



**S.C Department of Natural Resources**

# **LiDAR Campaign (Kershaw County, SC) Report of Survey**

2011

## EXECUTIVE SUMMARY

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S.C. Department of Natural Resources contracted with Sanborn to provide LiDAR mapping services for Kershaw County. Utilizing multi-return systems, Light Detection and Ranging (LiDAR) data in the form of 3-dimensional positions of a dense set of mass points was collected for approximately 740 square miles between February 21<sup>st</sup>, 2010 and March 24<sup>th</sup>, 2010. All systems consist of geodetic GPS positioning, orientation derived from high-end inertial sensors and high-accurate lasers. The sensor is attached to the aircraft's underside and emits rapid pulses of light that are used to determine distances between the plane and terrain below.

Specifically, the Leica ALS-50 LiDAR system was used to collect data for the survey campaign. The LiDAR system is calibrated by conducting flight passes over a known ground surface before and after each LiDAR mission. During final data processing, the calibration parameters are inserted into post-processing software.

A total of four airborne GPS (Global Positioning System) base stations were used in the Kershaw County project. The stations were set on NGS benchmarks AE3535, AJ7022, DE3192, and DF7761. These four base stations were tied to each other to create a GPS survey network. The coordinates of these stations were checked against each other with the three dimensional GPS baseline created at the airborne support set up and determined to be within project specifications.

The acquired LiDAR data was processed to obtain first and last return point data. The last return data was further filtered to yield a LiDAR surface representing the bare earth.

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## 1.0 INTRODUCTION

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This document contains the technical write-up of the LiDAR campaign, including standard specifications, system calibration techniques, field procedures, and the accuracy of the LiDAR data.

### 1.1 Contact Information

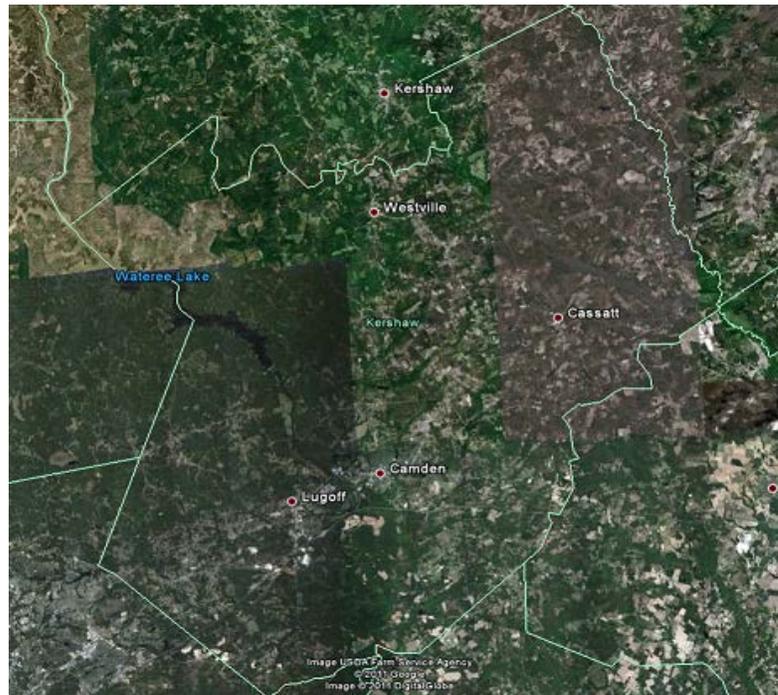
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### 1.2 Purpose of the LiDAR Acquisition

As stated in the Statement of Work for Acquisition and Production of High Resolution Elevation data for the SCDNR 2010 project, this LiDAR operation was designed to create high resolution data sets that will establish an authoritative source for elevation information for Kershaw County.

