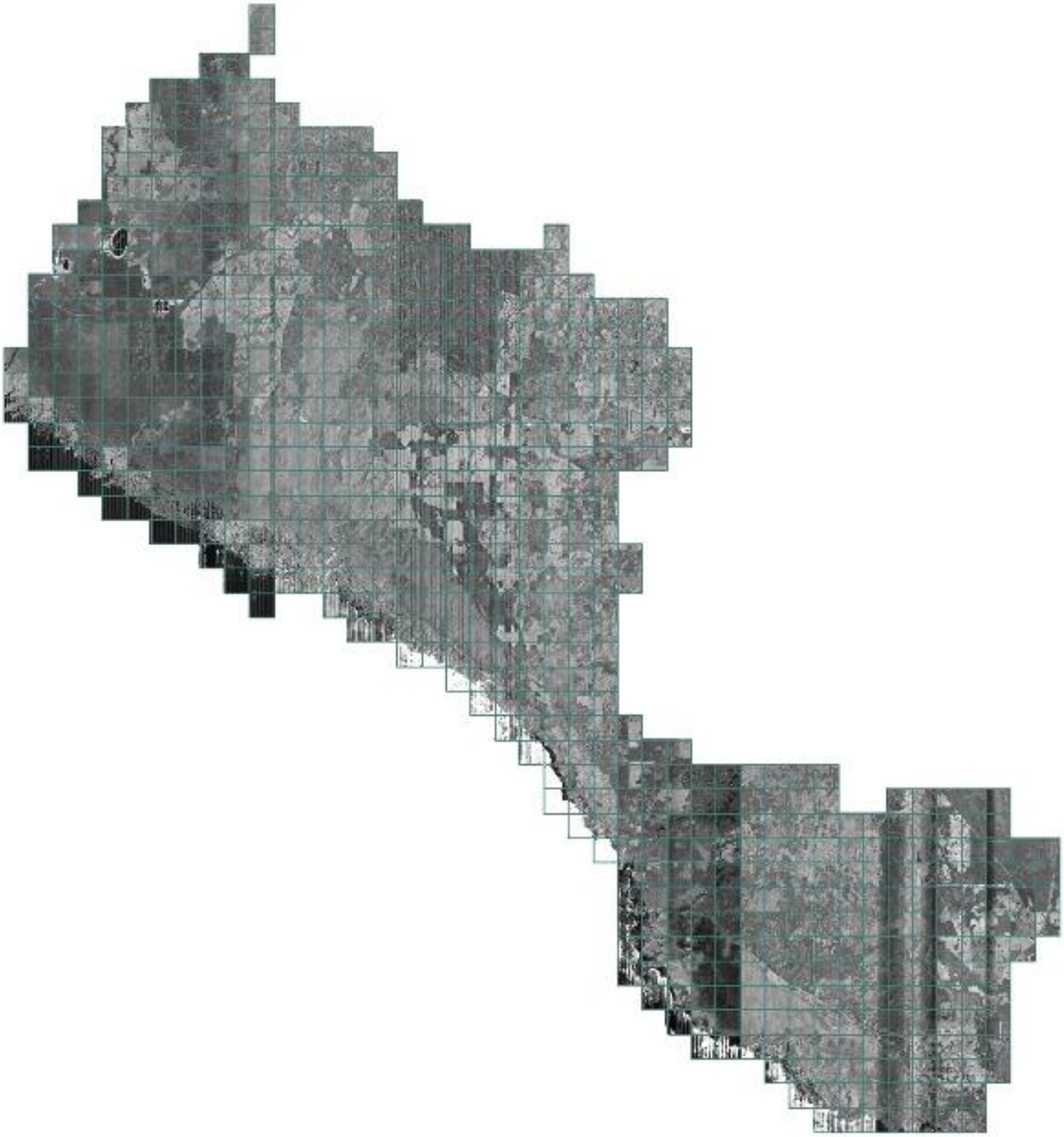


Figure 9 Screenshot of Taylor County LiDAR Orthos produced from Intensity Returns

Voids (areas with no LiDAR returns in the LAS files) that are present in the majority of LiDAR projects include voids caused by bodies of water. These are considered to be acceptable voids (Figure 2).

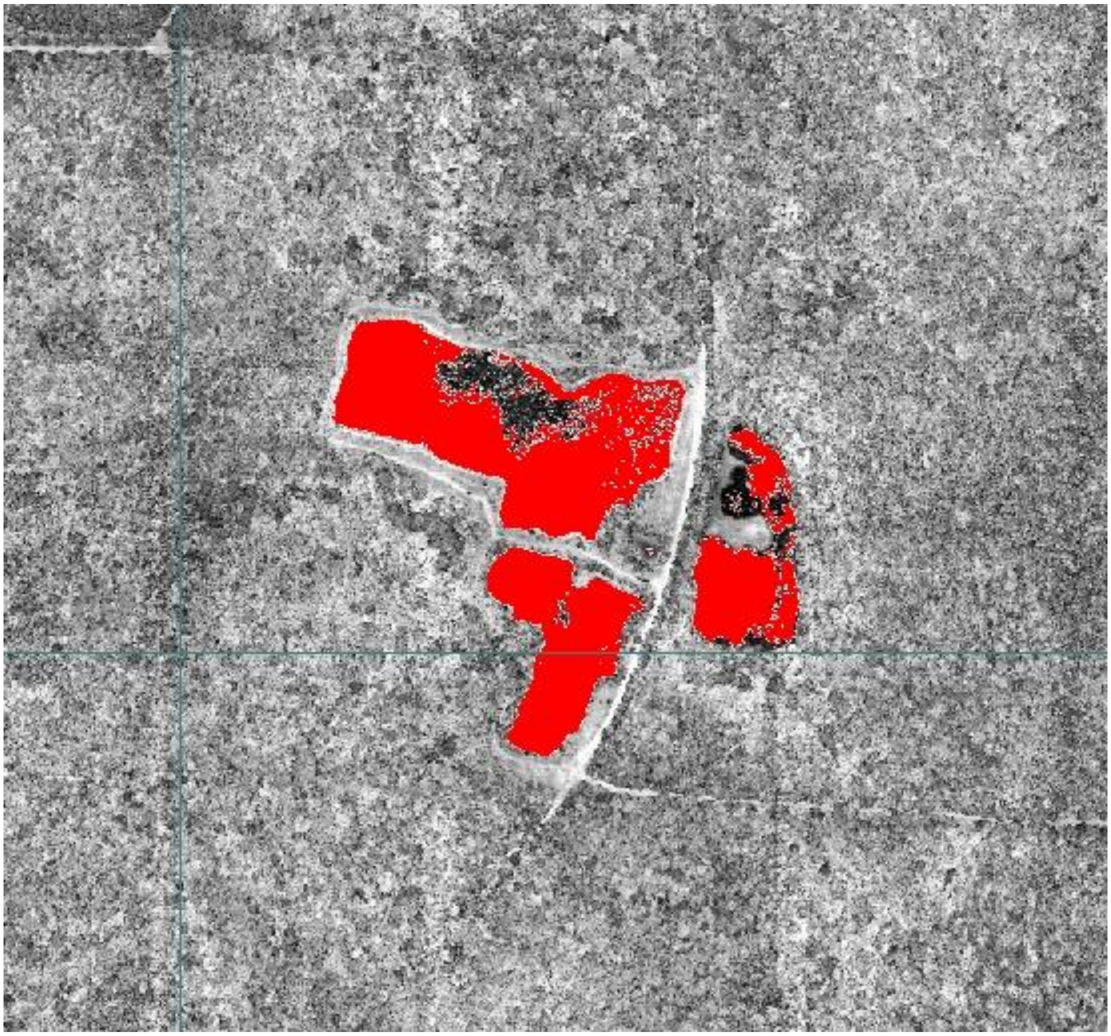


Figure 10 Acceptable voids in data due to water bodies

4. *Initial Data Verification:* PDS performs an initial 10% random check of the data delivery by looking at each tile individually in great detail utilizing TIN surfaces and profiles. If the data set passes the 10 % check, the tiles continue through the remaining QC work flow where every tile is reviewed. If the data set fails the 10% check it is normally due to a systematic process error and the data set is sent back to the vendor for correction. Upon receipt of the corrected tile/s the check is performed again to ensure that any flagged errors were corrected and additional issues were not inadvertently introduced during the corrective action.

5. *Data Density/Elevation checks:* The .LAS files are used to produce Digital Elevation Models using the commercial software package “QT Modeler” which creates a 3-dimensional data model derived from Class 2 (ground points) in the .LAS files. Grid spacing is based on the project density deliverable requirement for un-obscured areas. For the FDEM project it is stipulated that the maximum post spacing in un-obscured areas should not exceed 1.2m.

Model statistics were produced and characterized by density, scale, intensity, and elevation. (Figure 5) The low confidence area polygons were overlaid onto the density grids to ensure that all low confidence areas were properly identified with a polygon. As with the LiDAR orthos, this product was produced for Quality Assessment purposes only.

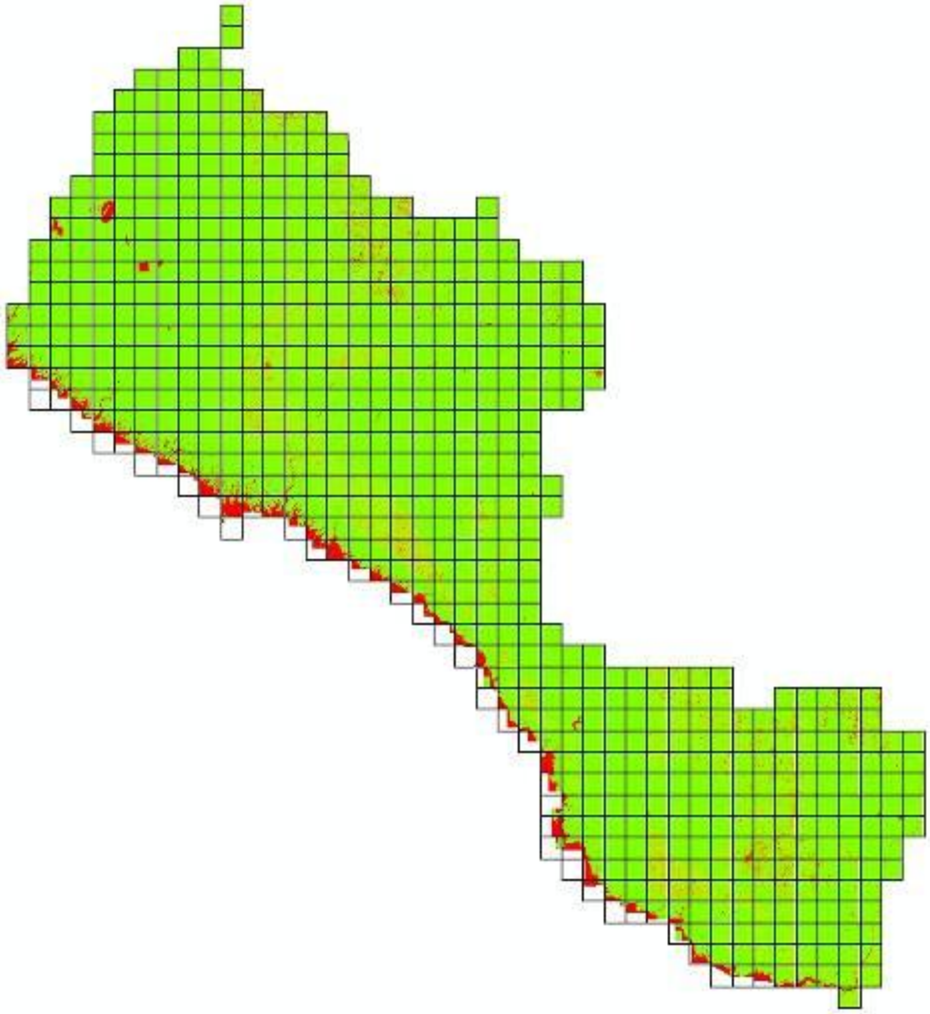


Figure 11 Density grid of Taylor County, created using a green to red color ramp. Green areas meet project specifications; red delineates areas not meeting minimum density requirements (primarily water and low-confidence areas)