### 1.3 Project Location



**Figure 1: Area of Collection**

## 1.4 Standard Specifications for LiDAR

Table 1: LiDAR Specifications

| <b>Data Acquisition</b>                   |                                                                                                                                                                                                                                                                                                                                                                |          |
|-------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------|
| Requirement                               | Description                                                                                                                                                                                                                                                                                                                                                    |          |
| Returns per pulse                         | LiDAR sensor shall be capable of recording up to 3 (or more) returns per pulse, including 1st and last returns                                                                                                                                                                                                                                                 |          |
| Scan angle                                | $\leq \pm 24$ degrees                                                                                                                                                                                                                                                                                                                                          | <b>*</b> |
| Swath overlap                             | Nominal sidelap on adjoining swaths, i.e., survey shall be designed for 50% overlap coverage at planned aircraft height above ground                                                                                                                                                                                                                           | 50%      |
| Design pulse density (nominal)            | Pulses/m <sup>2</sup> (includes swath overlap; e.g., with 30% sidelap, $\geq 2$ pulse/m <sup>2</sup> in each swath)                                                                                                                                                                                                                                            | $\geq 1$ |
| GPS procedures                            | At least 2 GPS reference stations in operation during all missions, sampling positions at 1 Hz or higher frequently. Differential GPS baseline lengths shall not exceed 30 km. Differential GPS unit in aircraft shall sample position at 2 Hz or higher. LiDAR data shall only be acquired when GPS PDOP is $\leq 3.5$ and at least 6 satellites are in view. | <b>*</b> |
| Data Collection Season                    | Target window for collection of LiDAR data ends Spring of 2010. This may be extended with approval by State program managers                                                                                                                                                                                                                                   | <b>*</b> |
| Survey conditions                         | Leaf-off and no significant snow cover, as observed by state contract representatives.                                                                                                                                                                                                                                                                         | <b>*</b> |
| <b>Geographic Coverage and Continuity</b> |                                                                                                                                                                                                                                                                                                                                                                |          |
| Coverage                                  | No voids between swaths.<br>No voids because of cloud cover or instrument failure.                                                                                                                                                                                                                                                                             |          |
| Swath overlap                             | $\leq 50\%$ no-overlap area per project.                                                                                                                                                                                                                                                                                                                       |          |

## 2.0 LIDAR CALIBRATION

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### 2.1 Introduction

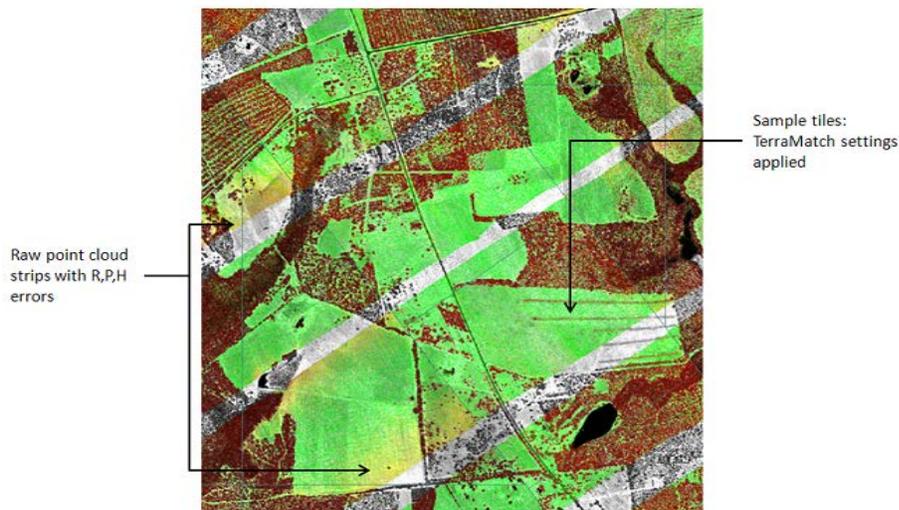
LiDAR calibrations are performed to determine and therefore eliminate systematic biases that occur within the hardware of the Leica ALS-50 system. Once the biases are determined they can be modeled out. The systematic biases are corrected for heading, scale, roll, and pitch errors.

The following procedures are intended to prevent operational errors in the field and office work, and are designed to detect inconsistencies. The emphasis is not only on the quality control (QC) aspects, but also on the documentation, i.e., on the quality assurance (QA).

### 2.2 Calibration Procedures

When Sanborn receives raw point cloud data from its field crew, calibration procedures using TerraSolid products are applied; including TerraScan and TerraMatch. Utilizing these two tools, Sanborn is able to correct each individual raw data strip to precisely match the two overlapping swaths. In return, the RMSE of the entire project is substantially lower, resulting in a more accurate dataset. TerraMatch samples the data perpendicular to the flight pattern to assess and correct for roll errors, pitch errors, and heading errors.

Throughout the Kershaw County project, flight direction consisted of a southwest to northeast flight pattern. Rows of small sample tiles were placed perpendicular to the raw strips, and populated with the raw point cloud data. Once the population of the data is complete, a filter is applied to each sample tile. The filter classifies bare earth and building rooftops per flight line in order for TerraMatch to recognize the individual strips and their features, allowing the software to find corrections for roll, pitch, and heading throughout the project. Once the adjustments are calculated, the settings are applied to the final delivery tiles.