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6. *Artifact Anomaly Checks.* The final step in the analysis was to review every tile for anomalies that may exist in the bare-earth terrain surface. Items that were checked include, but are not limited to: buildings, bridges, vegetation and water points classified as Class 2 points and elevation "steps" that may occur in the overlap between adjacent flight lines. Any issues found are addressed in the below "General comments and issues".

General comments and issues

The project area in Taylor County, Florida is predominantly rural. There is one significant Metropolitan incorporated area, the City of Perry. There is one State Park (Figure 6).

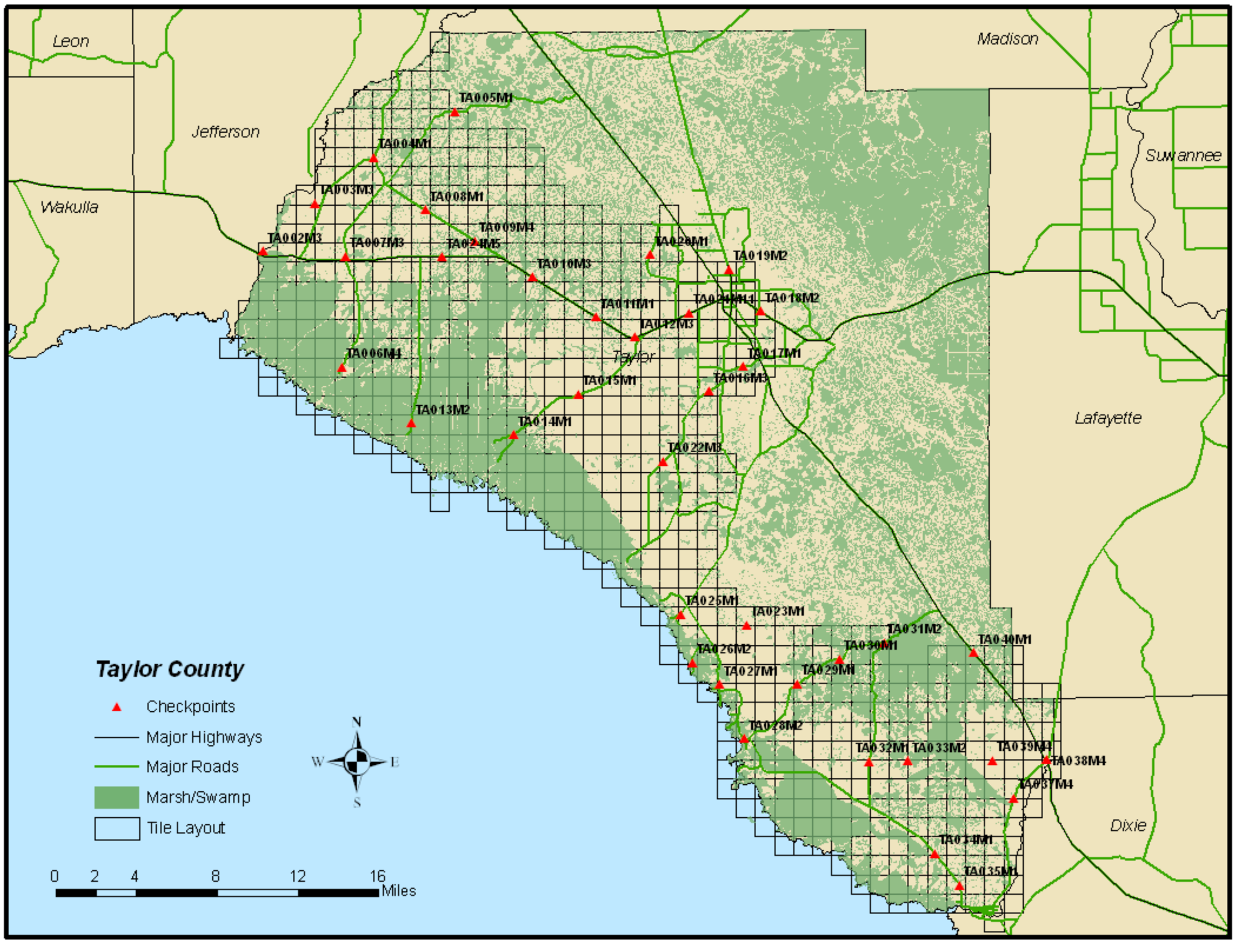

Figure 12 Map of Taylor County Florida with Marsh areas from Florida Geographic Data Library (FGDL)

The initial data acquisition was very dense. Overall the calculated maximum post spacing of all the Taylor County LAS files was .62m (2 feet), compared with the baseline specifications of 4 feet. In general, the bare earth ground surface was clear of artifacts and very clean. The algorithms used to classify the above-ground ground points were very stringent; given the overall physical characteristics of the county this does not seem inappropriate. There is a fine line in the decision-making process of which points to classify as ground. By removing points from the ground classification due to heavy vegetation there is risk of over-smoothing or “flattening” the ground surface which can have a greater impact than leaving points to maintain the ground surface model. In addition, due to the lack of significant elevation changes in the physical terrain there are places where there is no visible break in the terrain between the ground surface and what in traditional mapping would be considered a hard breakline feature, for example roads.

Because the project includes the collection of breaklines, this will be compensated for in the hard breakline collection. The LiDAR data contained sporadic issues such as artifacts or small anomalies which is typical of any LiDAR dataset. Due to the presence of dense vegetation throughout the county, the low confidence area polygons and breaklines are important deliverables for this particular county.

The bare earth terrain model was checked for consistency in bare earth processing, tile edge-match with neighboring tiles, flight line edge match, correct water classification and bridge, building and vegetation removal. There were some issues noted in the qualitative assessment but these were minor and repaired by the contractor. Of the 692 LAS files reviewed, some tiles were flagged for inconsistencies in filtering between adjacent tiles, culverts removed from the bare earth points that did not meet the criteria for removal, and for the improper classification of points in water bodies to the ground classification. The redelivery of the data was checked thoroughly and passed. The following table and associated screenshots is representative of the issues found in water bodies:

Points		
Tile	**Issue**	**Code**
LID 076430	Inconsistent filtering between tiles	Noted
LID 071570	Inconsistent filtering between tiles	Noted
LID 060208	Inconsistency in density between adjacent tiles	Noted
LID 073119	Culverts removed from bare earth classification	Corrected

In several areas inconsistencies in filtering we found between .LAS files that should have been homogenous in appearance (see Figures 7 - 9). This was likely due to differences in manual filtering processes. In addition, many culverts were inadvertently removed from a major highway feature (see Figure 10). These tiles were rejected and subsequently corrected by The Sanborn Map Company.

In addition, several tiles were found to contain ground points in water bodies, which was an issue that was more prevalent in areas of dense vegetation cover.

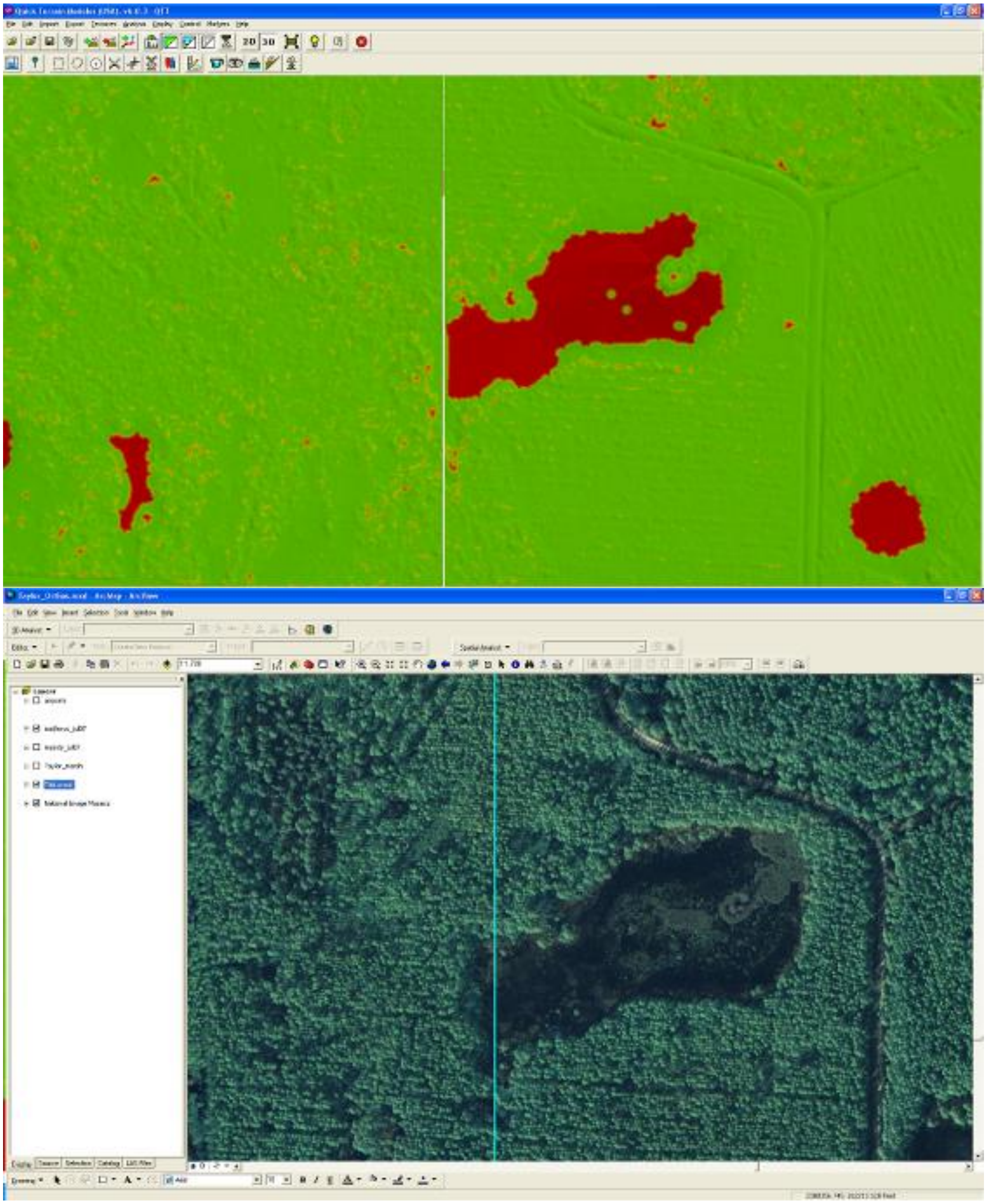

Figure 13 Tile 076430 – example of inconsistent filtering between tiles.

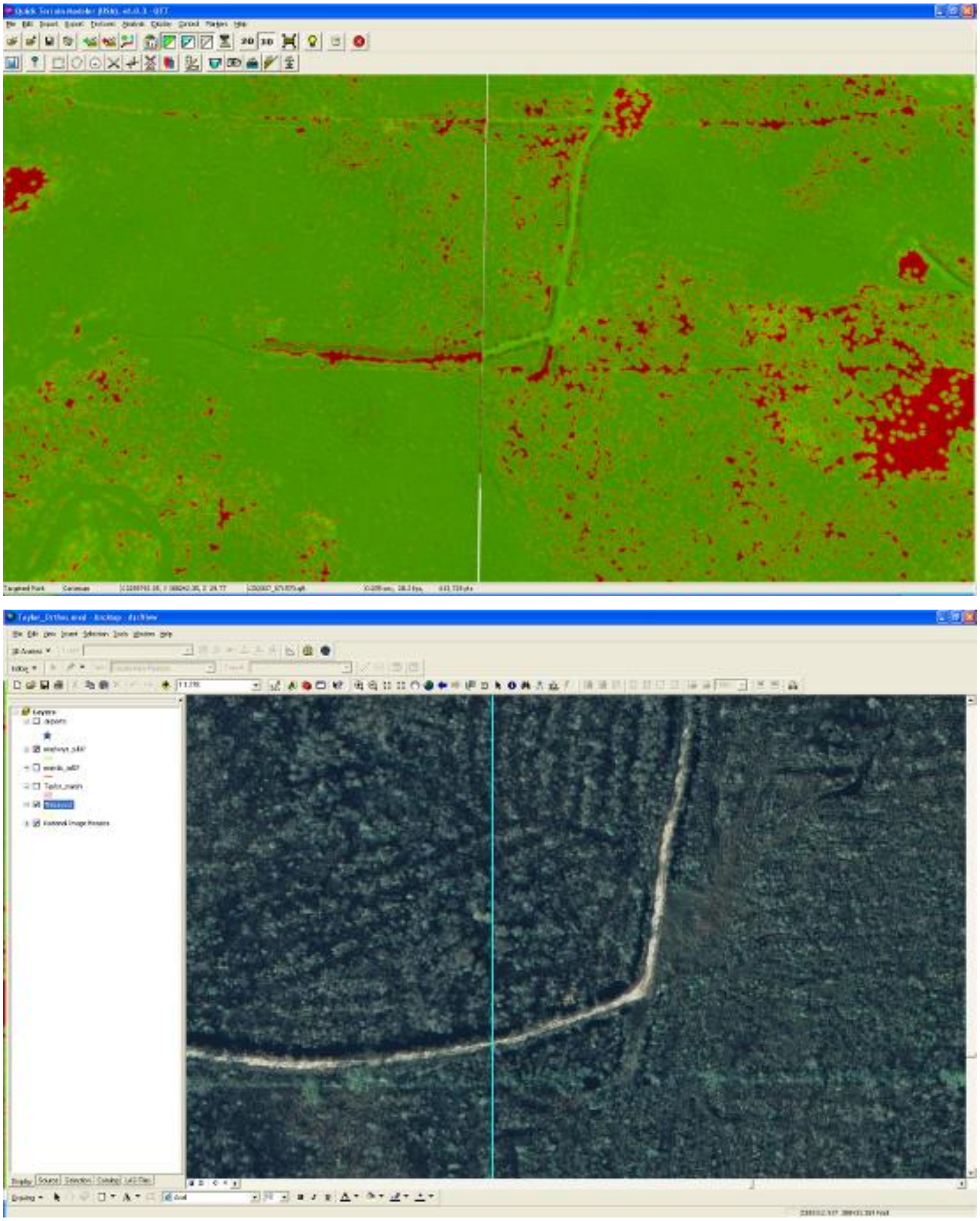

Figure 14 Tile 071570 – example of inconsistent filtering between tiles.

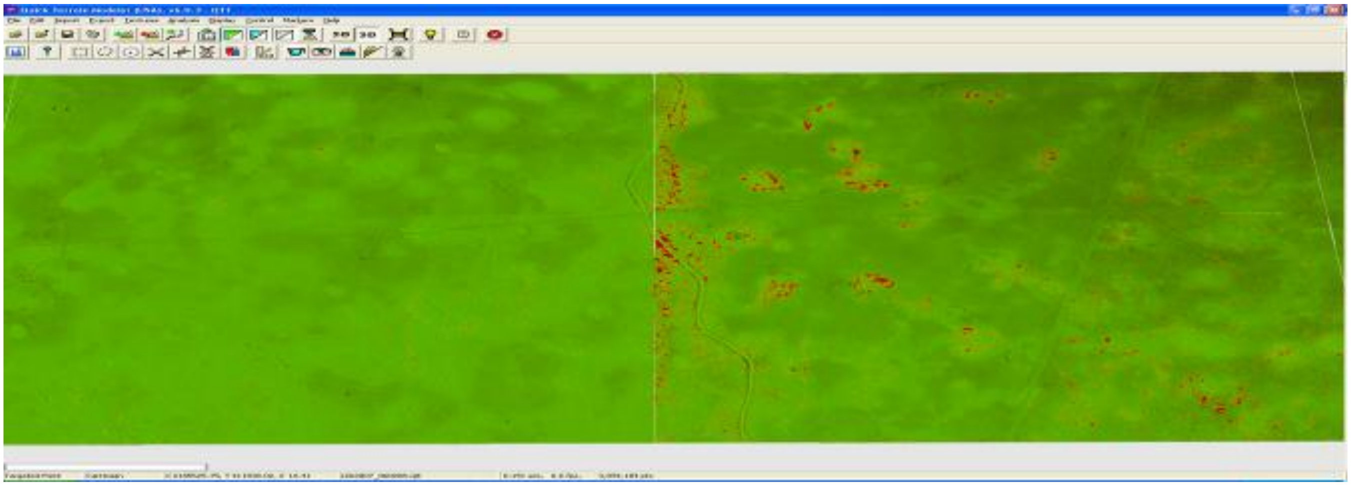

Figure 9 Tile 060208 – Example of inconsistency in density between tiles.

Figure 10 Tile 073119 – Culverts removed from bare earth classification

Intensity Streaks

Figure 11 is an example of a LiDAR intensity image, showing streaks over rivers and areas of standing water; such intensity streaks exist in LiDAR datasets nationwide. QA reviews identified the presence of anomalous LiDAR intensity values within the coastal regions of Taylor. The PDS team has reviewed the issue and while it was determined that the anomalies do not cause any of the datasets to fall short of the specifications of the project nor do they affect the overall integrity of the data, these anomalies have been corrected in the LAS data. This report documents the root cause, the geographic extent of the anomalies for this county, the geographic extent of areas exceeding the vertical specification of the contract expressed as % of the total county area, and modifications performed on the dataset to correct these anomalies.

Figure 11. LiDAR intensity streaks over water and marshy areas

Description of the Intensity Anomalies

Streaks caused by anomalous readings are most visible in the intensity image view of the affected LiDAR data. Each streak is characterized by high values that far exceed the normal range of values found in the surrounding data. In Figure 12, this anomaly is evident in both the overhead view and the profile of the area.

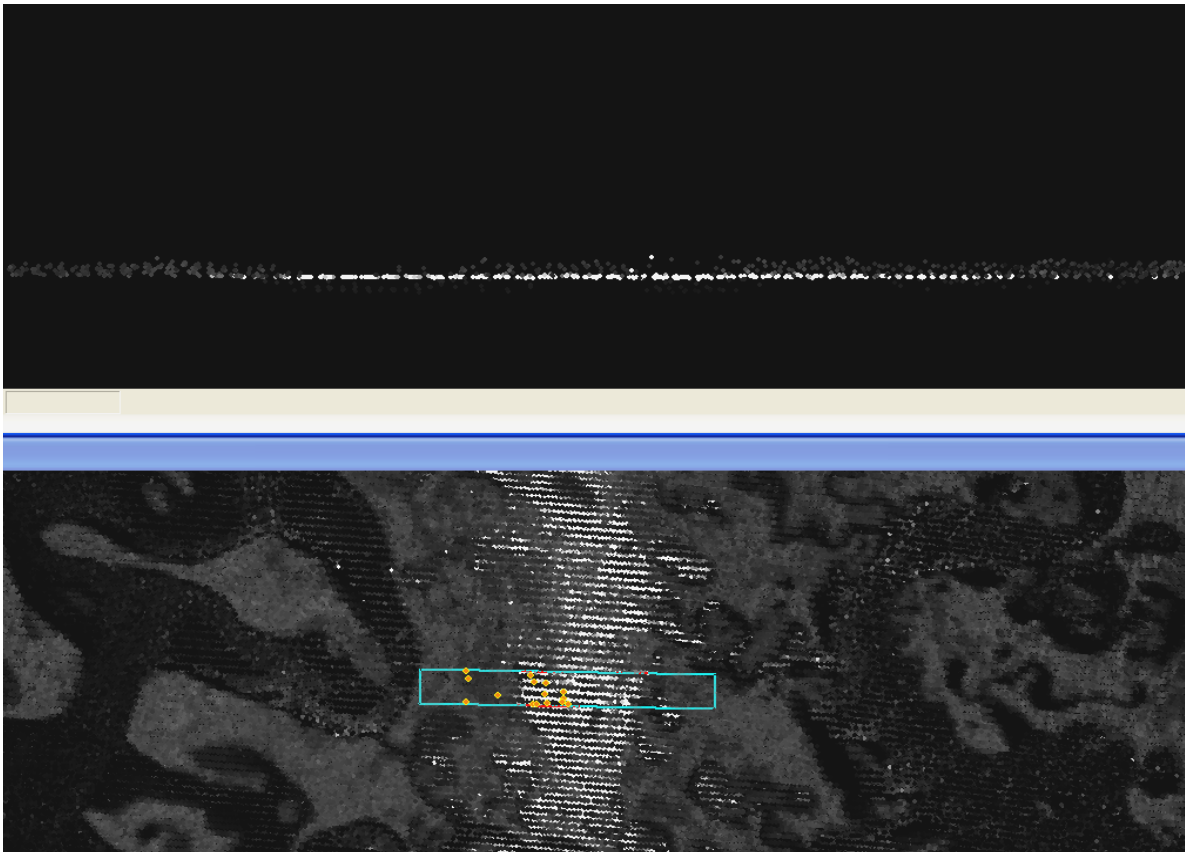

Figure 12 Profile of anomaly

The anomalous intensity values cause the elevation readings of the LiDAR points to be falsely depressed. This effect can be seen when generating a TIN using the Class 2 points in the area. In Figure 13, the elevation measurements are displayed over a cross section of a representative anomaly. The greatest error in elevation is located at the center of the anomaly with the elevations gradually rising up at the edges to meet "true" ground elevation. This screenshot is representative of the errors found.