**Figure 2: TerraMatch Tiling Sample**

## 3.0 LIDAR FLIGHT AND SYSTEM REPORT

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### 3.1 Introduction

This section addresses LiDAR system, flight reporting and data acquisition methodology used during the collection of the Kershaw county campaign. Although Sanborn conducts all LiDAR with the same rigorous and strict procedures and processes, all LiDAR collections are unique.

### 3.2 Field Work Procedures

A minimum of two GPS base stations were set for the Kershaw County project, which is within the project area or within the required baseline specifications of the project.

Pre-flight checks such as cleaning the sensor head glass are performed. A four minute INS initialization is conducted on the ground, with the engines running, prior to flight, to establish fine-alignment of the INS. GPS ambiguities are resolved by flying within ten kilometers of the base stations.

The flight missions were typically four or five hours in duration including runway calibration flights flown at the beginning and the end of each mission. During the data collection, the operator recorded information on log sheets which includes weather conditions, LiDAR operation parameters, and flight line statistics. Near the end of the mission GPS ambiguities are again resolved by flying within ten kilometers of the base stations, to aid in post-processing.

Table 2 shows the planned LiDAR acquisition parameters with a flying height of 1500 meters above ground level (AGL) for the Leica system on a mission to mission basis.

**Table 2: LiDAR Acquisition Parameters**

|                              |                 |
|------------------------------|-----------------|
| <b>Average Altitude</b>      | 1500 Meters AGL |
| <b>Airspeed</b>              | ~140 Knots      |
| <b>Scan Frequency</b>        | 36 Hertz        |
| <b>Scan Width Half Angle</b> | 20 Degrees      |
| <b>Pulse Rate</b>            | 71,800 Hertz    |

Preliminary data processing was performed in the field immediately following the missions for quality control of GPS data and to ensure sufficient overlap between flight lines. Any problematic data could then be re-flown immediately as required. Final data processing was completed in the Colorado Springs office.

**Table 3: Collection Dates, Times, Average Per Flight Collection Parameters and PDOP**

| <b>Mission</b> | <b>Date</b> | <b>Sensor</b> | <b>Start Time</b> | <b>End Time</b> | <b>Altitude (m)</b> | <b>Airspeed (Knots)</b> | <b>Scan Angle</b> | <b>Scan Rate</b> | <b>Pulse Rate</b> | <b>PDOP (Ave)</b> |
|----------------|-------------|---------------|-------------------|-----------------|---------------------|-------------------------|-------------------|------------------|-------------------|-------------------|
| 052b           | Feb 21      | Leica 40      | 20:07             | 00:03           | 1500                | 140                     | 40°               | 36               | 71,800            | 1.8               |
| 056a           | Feb 25      | Leica 40      | 15:44             | 20:26           | 1500                | 140                     | 40°               | 36               | 71,800            | 1.9               |
| 056b           | Feb 25      | Leica 40      | 21:33             | 23:00           | 1500                | 140                     | 40°               | 36               | 71,800            | 1.8               |
| 056c           | Feb 25      | Leica 40      | 23:55             | 02:25           | 1500                | 140                     | 40°               | 36               | 71,800            | 1.7               |
| 057a           | Feb 26      | Leica 40      | 12:28             | 14:44           | 1500                | 140                     | 40°               | 36               | 71,800            | 2.0               |
| 057b           | Feb 26      | Leica 40      | 18:31             | 22:34           | 1500                | 140                     | 40°               | 36               | 71,800            | 2.0               |
| 078a           | Mar 19      | Leica 40      | 12:51             | 18:28           | 1500                | 140                     | 40°               | 36               | 71,800            | 1.6               |
| 078b           | Mar 19      | Leica 40      | 20:25             | 22:32           | 1500                | 140                     | 40°               | 36               | 71,800            | 1.6               |
| 082a           | Mar 23      | Leica 40      | 16:09             | 20:57           | 1500                | 140                     | 40°               | 36               | 71,800            | 1.9               |
| 082b           | Mar 23      | Leica 40      | 21:48             | 00:30           | 1500                | 140                     | 40°               | 36               | 71,800            | 2.0               |
| 082a           | Mar 23      | Leica 49      | 14:14             | 19:12           | 1500                | 140                     | 40°               | 36               | 71,800            | 2.0               |
| 082b           | Mar 23      | Leica 49      | 20:47             | 00:55           | 1500                | 140                     | 40°               | 36               | 71,800            | 2.0               |
| 083a           | Mar 24      | Leica 49      | 14:32             | 19:38           | 1500                | 140                     | 40°               | 36               | 71,800            | 1.7               |

### 3.3 Final LiDAR Processing

LiDAR filtering was accomplished using TerraSolid LiDAR processing and modeling software. The filtering process reclassifies all the data into classes with in the LAS formatted file based scheme set using the LAS format 1.2 specifications or by the client. Once the data is classified, the entire data set is reviewed and manually edited for anomalies that are outside the required guidelines of the product specification or contract guidelines, whichever apply. Table 4 indicates the required product specifications.