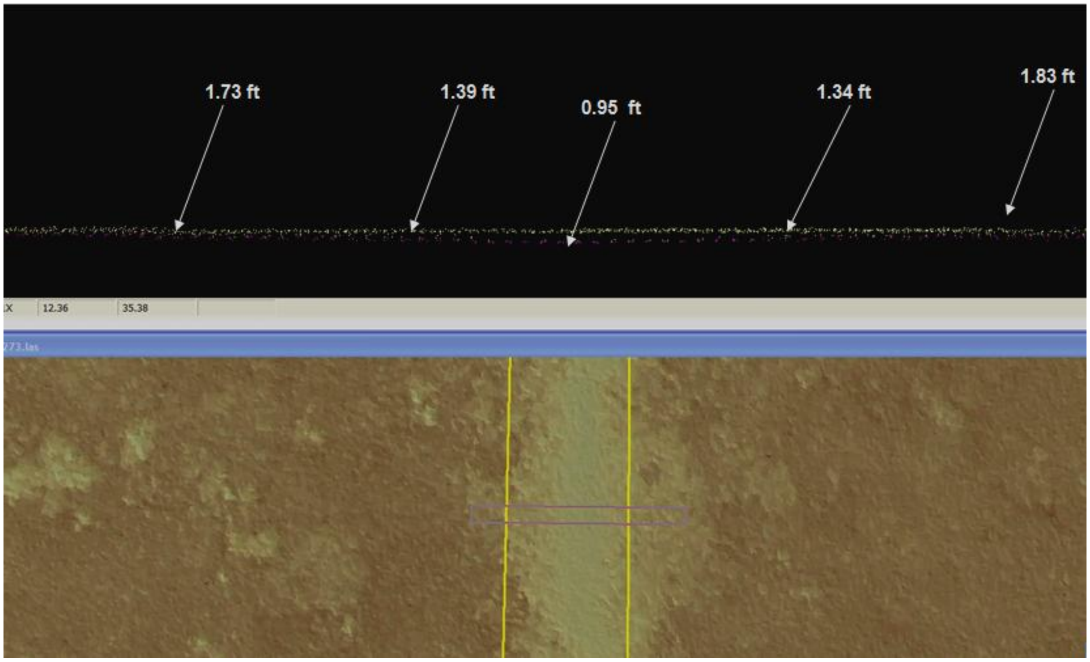

Figure 13 TIN and profile of anomaly

Figure 14 illustrates the connection between abnormally high intensity values and depressed elevation values within one of the anomalies. The highest intensity value is at the center of the anomaly with the values gradually decreasing until they are within a normal range at and beyond the edges of the anomaly.

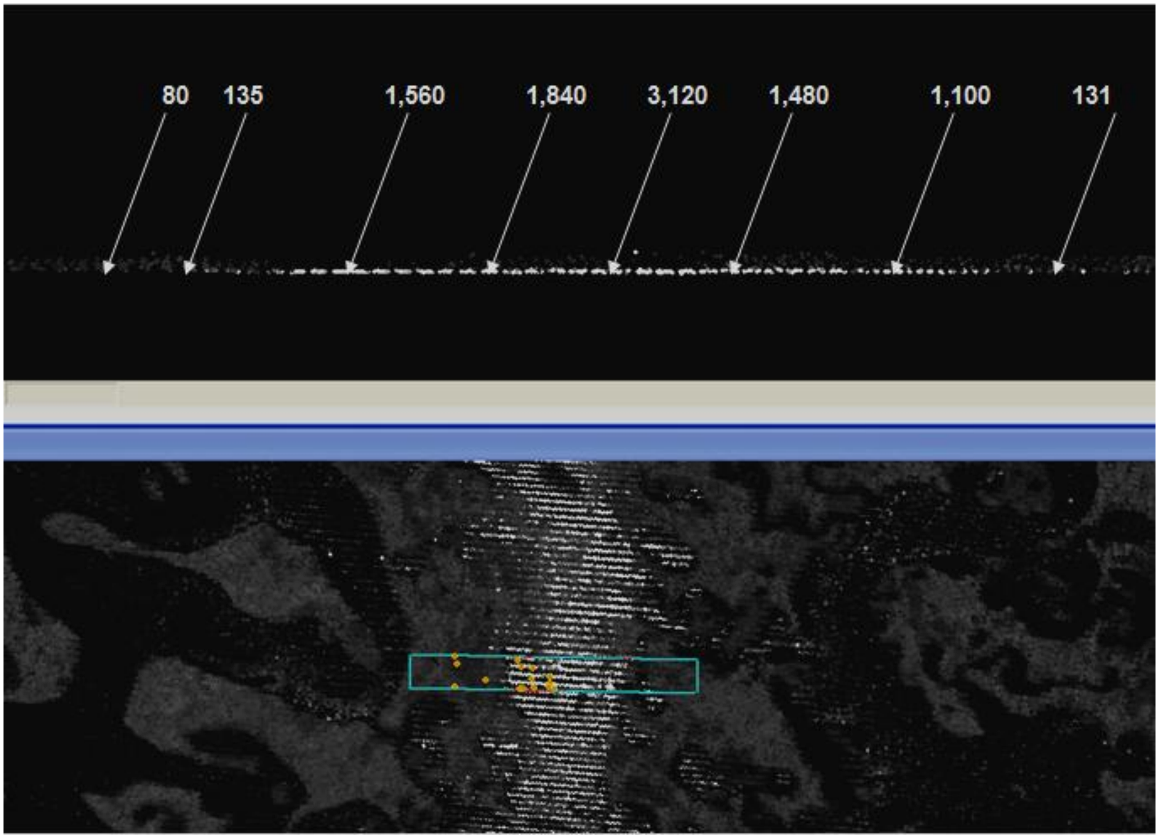

Figure 14 Cross section of anomaly with intensity values mapped

The following graphs (Figures 15-16) further demonstrate the correlation between the anomalous intensity values and falsely depressed elevations.

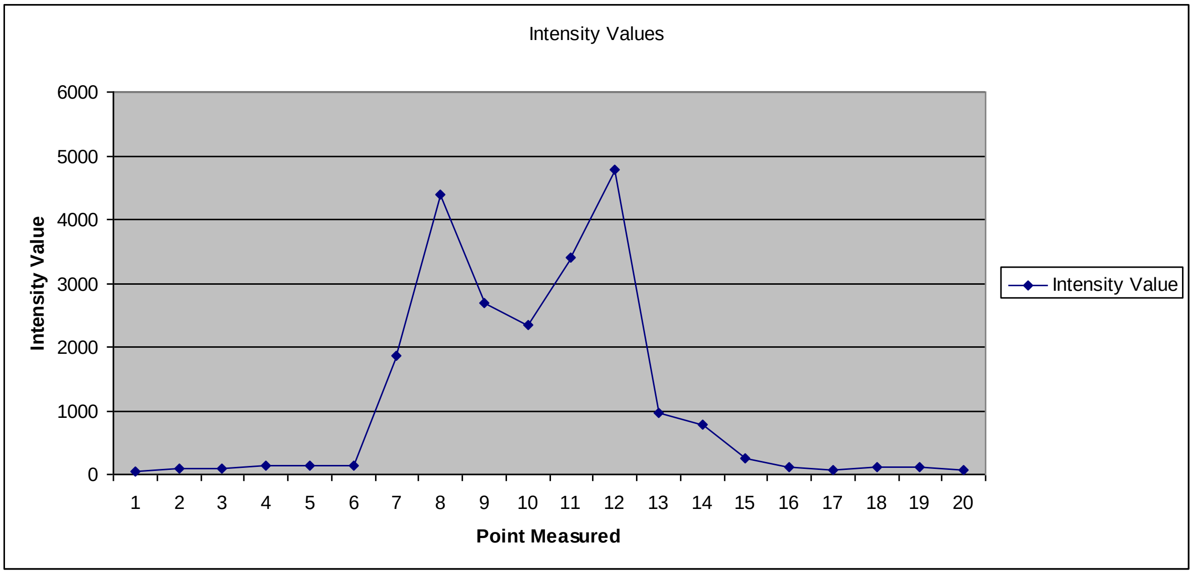

Figure 15 Graph of measured intensity values within profile of an anomaly

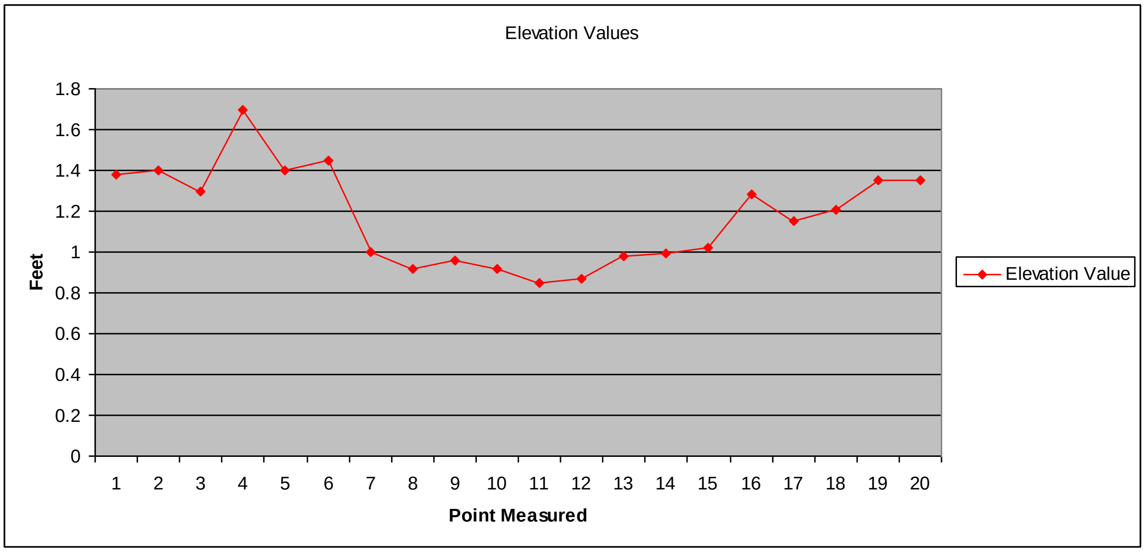

Figure 16 Graph of corresponding elevation values for points depicted in Figure 4

Root Causes of the LiDAR Intensity Anomalies

After careful review of the data by multiple experts on the PDS team, it was determined that two key factors contributed to the manifestation of the LiDAR intensity anomaly.