The coordinate and datum transformations are then applied to the data set to reflect the required deliverable projection, coordinate and datum systems as provided in the contract.

The client required deliverables are then generated. At this time, a final QC process is undertaken to validate all deliverables for the project. Prior to release of data for delivery, Sanborn’s quality control/quality assurance department reviews the data and then releases it for delivery.

**Table 4: Processing Accuracies and Requirements**

|                                             |            |
|---------------------------------------------|------------|
| <b>Accuracy of LiDAR Data (H)</b>           | 1m RMSE    |
| <b>Accuracy of LiDAR data in bare areas</b> | 15 cm RMSE |

## 4.0 GEODETIC AUTHENTICATION

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### 4.1 Final LiDAR Verification

The LiDAR data was evaluated using a collection of 21 NGS benchmarks; see figure 3 for diagram. For Kershaw County, the standard deviation is 0.399 feet and the root mean squared is 0.391 feet. The LiDAR data was compared to each of these benchmarks yielding much better result than was required for the project. Table 5 indicates the results for Kershaw County and each point including the overall results as it compares to the LiDAR data set.

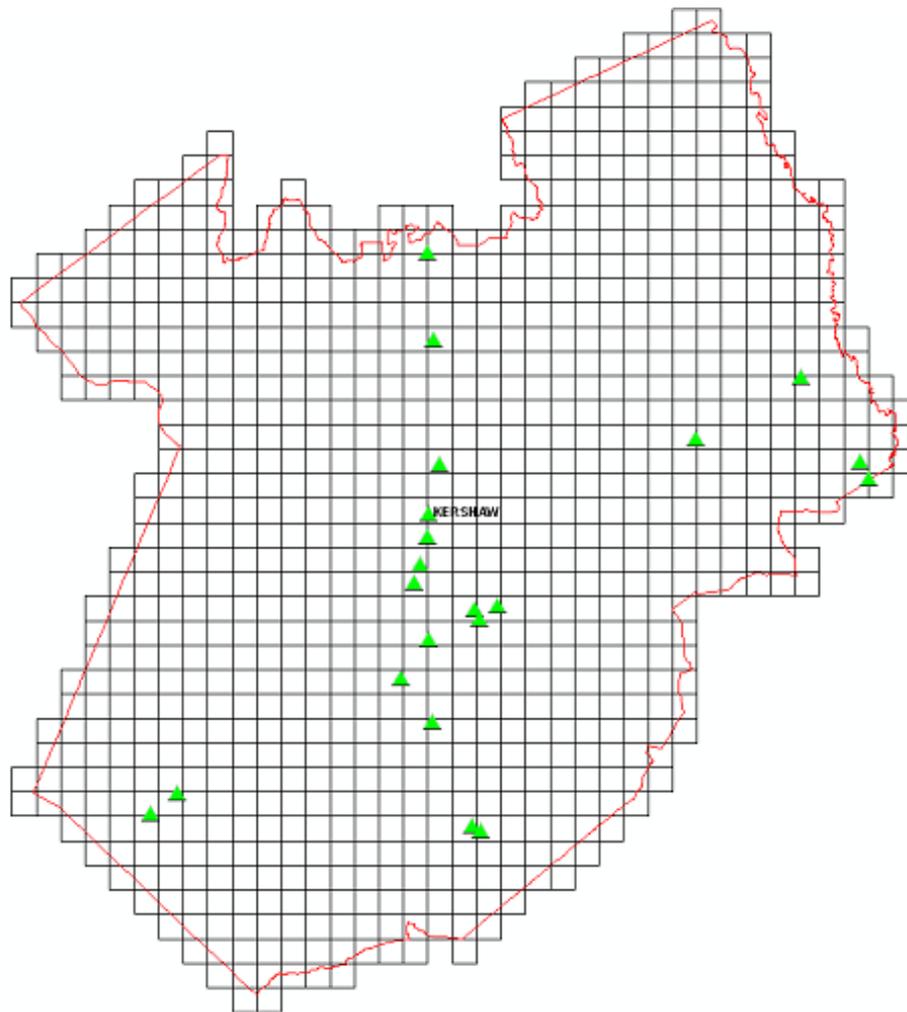


Figure 3: Kershaw Survey Checkpoint Diagram

**Table 5: LiDAR Accuracy Assessment based on the Checkpoint Survey (Feet)**

| <b>Name</b>             | <b>Vegetation Class</b> | <b>Easting</b> | <b>Northing</b> | <b>Known Z</b> | <b>Laser Z</b> | <b>Dz</b> |
|-------------------------|-------------------------|----------------|-----------------|----------------|----------------|-----------|
| AA4021                  | Bare Earth              | 2120294.190    | 886152.110      | 280.520        | 281.310        | +0.790    |
| EC0829                  | Bare Earth              | 2114633.750    | 878310.850      | 170.720        | 171.500        | +0.780    |
| EC3115                  | Bare Earth              | 2196550.580    | 939911.950      | 277.780        | 278.210        | +0.430    |
| EC0849                  | Bare Earth              | 2175083.830    | 927214.430      | 331.780        | 332.190        | +0.410    |
| EC3149                  | Bare Earth              | 2130703.230    | 890493.110      | 297.690        | 298.100        | +0.410    |
| EC3150                  | Bare Earth              | 2129775.700    | 892427.440      | 296.130        | 296.470        | +0.340    |
| EC3129                  | Bare Earth              | 2121219.710    | 869377.860      | 149.290        | 149.480        | +0.190    |
| AA4018                  | Bare Earth              | 2117358.930    | 897770.570      | 303.850        | 304.000        | +0.150    |
| EC3110                  | Bare Earth              | 2210329.540    | 919026.740      | 260.110        | 260.240        | +0.130    |
| AA4003                  | Bare Earth              | 2120079.590    | 965270.100      | 482.980        | 483.030        | +0.050    |