1. LiDAR sensors of a particular type from one manufacturer (Optech) has more intensity anomalies nationwide, while having lesser issues with other anomalies.
2. Standing and/or highly reflective bodies of water and ground saturated with water were present in all areas.

LiDAR vendors responsible for the aerial collection in multiple counties in Florida used Optech LiDAR sensors during the collection phase of the project. Because of this, the anomalies in such counties are similar in appearance and impact. The root causes apply to all counties affected by the anomaly.

The performance of any particular LiDAR sensor is greatly affected by the ability of the Automatic Gain Control (AGC) card to adjust to the strength of the reflected energy returning to the sensor. To ensure that the AGC card operates properly, manufacturers calibrate the cards to ensure optimal performance. In addition, there are basic settings to the AGC card that the aerial vendor can adjust based on the overall flight parameters of the collection.

Although the AGC cards are calibrated and settings for the cards are adjusted for specific flight parameters they typically cannot process energy levels that are well outside of the expected range. A parallel can be drawn to the effect that a highly reflective surface has on the production of an aerial image. Sun reflecting off of glass or water tends to create a flare or excessive brightness in an image over such locations.

When standing and/or highly-reflective water is present in the project area it can act as a reflector similar to a mirror; thus as a result pulses with an abnormally high strength are returned to the LiDAR sensor giving an intensity measurement that is significantly higher than expected. During the conversion and calibration of the LiDAR pulses into an LAS format, a standard correction from the sensor manufacturer is applied to all of the pulse returns of the data which adjusts the range of the pulse to compensate for normal high and low intensity levels. If the returning pulse has an abnormal intensity level the calibration software will apply an incorrect range adjustment to the pulse, potentially resulting in offset data.

The reason that the anomaly is more intense at nadir (directly below the sensor) is that pulses reflected at nadir have to travel a shorter distance and thus are stronger than pulses reflected back from points in the swath that are away from nadir.

This anomaly may occur throughout all areas that contain standing or highly-reflective water. In the case of this project, however, this issue occurs over a very small percentage of the project area. The extent and degree of the anomaly likely differs between various LiDAR sensors depending upon the design and manufacture.

Impact Assessment

An assessment of the impact of the anomaly on data quality was conducted by:

1. Creating extent polygons in a shape file to delineate the full extent of each intensity streak visible in the LiDAR intensity image or TIN
2. Taking representative cross sections along each intensity streak within the Class 2 points to measure elevations
3. Creating polygons within the extent polygon of each streak to delineate any areas that containing anomalous elevations greater than 1 foot from true elevation.
4. Using tools in ArcMap to calculate area coverage of any area exceeding the vertical accuracy threshold

The following results are reported from the Taylor County portion of the assessment:

1. Total land area affected by intensity anomalies – 2.16 sq. mi.
2. Total land area of anomalies exceeding a 1 foot error – 0.39 sq. mi.
3. Percentage of project area in Taylor County exceeding a 1 foot error due to intensity anomalies - ~0.037%
4. A location map is provided in Figure 17.

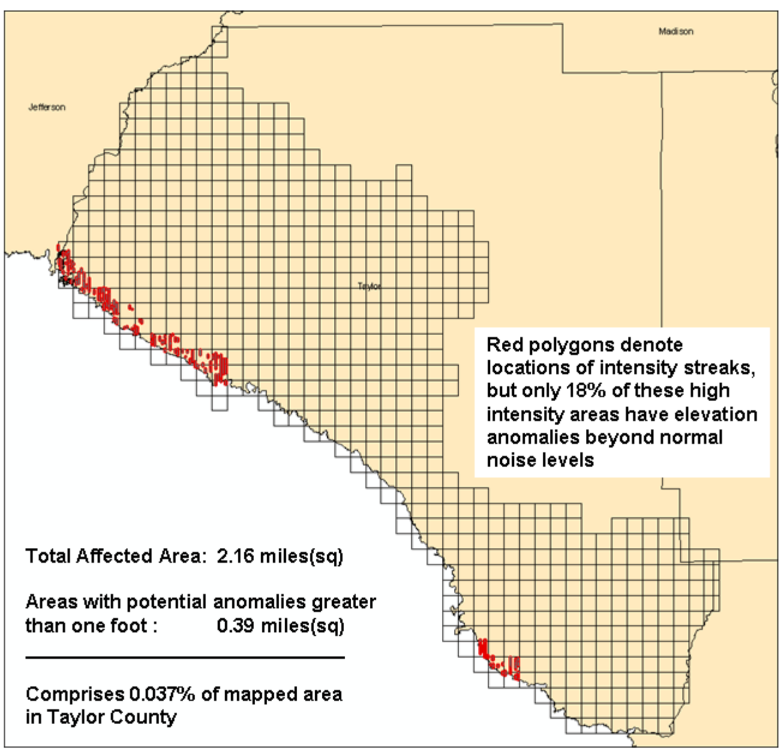

Figure 17 Overview of Taylor County

Vertical Accuracy Assessment

Given that the anomaly occurs predominantly in marsh land with significant amounts of water present, the most relevant land cover Category would be Category 2 or 3. Since the errors are not distributed normally the standard would be a 95% percentile (expected accuracy) within NDEP and ASPRS guidelines. Areas with potential anomalies greater than 1 foot are significantly less than the 5% allowable outliers under these guidelines.

If the errors were distributed normally, the percentage of allowable outliers would be 0.25% in accordance with a (3 x RMSEz) statistic. Even when applying this stricter specification and guideline to the anomalies the counties are still well within the 0.25% of allowable outliers.

Based on the qualitative assessment conducted by PDS, the impact of the LiDAR intensity anomaly on the overall quality of the LiDAR in this county is minimal and does not affect the overall integrity of the data set. All data affected by the anomaly are well within the acceptable percentage of vertical errors allowed by the project specifications.

Corrective Measures

While the data overall meets project specifications concerning vertical accuracy and usability of the data, these intensity anomalies are present in the data. In an effort to minimize the appearance of these anomalies in the data, LAS data were classified according to the following steps:

1. The polygons denoting areas with intensity anomalies were delivered to the vendors who produced the LAS data.
2. In areas highlighted by the area of interest (AOI) polygons, vendors reviewed the full point cloud data to compare the currently classified ground points with other points that could possibly represent a better ground classification.
3. In AOI's with sufficient flightline overlap across the entire anomaly, better ground points existed above the false depression ground points. In these cases the false depression ground points were re-classified to class 1, unclassified, and the higher elevated points representing the true ground were re-classified from class 1, unclassified, to class 2, ground.
4. In AOI's with insufficient flightline overlap across the entire anomaly, better ground points above the false depressions did not exist. In these cases the false depression ground points were still re-classified to class 1, unclassified. However, with no good ground points in existence, a gap in the ground class exists over these intensity anomalies so that any terrain modeling will essentially "TIN" across gaps, effectively removing the false depressions from the data.
5. To avoid any confusion that might arise from data users who would question why there were points located in class 1 that are lower than the ground classified points, PDS reclassified the points that had been originally moved from class 2 to class 1 into class 7, noise. These points were identified by locating points with elevations lower than a TIN

surface model of the currently classified ground layer. Of these low points, those with abnormally high intensity values were reclassified from class 1 to class 7.

Conclusion

Overall the data meets the project specifications. The classification of the raw point cloud to bare ground was executed well given the low terrain relief and areas of dense vegetation. The data did contain areas of improperly classified water points, and removed culverts; however these issues were corrected by The Sanborn Map Company and were not present in the redelivered data. There were areas noted as containing visible differences in the filtering from tile to tile however the filtering in these areas does meet project specifications. Small intensity anomalies corresponding to false depressions in the ground data were found in 2.16 sq. miles of the data. While these intensity anomalies and false depressions impacted a small geographic extent of the data, these anomalies could still visually be seen in the data. To effectively remove the false depressions from the bare-earth data, ground points representing the false depression were reclassified from class 2 to class 7 and "good" ground points were reclassified from class 1 to class 2 when present in overlap data.

Appendix H: Breakline/Contour Qualitative Assessment Report

Coastal Shorelines

Coastal shorelines are correctly captured as two-dimensional polygon features, extracted from the LiDAR data and not from digital orthophotos, except for manmade features with varying heights such as seawalls which are captured as three-dimensional breaklines. Coastal breaklines merge seamlessly with linear hydrographic features. Shorelines continue beneath docks and piers. There is no “stair-stepping” of coastal shorelines. Figure 1 shows example coastal breaklines and contours.