| EC3111                  | Bare Earth              | 2208484.420    | 922542.550      | 249.780        | 249.790        | +0.010    |
| EC0818                  | Bare Earth              | 2069019.360    | 854791.790      | 296.030        | 296.020        | -0.010    |
| AA4017                  | Bare Earth              | 2118533.010    | 901465.190      | 273.680        | 273.580        | -0.100    |
| EC0835                  | Bare Earth              | 2134364.720    | 893012.550      | 287.220        | 287.050        | -0.170    |
| AA4007                  | Bare Earth              | 2121277.680    | 947417.350      | 423.110        | 422.920        | -0.190    |
| EC3135                  | Bare Earth              | 2131005.620    | 847073.570      | 177.090        | 176.820        | -0.270    |
| EC0815                  | Bare Earth              | 2063459.000    | 850649.700      | 418.600        | 418.300        | -0.300    |
| AA4016                  | Bare Earth              | 2120099.390    | 907200.390      | 304.130        | 303.790        | -0.340    |
| EC3134                  | Bare Earth              | 2129336.920    | 848108.760      | 162.910        | 162.540        | -0.370    |
| AA4015                  | Bare Earth              | 2120337.460    | 911801.830      | 267.620        | 267.030        | -0.590    |
| AA4012                  | Bare Earth              | 2122661.920    | 922090.130      | 378.270        | 377.620        | -0.650    |
| Average dz              |                         | +0.033         |                 |                |                |           |
| Minimum dz              |                         | -0.650         |                 |                |                |           |
| Maximum dz              |                         | +0.790         |                 |                |                |           |
| Average Magnitude       |                         | 0.318          |                 |                |                |           |
| <b>Root Mean Square</b> |                         | <b>0.391</b>   |                 |                |                |           |
| Std deviation           |                         | 0.399          |                 |                |                |           |

## 5.0 COORDINATES AND DATUM

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### 5.1 Introduction

The final adjustment was constrained to the published NAD83 geodetic coordinates ( $\phi$ ,  $\lambda$ ) and NAVD88 elevations. The adjustment was cross-referenced to the GEOID03 model to enable the estimation of orthometric heights.

### 5.2 Horizontal Datum

The final horizontal coordinates are provided in State Plane HARN South Carolina FIPS 3900 on the North American Datum of 1983 (NAD83 adjustment of 1992) units of intl feet.

### 5.3 Vertical Datum

The final orthometric elevations were determined for all points in the network using Geoid03 model and are provided on the North American Vertical Datum of 1988 in units of US survey feet.