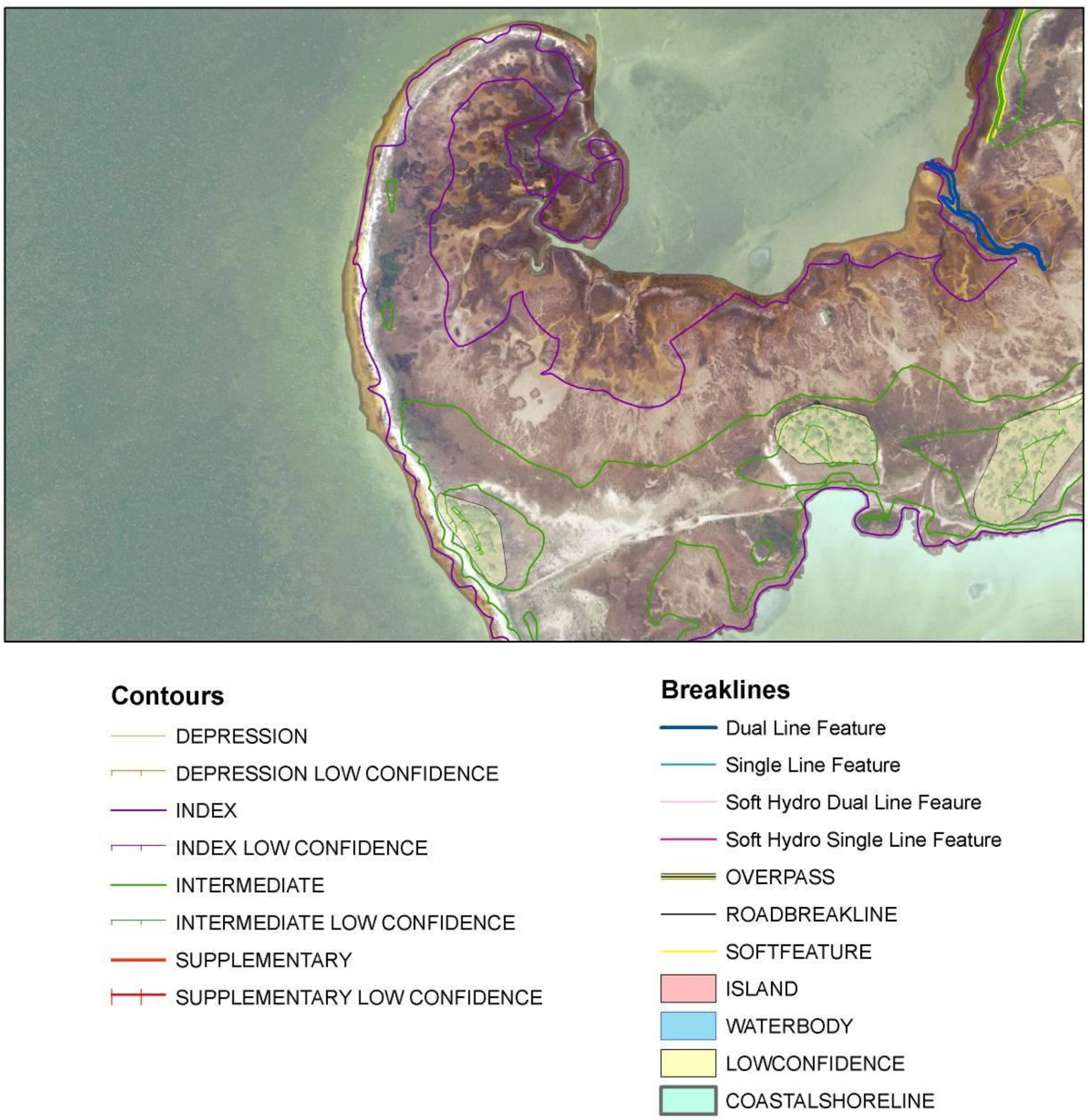

Figure 1. Example coastal breaklines and contours from tile #73227

Linear Hydrographic Features

Linear hydrographic features are correctly captured as three-dimensional breaklines – single line features if the average width is 8 feet or less and dual line features if the average width is greater than 8 feet. Each vertex maintains vertical integrity. Figure 2 shows example breaklines and contours of linear hydrographic features.

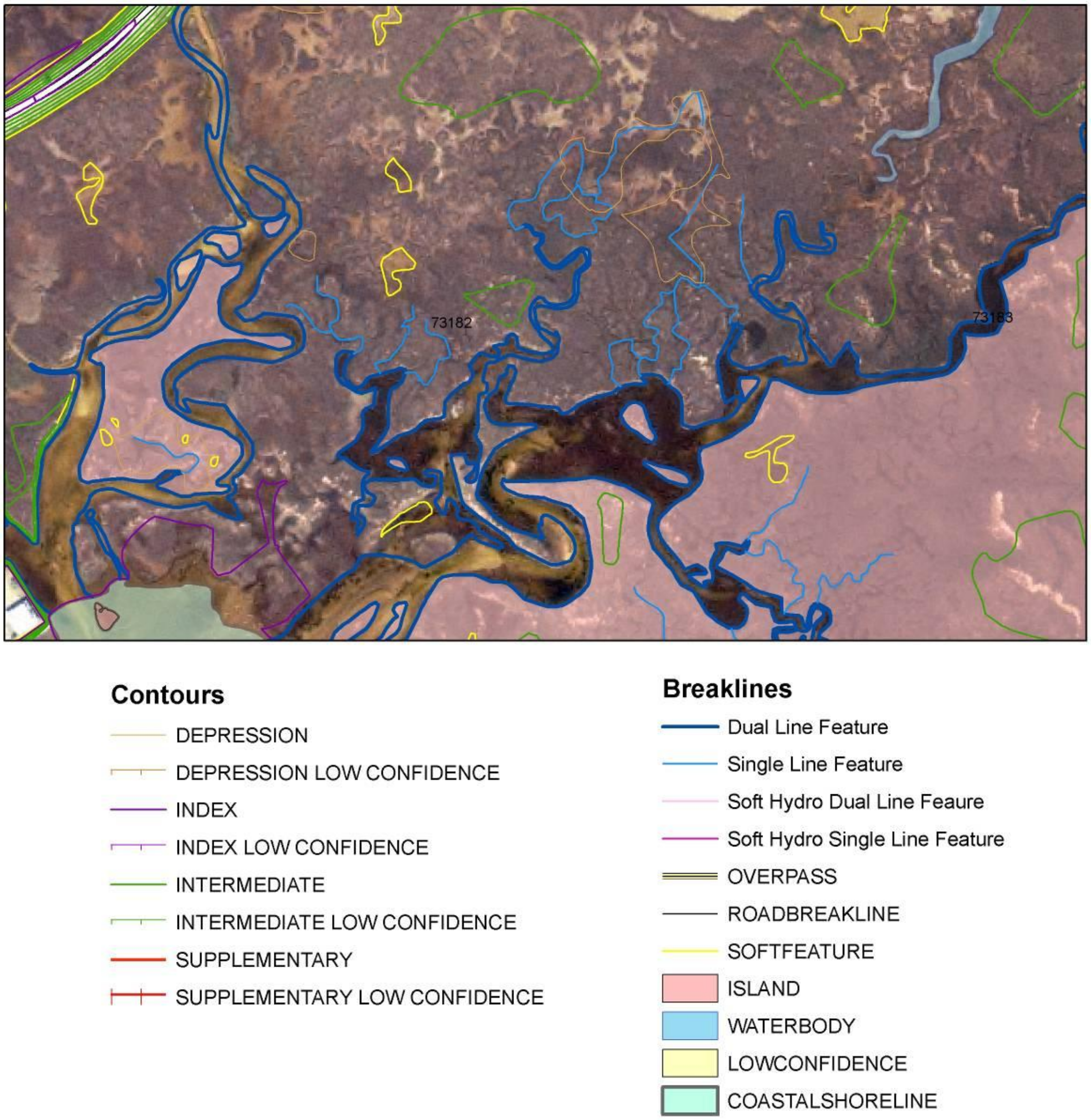

Figure 2. Example linear hydrographic feature breaklines and contours from tile # 73182

Closed Water Body Features

Closed water body features with an area of one-half acre or greater are correctly captured as two-dimensional closed polygons with a constant elevation that reflects the best estimate of the water elevation at the time of data capture. "Donuts" exist where there are islands within a closed water body feature. Figure 3 shows example breaklines and contours of closed water body features.

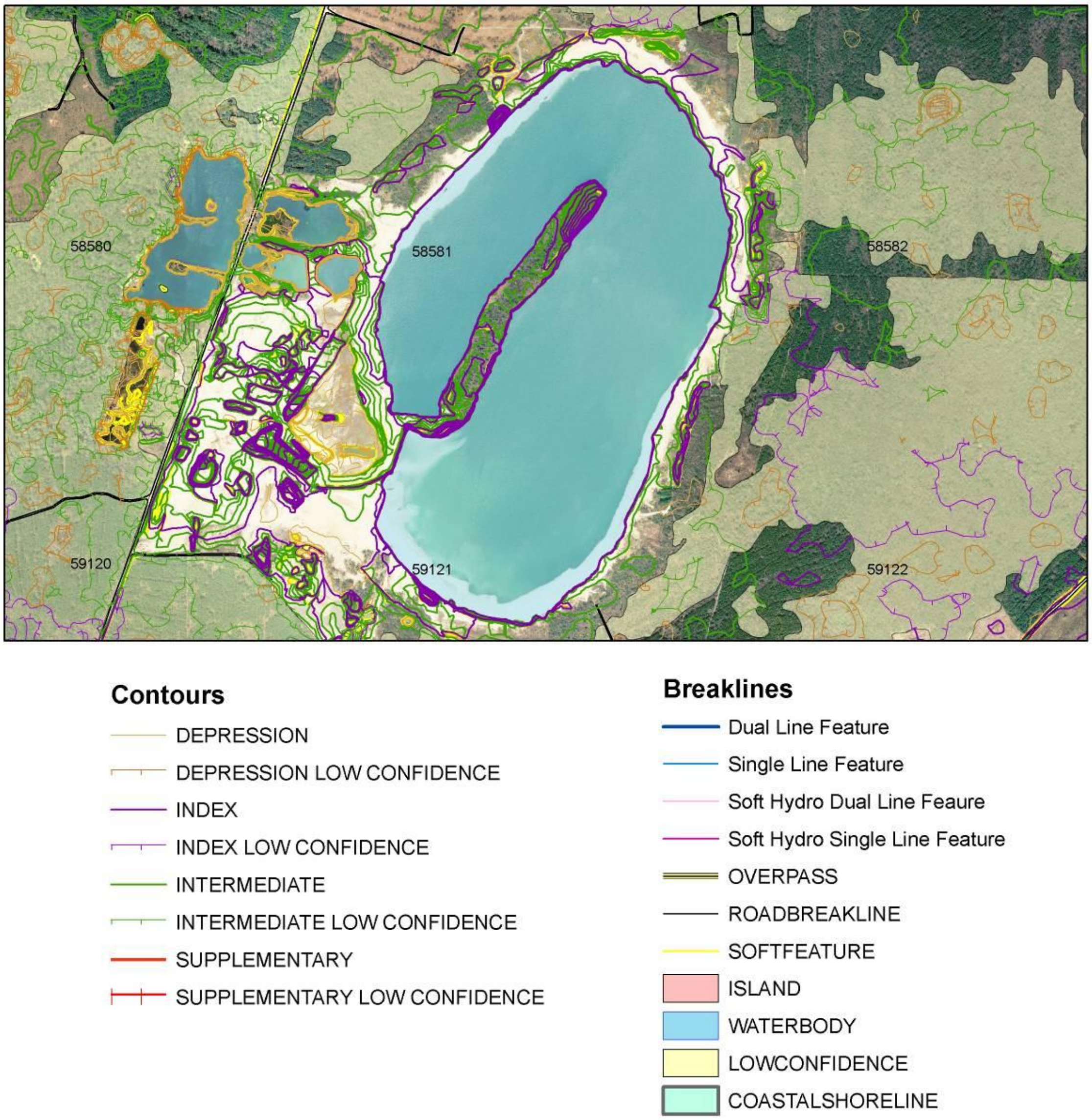

Figure 3. Example closed water body feature breaklines and contours from tile #58581

Road Features

Road edge of pavement features are correctly captured as three-dimensional breaklines on both sides of paved roads. Box culverts are continued as edge of pavement unless a clear guardrail system is in place; in that case, culverts are captured as a bridge or overpass feature. Each vertex maintains vertical integrity. Figure 4 shows example breaklines and contours of road features.

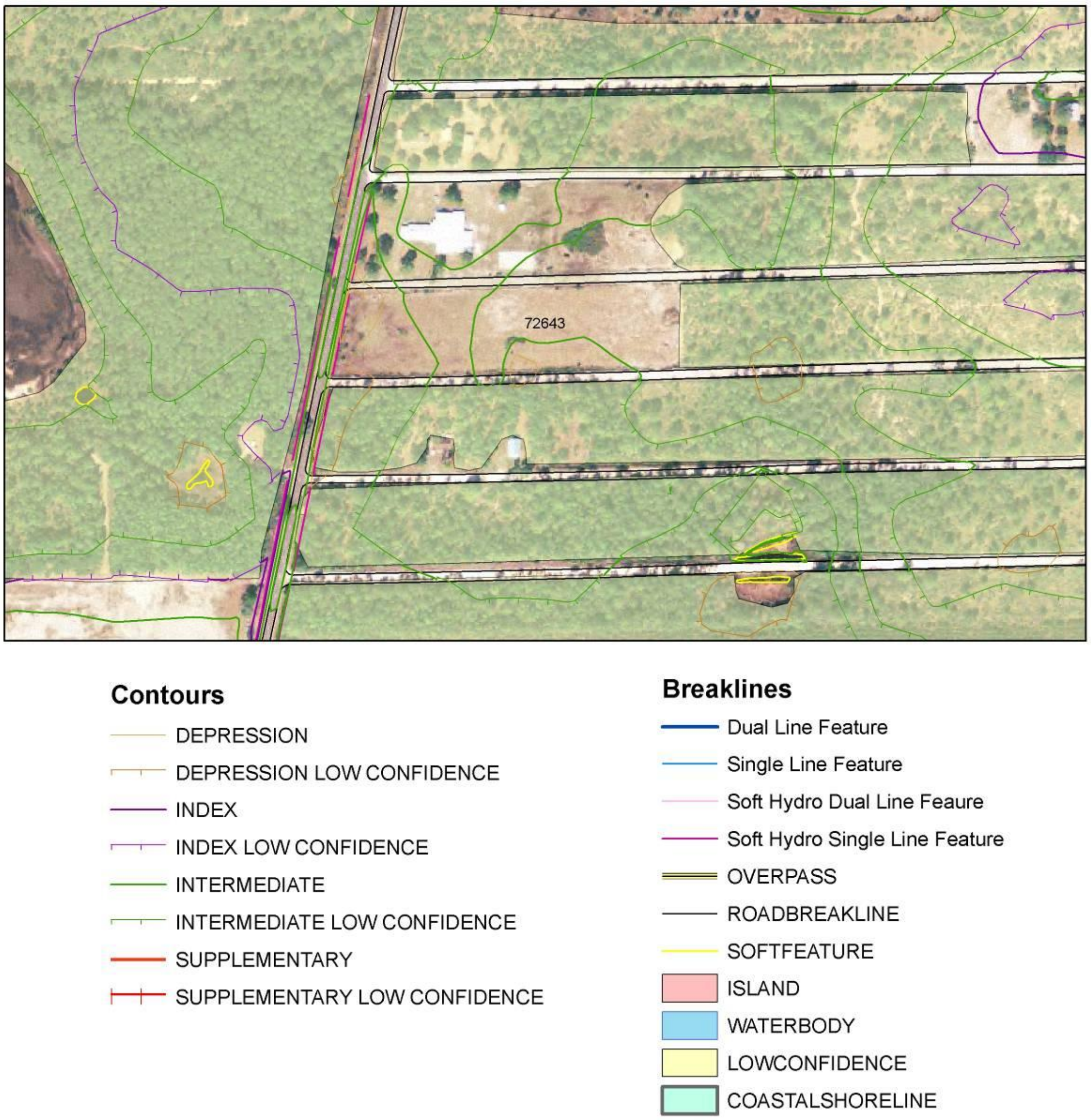

Figure 4. Example road feature breaklines and contours from tiles #72643

Bridge and Overpass Features

Bridges and overpasses are correctly captured as three-dimensional breaklines, capturing the edge of pavement on the bridge, rather than the elevation of guard rails or other bridge surfaces. Each vertex maintains vertical integrity. Figure 5 shows example breaklines and contours of bridge and overpass features.

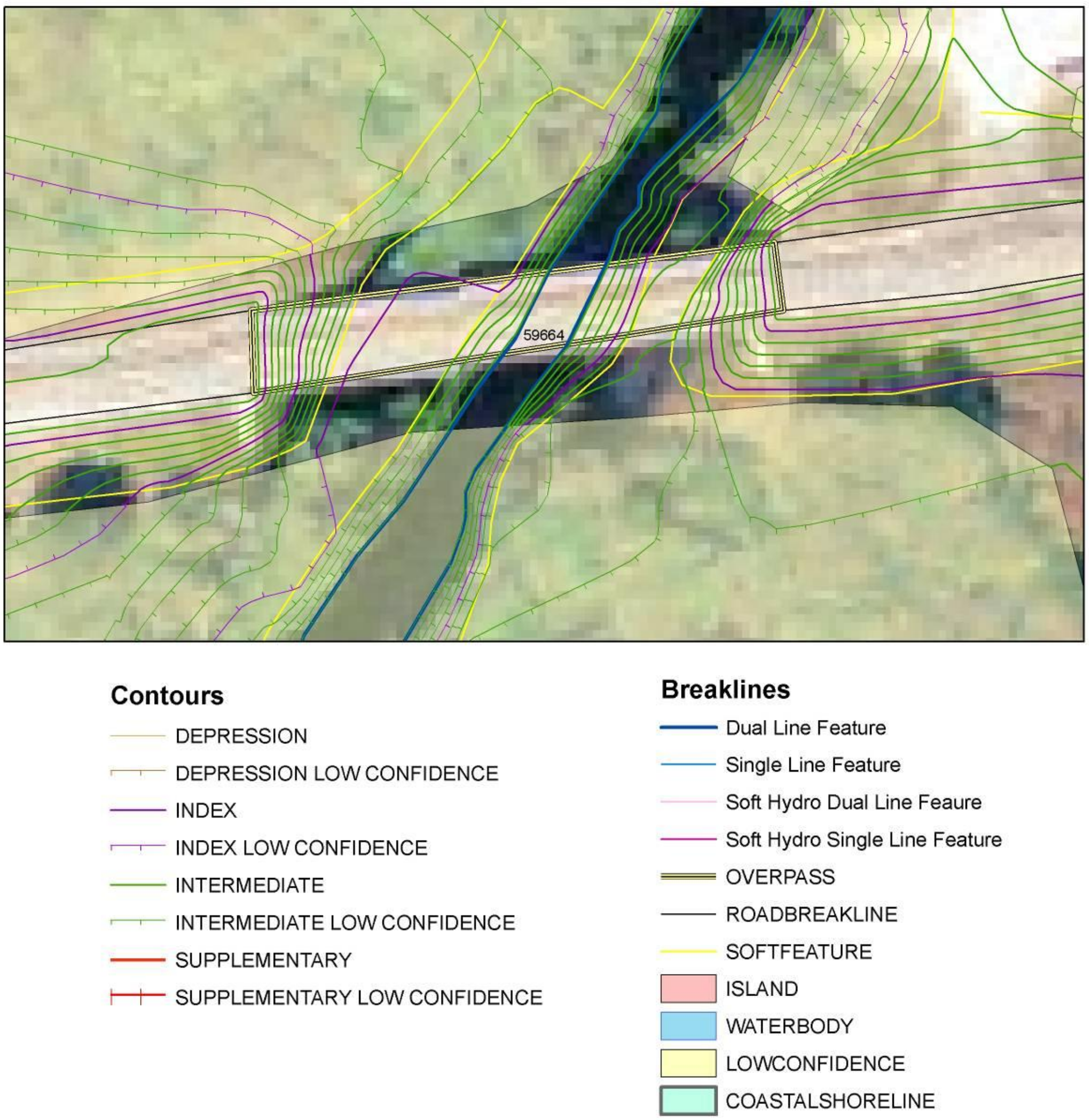

Figure 5. Example bridge and overpass feature breaklines and contours from tile # 59664

Soft Features

Soft features such as ridges, valleys, top of banks, etc. are correctly captured as three-dimensional breaklines so as to support better hydrological modeling of the LiDAR data and contours. Each vertex maintains vertical integrity. Figure 6 shows example breaklines and contours of soft features.

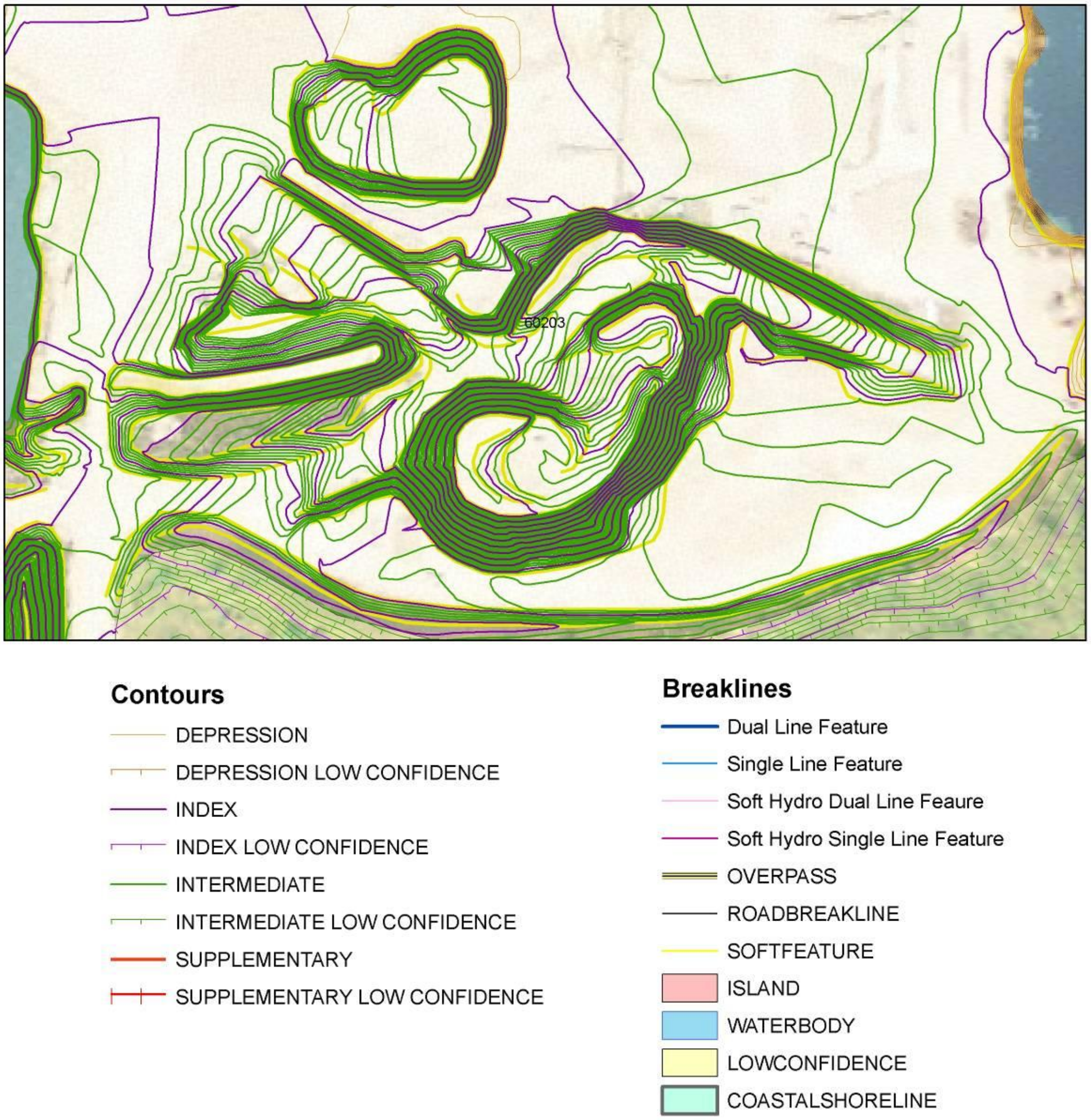

Figure 6. Example soft feature breaklines and contours from tile #60203

Island Features

The shoreline of islands within water bodies are correctly captured as two-dimensional breaklines in coastal and/or tidally influenced areas and as three-dimensional breaklines in non-tidally influenced areas for island features one-half acre in size or greater. All natural and man-made islands are depicted as closed polygons with constant elevation. Figure 7 shows example breaklines and contours for island features.

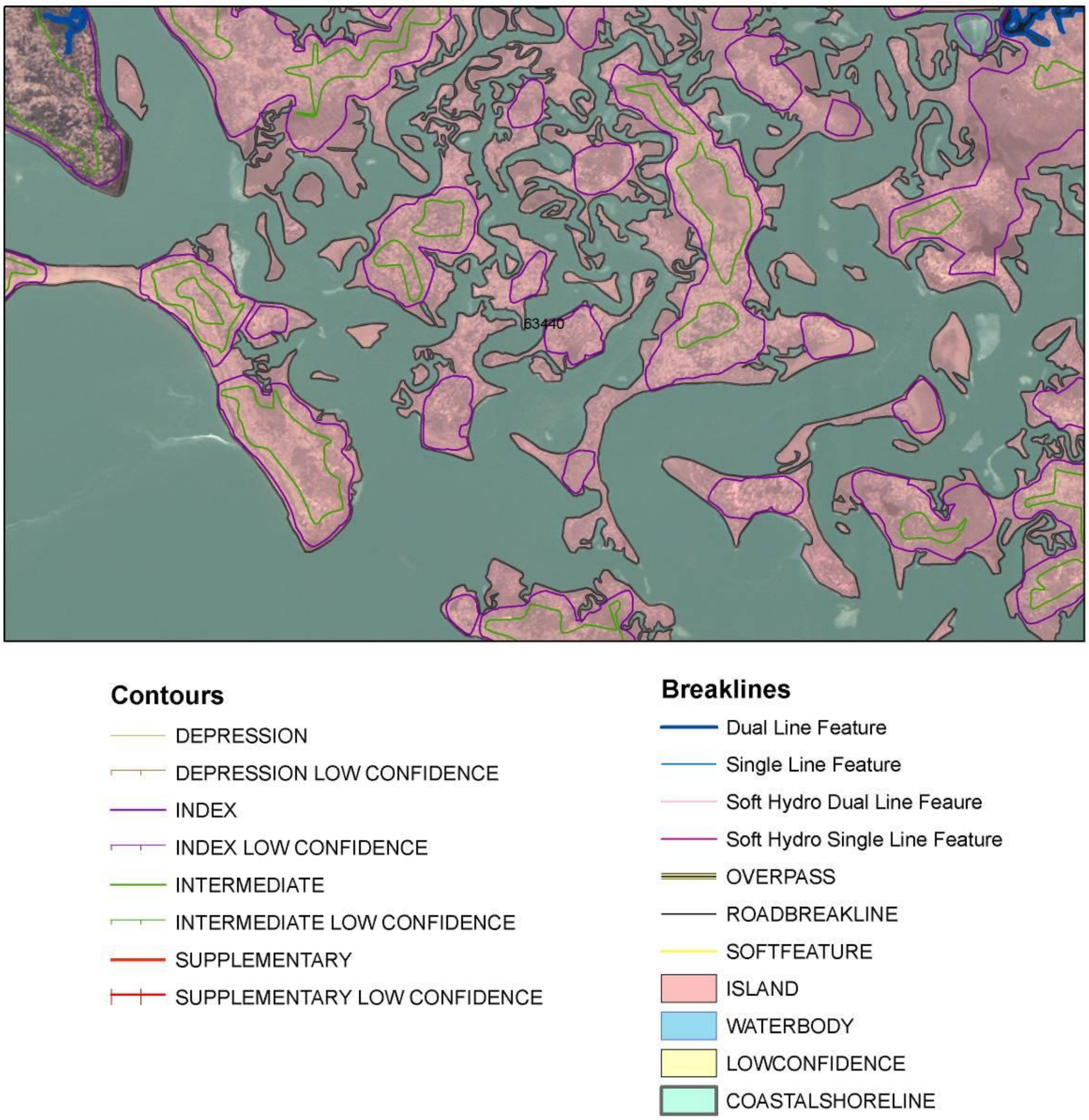

Figure 7. Example island feature breaklines and contours from tiles # 53440

Low Confidence Areas

The apparent boundary of vegetated areas (1/2 acre or larger) that are considered obscured to the extent that adequate vertical data cannot be clearly determined to accurately define the DTM are correctly captured as two-dimensional features with no z-values. Figure 8 shows example breaklines and contours for low confidence areas.

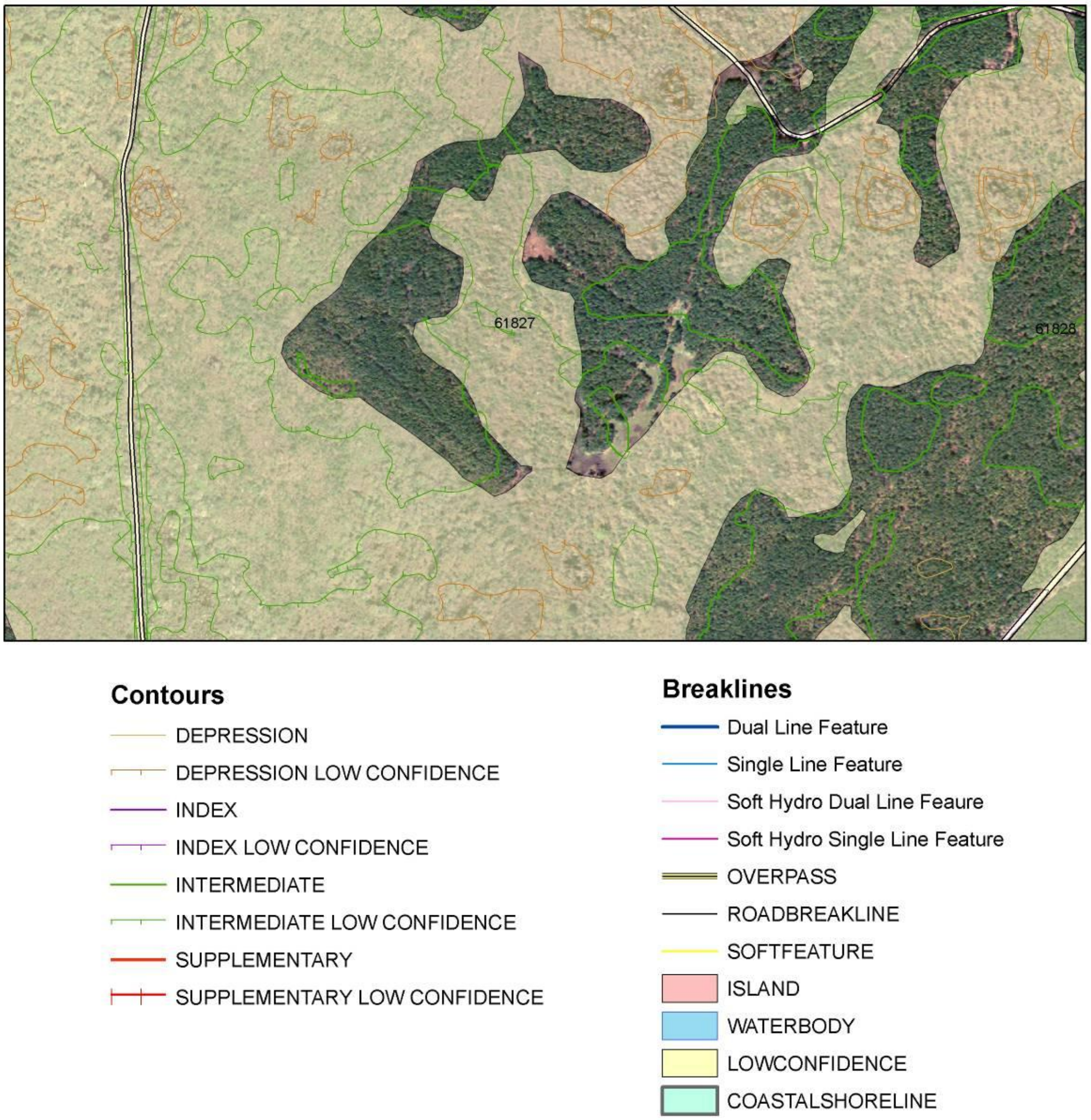

Figure 8. Example low confidence area feature breaklines and contours from tile #61827

Appendix I: Geodatabase Structure